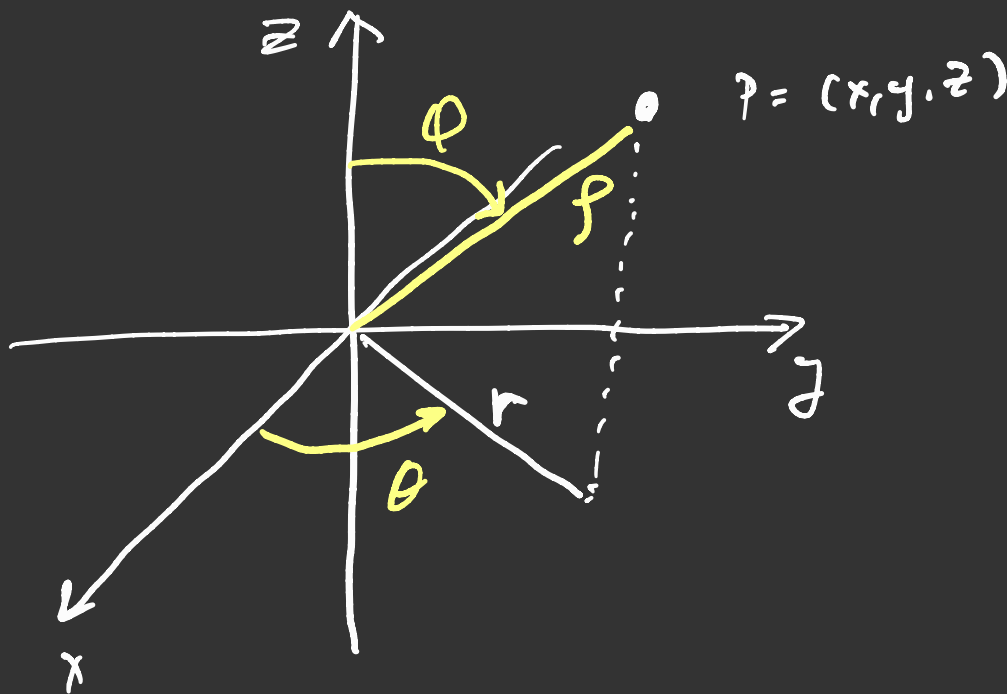


# Spherical Coordinates



$\rho$  = distance to the origin

$\phi$  = angle to the  $z$ -axis  $\phi \in [0, \pi]$

$\theta$  = angle to  $x$ -axis

$\rho=0$  is north pole, equator is  $90^\circ$ , south pole is  $180^\circ$

$r$  = distance to  $z$  axis  $\theta \in [0, \pi]$

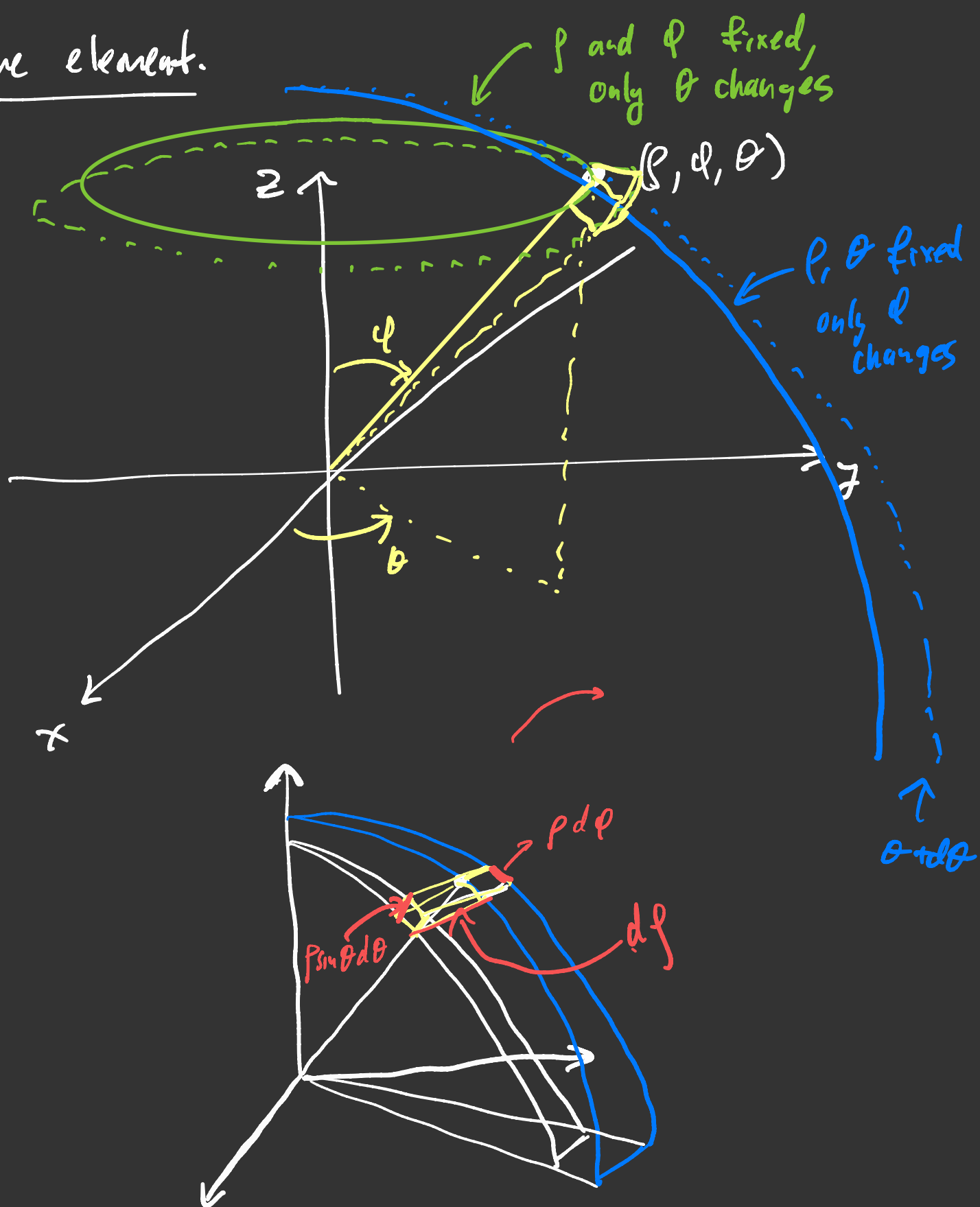
$$r = \rho \sin \phi$$

$$x = r \cos \theta = \rho \sin \phi \cos \theta$$

$$y = r \sin \theta = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

Volume element.



$$dV = \rho^2 \sin \phi d\phi d\theta d\phi$$

