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> with(plots):
  with(DEtools):
> xphug:=R-> [diff(theta(t),t) = (v(t)^2 - cos(theta(t)))/(v(t)),
              diff(v(t),t) = -sin(theta(t))-R*v(t)^2,
              diff(x(t),t) = v(t)*cos(theta(t)),
              diff(y(t),t) = v(t)*sin(theta(t))];

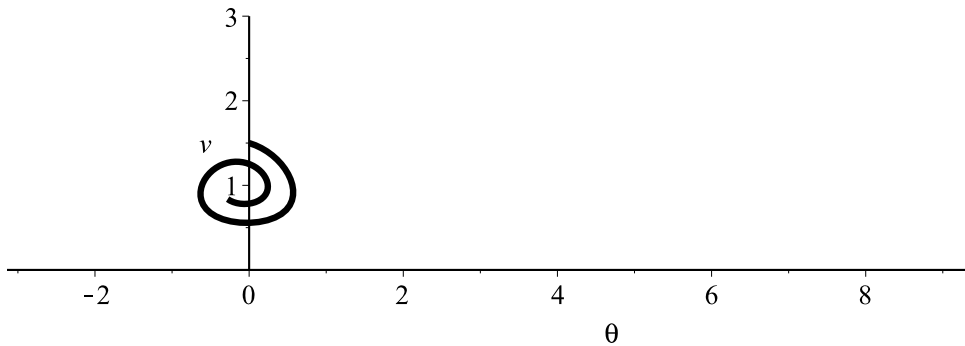
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$$xphug := R \rightarrow \left[\frac{d}{dt} \theta(t) = \frac{v(t)^2 - \cos(\theta(t))}{v(t)}, \frac{d}{dt} v(t) = -\sin(\theta(t)) - R v(t)^2, \frac{d}{dt} x(t) = v(t) \cos(\theta(t)), \frac{d}{dt} y(t) = v(t) \sin(\theta(t)) \right] \quad (1)$$

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> DEplot(xphug(.1), [theta,v,x,y], t=0..7,
          [[theta(0)=0, v(0)=1.5, x(0)=0, y(0)=3]],
          theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
          linecolor=black, stepsize=0.1, obsrange=false,
          scene=[theta,v]);

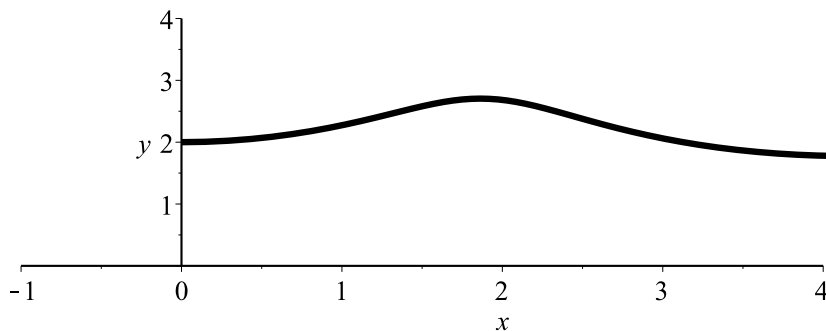
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> DEplot(xphug(.1), [theta,v,x,y], t=0..7,
          [[theta(0)=0, v(0)=1.5, x(0)=0, y(0)=2]],
          theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
          linecolor=black, stepsize=0.1, obsrange=false,
          scene=[x,y]);

```



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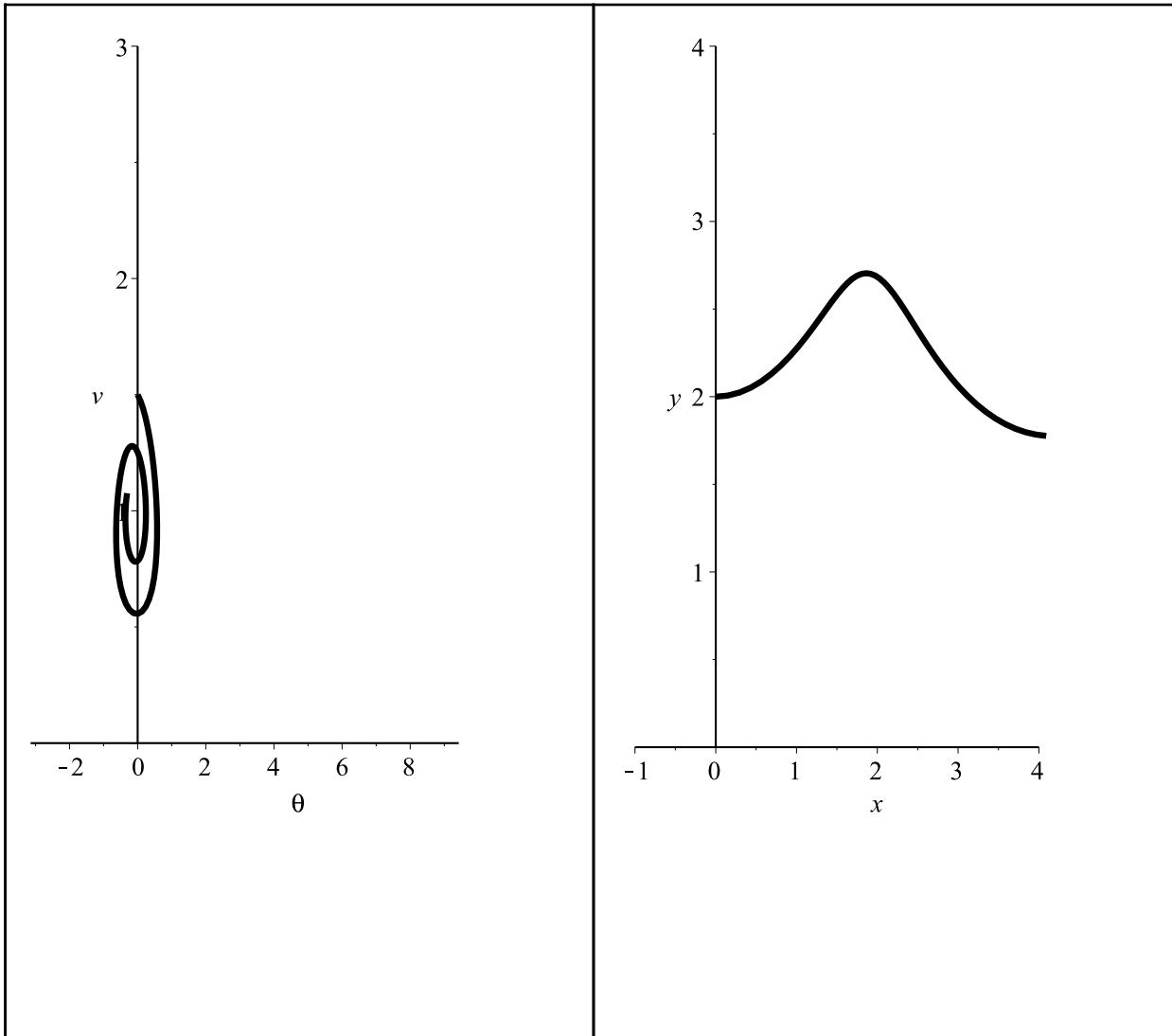
> display(
  Array([DEplot(xphug(.1), [theta,v,x,y], t=0..8,
                [[theta(0)=0, v(0)=1.5, x(0)=0, y(0)=2]],
                theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,

