

Degeneration of Abelian Differentials and Period Matrices

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Motivations

- The Hodge bundle $\Omega\mathcal{M}_g$ over the moduli of curves \mathcal{M}_g extends to $\overline{\mathcal{M}}_g^{DM}$.
- Goal: 1)** Study this extension by giving the expansion of an abelian differential in local coordinates near the boundary of $\overline{\mathcal{M}}_g$.
- 2)** To study the degeneration of the period matrices, i.e. gives a description of the boundary of the Torelli image of $\overline{\mathcal{M}}_g$ in $\overline{\mathcal{A}}_g$, the moduli of pvav.

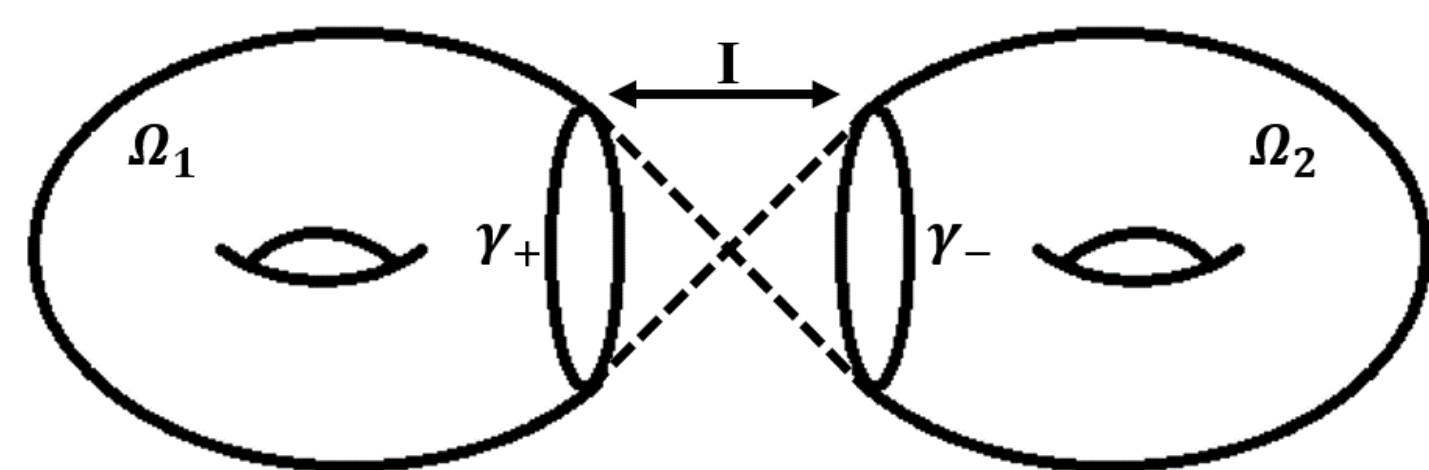
Outline

- We give an explicit expansion in plumbing coordinates for an **arbitrary degenerate** abelian differential.
- We compute the ¹variational formula for the period over **any** given cycle of the abelian differential.
- As a corollary, we give the variational formula for the **period matrices** near an arbitrary boundary stratum of $\overline{\mathcal{M}}_g$.

Plumbing Coordinates

Want: Construct a smooth curve $X_{\underline{s}}$ from a nodal curve X .

- We cut out neighborhoods at the two pre-images q_e and q_{-e} of each node $q_{|e|}$ of X , and identify their boundaries via a gluing map $I_e : z_e \mapsto s_e/z_e$.



- Before:** Local equation near a node $q_{|e|}$: $z_e \cdot z_{-e} = 0$.
- After:** Local equation near the *seams* $\gamma_{\pm e}$: $z_e \cdot z_{-e} = s_e$.
- $|s_e|$ is called the **plumbing parameter** at the node $q_{|e|}$.
- The plumbing parameters $\underline{s} := (s_1, \dots, s_n)$ give **versal deformation coordinates** on $\overline{\mathcal{M}}_g$ to the boundary stratum containing the point X .

Jump Problem

- Given a stable differential Ω on X , denote Ω_v the restriction of a stable differential Ω on the connected component X_v .
- We have the mis-matches $\{\Omega_v(e)|_{\gamma_e} - I_e^*(\Omega_v(-e)|_{\gamma_{-e}})\}$ (which we call the **jumps** of Ω) on the seams.
- Want: Correction differentials $\{\eta_{v,\underline{s}}\}$ that matches the jumps of Ω_v .**
- Then $\Omega_{v,\underline{s}} := \Omega_v - \eta_{v,\underline{s}}$ glue correctly to be a global meromorphic differential $\Omega_{\underline{s}}$ on $X_{\underline{s}}$.
- This construction is called **(solving) the jump problem**. It is first developed and used in a real-analytic setting in [GKN17].