## Volume of a Ball

$$B: 0 \leq \theta \leq 2\pi, \quad 0 \leq \varphi \leq \pi, \quad 0 \leq \rho \leq R$$

$$V(B) = \int_0^{2\pi} \int_0^{\pi} \int_0^R \rho^2 \sin \varphi \, d\rho \, d\varphi \, d\theta$$

$$= 2\pi \int_0^R \rho^2 \, d\rho \int_0^{\pi} \sin \varphi \, d\varphi$$

$$= \frac{2\pi}{3} R^3 \cdot (-\cos \varphi) \Big|_0^{\pi}$$

$$= \frac{4\pi}{3} R^3$$



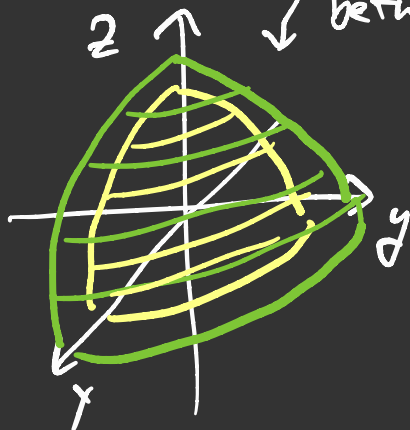
Ex:

$$B: 0 \leq \varphi \leq \pi/2$$

$$0 \leq \theta \leq \pi/2$$

$$R_1 \leq \rho \leq R_2$$

between two spheres:  $\frac{1}{8}$  of spherical shell.