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linecolor=black, stepsize=0.1, obsrange=false,
scene=[theta,v]),
DEplot(xphug(.1), [theta,v,x,y], t=0..8,
[[theta(0)=0, v(0)=1.5, x(0)=0, y(0)=2]],
theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
linecolor=black, stepsize=0.1, obsrange=false,
scene=[x,y]]));

```



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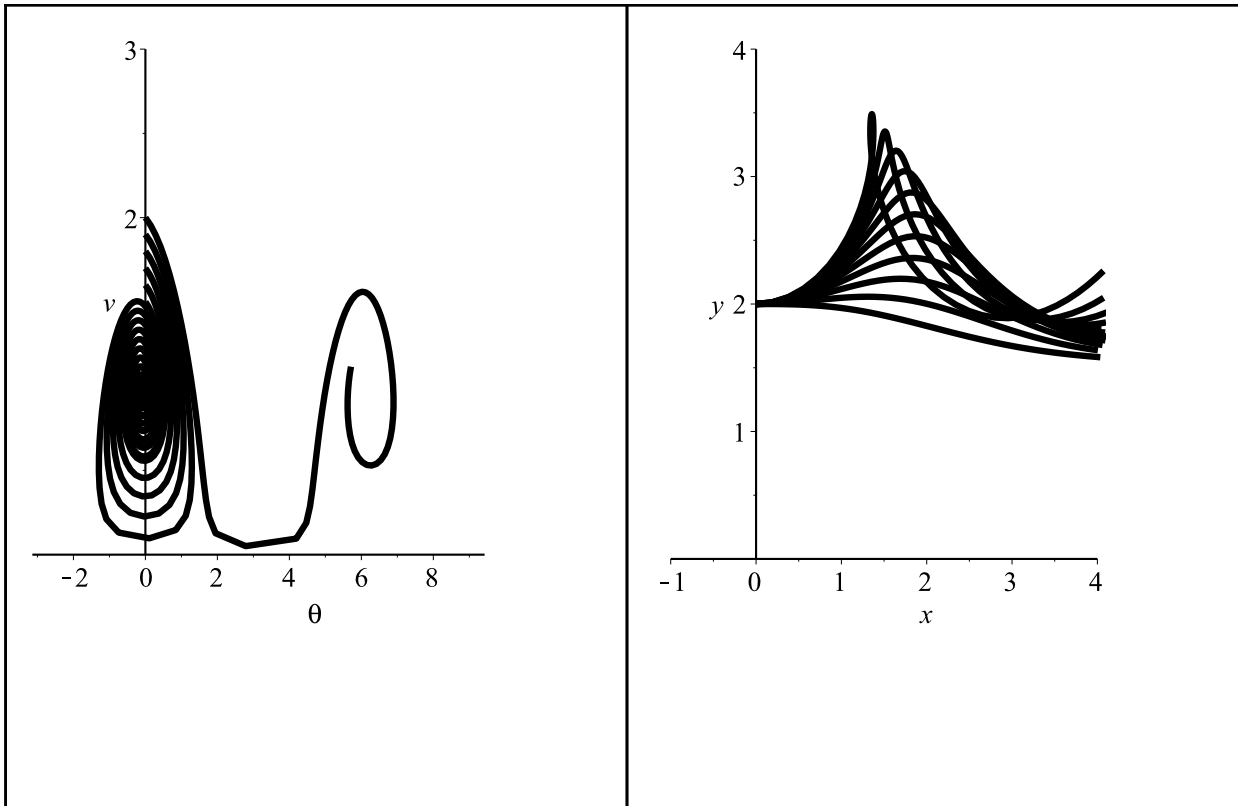
> Plot4 := proc(vmin, vmax, numv)
local inits,vi;
inits:= [seq( [theta(0)=0, v(0)=vi, x(0)=0, y(0)=2],
vi=vmin..vmax, (vmax-vmin)/numv )];
display(
Array([DEplot(xphug(.1), [theta,v,x,y], t=0..8,
inits,
theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
linecolor=black, stepsize=0.1, obsrange=false,
scene=[theta,v]),
DEplot(xphug(.1), [theta,v,x,y], t=0..8,
inits,
theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