Main Result: Degeneration of Abelian Differentials

- The solution to the jump problem $\eta_{v,\underline{s}}$** can be constructed explicitly as $\eta_{v,\underline{s}} = \sum_{k=1}^{\infty} \eta_{v,\underline{s}}^{(k)}$.
- The \underline{s} -expansion of $\eta_v^{(k)}$ is given as follows:

$$\eta_v^{(k)}(z) = (-1)^k \sum_{l_v^k} \prod_{i=1}^k s_{e_i} \cdot \omega_v(z, q_{e_i}) \beta(l_v^k) \text{hol}(\Omega)(q_{-e_k}) + O(|\underline{s}|^{k+1}). \quad (1)$$
- For each k , $\|\eta_v^{(k)}\|_{L^2}$ is controlled by $\sqrt{|\underline{s}|^k}$. Therefore $\|\eta_{v,\underline{s}}\|_{L^2}$ is controlled by $\sqrt{|\underline{s}|}$.

Degeneration of general periods

- Let α be any oriented loop on X .
- Let $\{q_1, \dots, q_N\}$ be the collection of nodes that α passes through (with possible repetition).

Corollary 1 (General Periods)

The variational formula for a general period of $\Omega_{\underline{s}}$ is given by:

$$\int_{\alpha_{\underline{s}}} \Omega_{\underline{s}} = \sum_{i=1}^N (r_{e_i} \ln |s_{e_i}| + c_i + l_i) + O(|\underline{s}|^2),$$

here c_i and l_i are the constant and linear terms in \underline{s} respectively, which are explicitly given.

Degeneration of period matrices

- Choose a suitable symplectic basis $\{A_{i,\underline{s}}, B_{i,\underline{s}}\}_{i=1}^g$ of $H_1(X_{\underline{s}}, \mathbb{Z})$.
- Choose a normalized basis of 1-forms $\{v_i\}_{i=1}^g$ w.r.t $\{A_{i,0}, B_{i,0}\}$ on X .
- Apply the jump problem and get $\{v_{i,\underline{s}}\}$ on $X_{\underline{s}}$. We claim that $\{v_{i,\underline{s}}\}$ is a normalized basis of $H^{1,0}(X_{\underline{s}}, \mathbb{C})$ with respect to $\{A_{i,\underline{s}}, B_{i,\underline{s}}\}$.

Corollary 2 (Period Matrices)

For any fixed h, k , the variational formula for the period matrix $\tau_{h,k}(\underline{s})$ is given by

$$\tau_{h,k}(\underline{s}) = \sum_{e \in E_X} N_{|e|,h} \cdot N_{|e|,k} \cdot \ln |s_e| + c_{h,k} + l_{h,k} + O(|\underline{s}|^2) \quad (2)$$

where $N_{|e|,k} := \gamma_{|e|} \times B_{k,\underline{s}}$, E_X is the set of nodes of X , $\{q_{|e_i|}\}_{i=0}^{N-1}$ is the set of nodes B_h passes through. Explicitly,

$$c_{h,k} = \lim_{\underline{s} \rightarrow 0} \sum_{i=1}^N \left(\int_{p_i}^{p_{i+1}} v_k - N_{|e_i|,h} N_{|e_i|,k} \ln |s_{e_i}| \right)$$

$$l_{h,k} = - \sum_{e \in E_X} s_e (\text{hol}(v_k)(q_e) \text{hol}(v_h)(q_{-e})).$$

Prior Works

- Yamada [Yam80] and Fay [Fay73] computed the variational formula of the period matrices on stable curves with one node. We reprove their results by restricting formula (1) to the case $n = 1$.
- For general n , the logarithmic term in formula (2) gives the main result of [Tan91].
- Our result is a total generalization of these works.**

Compactification of Strata

- Using our method we also give an **alternative proof** for the main result in [BCGGM16], which gives the necessary and sufficient conditions for an abelian differential to lie in the boundary of the *incidence variety compactification* of strata.

Future Works

- Compute the variational formula for the **period coordinates** on the strata of abelian differentials $\Omega\mathcal{M}_g(\mu)$.
- Apply the jump problem to a **more general setting**: compute the expansion of a section of any vector bundle as the curve degenerates. For instance, the Higgs bundle.
- Use the variational formulas of the period matrices of the totally degenerate curve to obtain information about **Teichmüller curves**.

References

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Variational formula = Expansion in terms of s_e and $\ln s_e$.