density  $\delta = \text{const}$

$$\text{Mass} = \iiint_B \delta \, dV = \delta \int_0^{\pi/2} \int_0^{\pi/2} \int_{R_1}^{R_2} \rho^2 \sin \varphi \, d\rho \, d\theta \, d\varphi$$

$$= \delta \frac{\pi}{2} \int_0^{\pi/2} \sin \varphi \, d\varphi \int_{R_1}^{R_2} \rho \, d\rho$$

$$= \delta \frac{\pi}{2} \cdot \frac{1}{3} (R_2^3 - R_1^3) \int_0^{\pi/2} \sin \varphi \, d\varphi$$

$$= \delta \frac{\pi}{6} (R_2^3 - R_1^3)$$



moment:

$$z = \rho \cos \phi$$

$$M_{xy} = \iiint_B z \delta \, dV$$

$$= \delta \int_0^{\pi/2} \int_0^{\pi/2} \int_{R_1}^{R_2} \rho^3 \sin \phi \cos \phi \, d\rho \, d\phi \, d\theta$$

$$= \frac{\delta \pi}{2} \int_0^{\pi/2} \sin \phi \cos \phi \, d\phi \int_{R_1}^{R_2} \rho^3 \, d\rho$$

$$= \frac{\delta \pi}{8} (R_2^4 - R_1^4) \int_0^{\pi/2} \sin \phi \cos \phi \, d\phi$$

$$= \frac{\delta \pi}{8} (R_2^4 - R_1^4) \int_0^1 u \, du \quad \begin{array}{l} u = \cos \phi \\ du = -\sin \phi \, d\phi \end{array}$$

$$= \frac{\delta \pi}{16} (R_2^4 - R_1^4)$$

Since domain is symmetric,

$$M_{xy} = M_{yz} = M_{zx}$$

$$\text{Center of mass: } \bar{z} = \frac{M_{xy}}{M} = \frac{3}{8} \frac{R_2^4 - R_1^4}{R_2^3 - R_1^3}$$

Extremes: first shell is the ball:

If  $R_1 = 0$ , then

$$\boxed{\bar{z} = \frac{3}{8} R_2} = \bar{x} = \bar{y}$$

other extreme:  $R_1 = R_2 - \varepsilon$ ,  $\varepsilon \ll R_2$

$$\bar{z} = \frac{3}{8} \frac{R_2^4 - (R_2 - \varepsilon)^4}{R_2^4 - (R_2 - \varepsilon)^3}$$

But,  $f(x - \varepsilon) \approx f(x) + f'(x)(-\varepsilon)$

Thus

$$\bar{z} \approx \frac{3}{8} \frac{R_2^4 - R_2^4 - 4 R_2^3 (-\varepsilon)}{R_2^3 - R_2^3 - 3 R_2^2 (-\varepsilon)}$$

$$= \frac{3}{8} \cdot \frac{4 R_2^3 (-\varepsilon)}{3 R_2^2 (-\varepsilon)} = \boxed{\frac{1}{2} R_2}$$

For the thin shell, center of mass moves up.  
relative to solid  $\frac{1}{8}$  of ball.

Ex: (with important mechanical implications)

$$B: 0 \leq \varphi \leq \varphi_0, \quad 0 \leq \theta \leq 2\pi, \quad 0 \leq \rho \leq R$$



drumstick domain

Let  $\delta$  be density

$$M = \iiint_B \delta \, dV = \delta \int_0^{2\pi} \int_0^{\varphi_0} \int_0^R \rho^2 \sin \varphi \, d\rho \, d\varphi \, d\theta$$

$$= 2\pi\delta \int_0^{\varphi_0} \int_0^R \rho^2 \sin \varphi \, d\rho \, d\varphi$$

$$= \frac{2}{3}\pi\delta R^3 \cdot (-\cos) \Big|_0^{\varphi_0}$$

$$= \frac{2\pi}{3}\delta R^3 (1 - \cos \varphi_0).$$

Now we want to find center of mass.