linecolor=black, stepsize=0.1, obsrange=false,

```

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    scene=[x,y]))
end:
> Plot4(1,2,10);

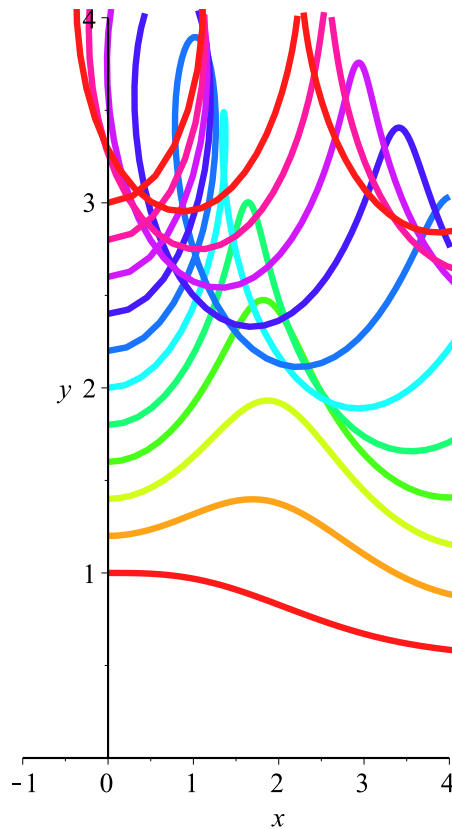
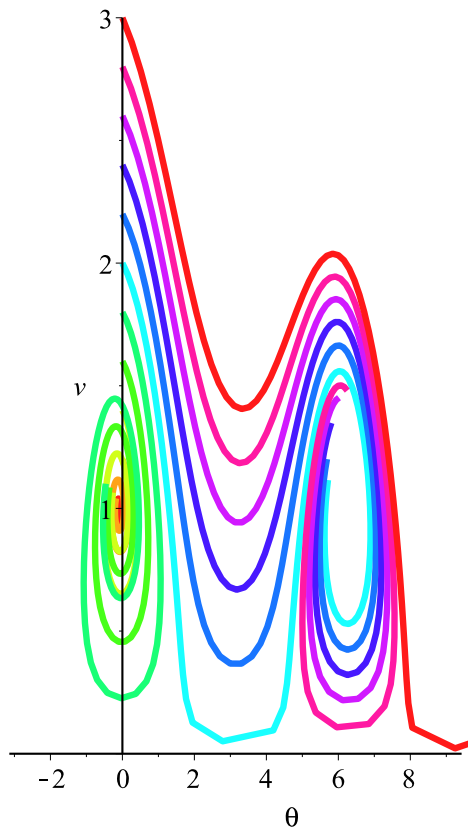
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> Plot4 := proc(vmin, vmax, numv)
local inits,vi,i,cols;
inits:= [seq( [theta(0)=0, v(0)=vi, x(0)=0, y(0)=vi],
  vi=vmin..vmax, (vmax-vmin)/numv )];
cols:= [seq(COLOR(HUE,i),i=0..1,1/numv)];
display(
Array([DEplot(xphug(.1), [theta,v,x,y], t=0..8,
  inits,
  theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
  linecolor=cols, stepsize=0.1, obsrange=false,
  scene=[theta,v]),
DEplot(xphug(.1), [theta,v,x,y], t=0..8,
  inits,
  theta=-Pi..3*Pi, v=0..3, x=-1..4, y=0..4,