Since it is a body of revolution,  
center of mass must be on  $z$  axis, so

$$\bar{x} = \bar{y} = 0.$$

$$\bar{z} = \frac{M_{xy}}{M}$$

$$z = \rho \cos \varphi$$

$$M_{xy} = \iiint_B \delta z \, dV$$

$$= \delta \int_0^{2\pi} \int_0^{\varphi_0} \int_0^R \rho^3 \cos \varphi \sin \varphi \, d\rho \, d\varphi \, d\theta$$

$$= \frac{2\pi\delta}{4} R^4 \int_0^{\varphi_0} \cos \varphi \sin \varphi \, d\varphi$$

$$= \frac{\pi\delta}{2} R^4 \int_0^{\sin \varphi_0} u \, du$$

$$= \frac{\pi\delta}{4} R^4 \sin^2 \varphi_0$$

$$\text{Thus } \bar{z} = \frac{\pi\delta R^3 \sin^2 \varphi_0 / 4}{\frac{2}{3}\pi\delta R^3 (1 - \cos \varphi_0)} = \frac{3}{8} \frac{R \sin^2 \varphi_0}{1 - \cos \varphi_0}$$

$$\bar{x} = \bar{y} = 0$$

If  $\varphi_0 = \pi$  (whole ball) then  $\bar{z} = 0$  (center of mass is center of ball)

# Moment of Inertia

$$I_z = \iiint_B \delta (x^2 + y^2) dV$$

$$E = \frac{1}{2} I_z \omega^2 \quad \text{where } \omega = \text{angular velocity in rad/sec.}$$

↑ plays role of mass if you consider rotation instead of linear motion.

$$I_z = \int_0^{2\pi} \int_0^{\phi_0} \int_0^R \delta \rho^2 \sin^2 \phi \cdot \rho^2 \sin \phi \, d\rho \, d\phi \, d\theta$$

$$= 2\pi\delta \int_0^{\phi_0} \int_0^R \rho^4 \sin^3 \phi \, d\rho \, d\phi$$

$$= \frac{2\pi\delta}{5} R^5 \int_0^{\phi_0} \sin^3 \phi \, d\phi$$

$$= \int_0^{\phi_0} (1 - \cos^2 \phi) \sin \phi \, d\phi$$
$$c = \cos \phi \quad dc = -\sin \phi \, d\phi$$

$$= -\int_{\cos \phi_0}^{\cos 0} (1 - c^2) \, dc$$

$$= \frac{2\pi\delta}{15} R^5 (2 - 3 \cos \phi_0 + \cos^3 \phi_0)$$

$$= \int_{\cos \phi_0}^1 (1 - c^2) \, dc$$

$$= 1 - \cos \phi_0 - \frac{1}{3} + \frac{1}{3} \cos^3 \phi_0$$

$$= \frac{2}{3} - \cos \phi_0 + \frac{1}{3} \cos^3 \phi_0$$

What is interesting here?

If  $\phi_0 = \pi$  (all the ball), then

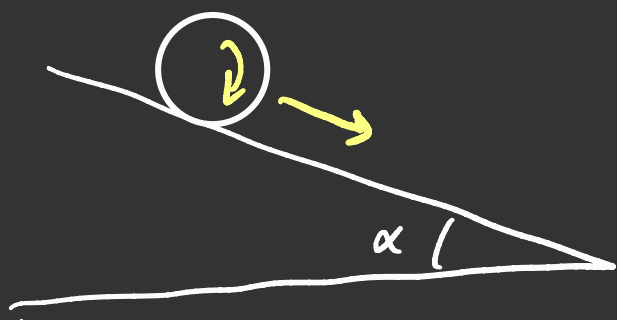
$$\begin{aligned} I_z &= \frac{2}{15} \pi \delta R^5 (2 + 3 - 1) \\ &= \frac{8}{15} \pi \delta R^5 \end{aligned}$$

With this result, we can correct a mistake in the textbooks of Mechanics.