  linecolor=cols, stepsize=0.1, obsrange=false,
  scene=[x,y])]))
end:
> Plot4(1,3,10);

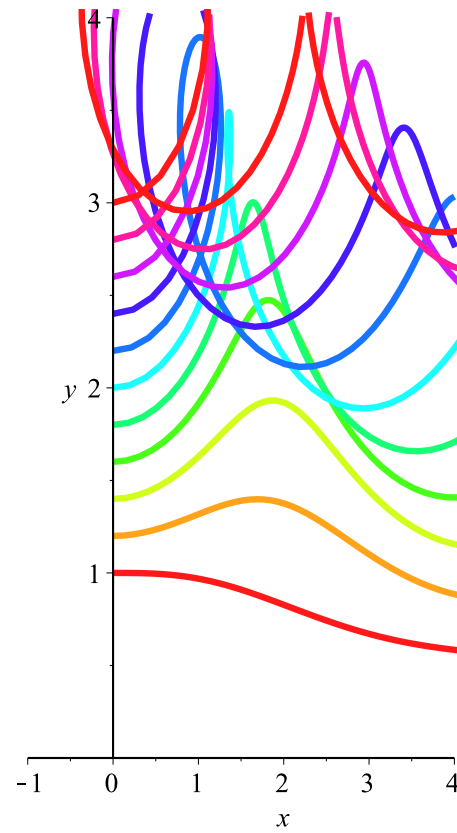
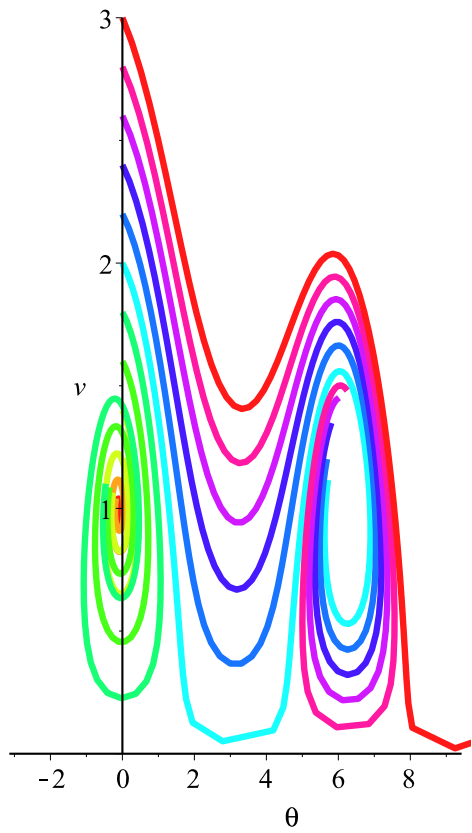
```



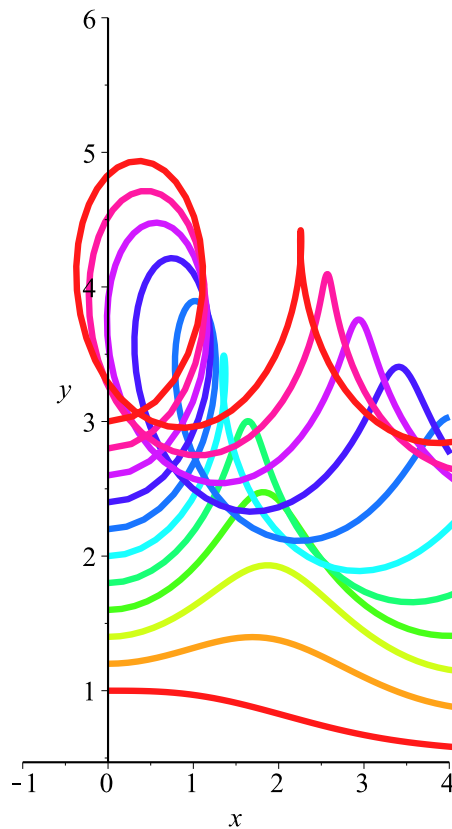
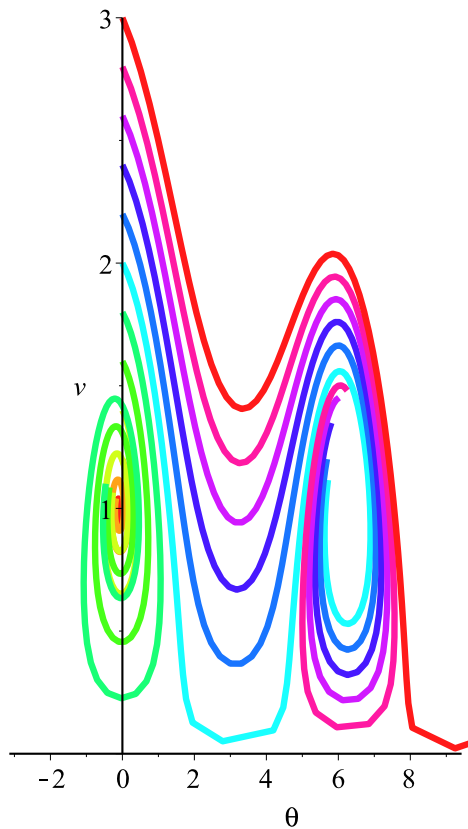
```

> Plot4 := proc(vmin, vmax, numv, {yrange:=0..4})
  local inits,vi,i,cols;
  inits:= [seq( [theta(0)=0, v(0)=vi, x(0)=0, y(0)=vi],
    vi=vmin..vmax, (vmax-vmin)/numv )];
  cols:= [seq(COLOR(HUE,i),i=0..1,1/numv)];
  display(
    Array([DEplot(xphug(.1), [theta,v,x,y], t=0..8,
      inits,
      theta=-Pi..3*Pi, v=0..3, x=-1..4, y=yrange,
      linecolor=cols, stepsize=0.1, obsrange=false,
      scene=[theta,v]),
      DEplot(xphug(.1), [theta,v,x,y], t=0..8,
        inits,
        theta=-Pi..3*Pi, v=0..3, x=-1..4, y=yrange,