Some such texts make the following claim:

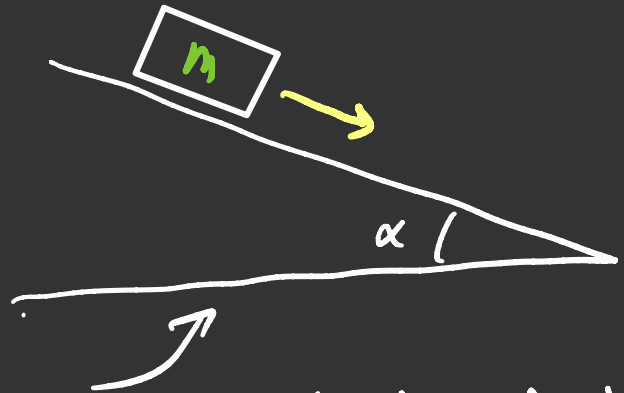
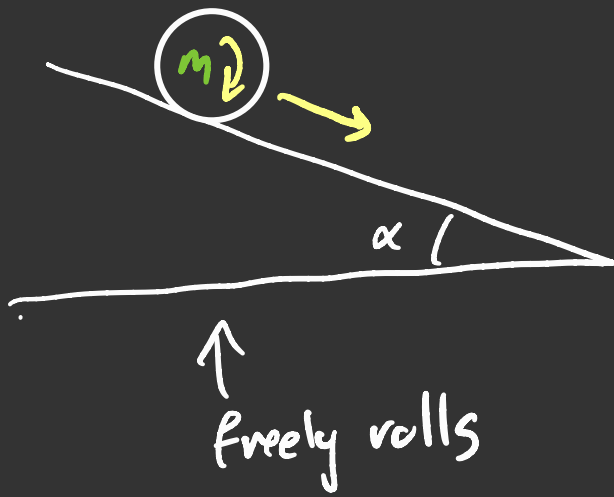
It is hard to measure acceleration of ball in free fall.

In order to find the law of free fall, we can perform the following experiment: instead:



If  $\alpha$  is small, we can measure its displacement easier and exp. will say it moves with constant acceleration.

In fact, the rolling ball moves with different acceleration!

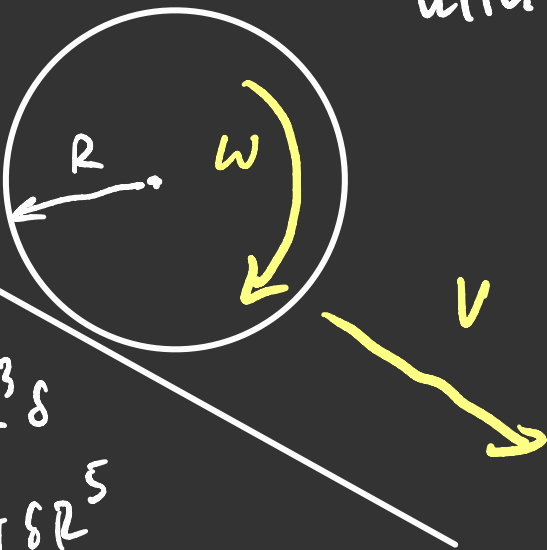


consider instead a frictionless block of equal mass  $m$  sliding down

Do they move down with same acceleration?

NO.

When ball moves, moves down at speed  $v$  with angular velocity



$$\omega = \frac{v}{R}$$

Kinetic energy

$$= \frac{1}{2} m v^2 + \frac{1}{2} I \omega^2$$

translation + rotation

$$m = \frac{4}{3} \pi R^3 \delta$$

$$I = \frac{8}{15} \pi \delta R^5$$

$$E = \frac{4}{3} \pi R^3 \delta v^2 + \frac{8}{15} \pi \delta R^5 \left( \frac{v^2}{R^2} \right) = \left( \frac{4}{3} + \frac{8}{15} \right) \pi R^3 \delta \frac{v^2}{2}$$

$$E = \underbrace{\left( \frac{4}{3} + \frac{2}{15} \right)}_{M_{\text{eff}}} \pi R^3 \delta \frac{v^2}{2}$$

rolling ball

$$E = \frac{4}{3} \pi R^3 \delta \frac{v^2}{2}$$

sliding block

$M_{\text{eff}}$  is effective mass that arises since some of the energy is expressed in "rolling" degrees of freedom

$M_{\text{eff}}$  is 40% larger than  $m$ .

If you put a ball (or brick) that slides down, its acceleration is 40% larger than the rolling ball.

That is, rolling ball will move down slower than the sliding ball.