        linecolor=cols, stepsize=0.1, obsrange=false,
        scene=[x,y])]))
  end:
> Plot4(1,3,10);

```



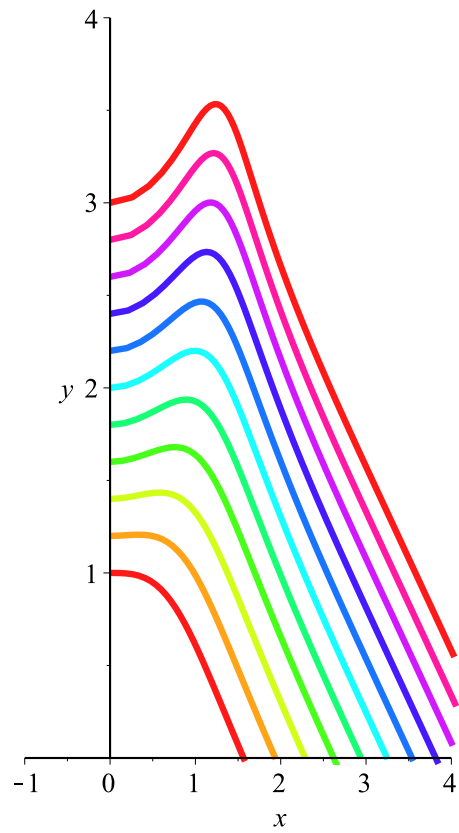
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> Plot4(1,3,10,yrange=.5..6);
```



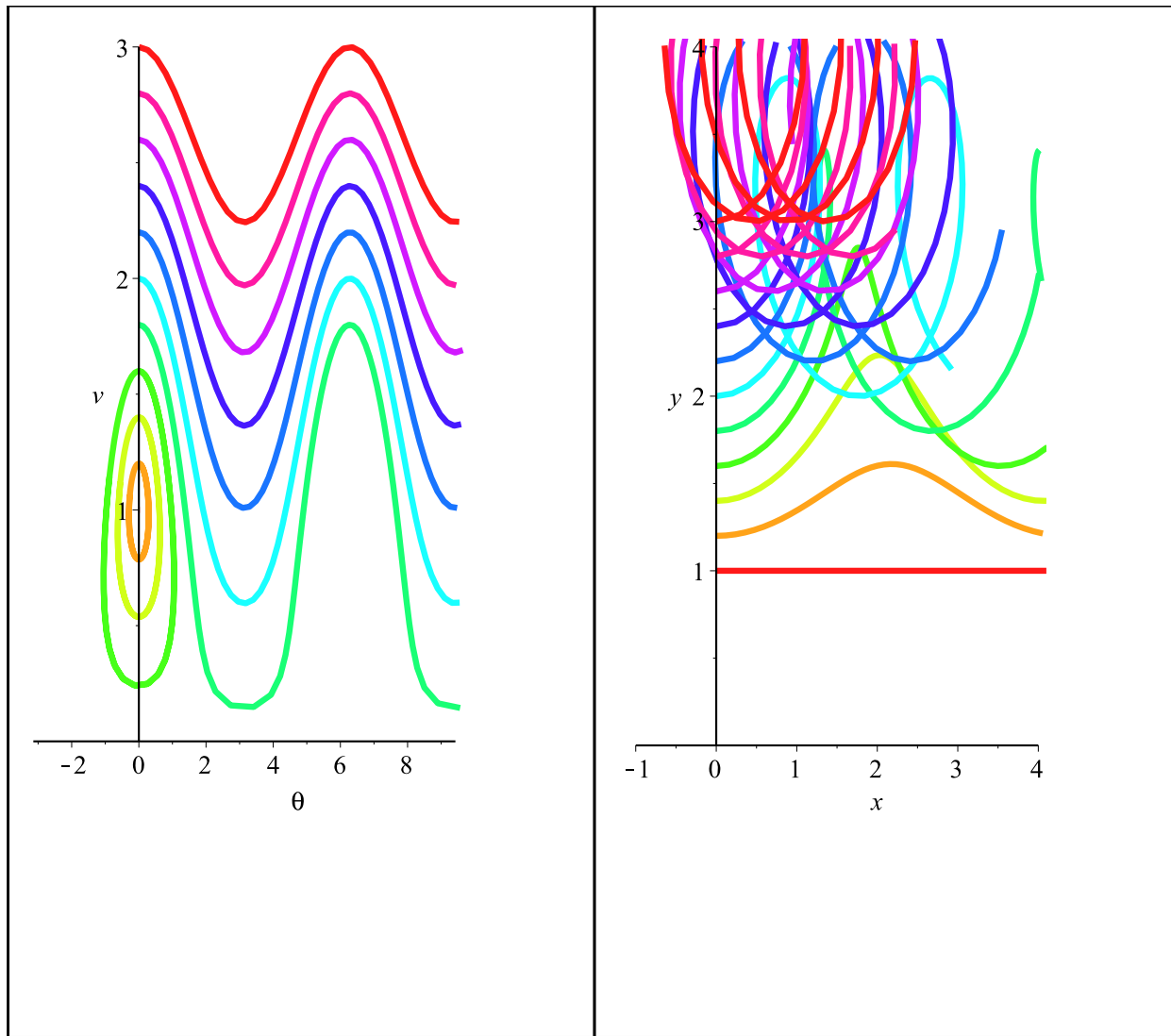
```

> Plot4 := proc(vmin, vmax, numv, {yrange:=0..4, R:=0})
  local inits,vi,i,cols;
  inits:= [seq( [theta(0)=0, v(0)=vi, x(0)=0, y(0)=vi],
    vi=vmin..vmax, (vmax-vmin)/numv )];
  cols:= [seq(COLOR(HUE,i),i=0..1,1/numv)];
  display(
    Array([DEplot(xphug(R), [theta,v,x,y], t=0..8,
      inits,
      theta=-Pi..3*Pi, v=0..3, x=-1..4, y=yrange,
      linecolor=cols, stepsize=0.1, obsrange=false,
      scene=[theta,v]),
      DEplot(xphug(R), [theta,v,x,y], t=0..8,
        inits,
        theta=-Pi..3*Pi, v=0..3, x=-1..4, y=yrange,
        linecolor=cols, stepsize=0.1, obsrange=false,
        scene=[x,y])]))
  end:
> Plot4(1,3,10,R=1);

```



```
> display( [seq(Plot4(1,3,10,R=r),r=0..2,.05)], insequence=true);
```



> xpflug(R);

$$\left[\frac{d}{dt} \theta(t) = \frac{v(t)^2 - \cos(\theta(t))}{v(t)}, \frac{d}{dt} v(t) = -\sin(\theta(t)) - R v(t)^2, \frac{d}{dt} x(t) = v(t) \cos(\theta(t)), \right. \\ \left. \frac{d}{dt} y(t) = v(t) \sin(\theta(t)) \right] \quad (2)$$

> solve({v^2 - cos(theta)=0, -sin(theta)-R*v^2=0}, {v,theta});

$$\{\theta = \arctan(-R \operatorname{RootOf}(-1 + (R^2 + 1) _Z^2), \operatorname{RootOf}(-1 + (R^2 + 1) _Z^2)), v = \operatorname{RootOf}(-\operatorname{RootOf}(-1 + (R^2 + 1) _Z^2) + _Z^2)\} \quad (3)$$

> convert(%,radical);

$$\left\{ \theta = \arctan\left(-R \sqrt{\frac{1}{R^2 + 1}}, \sqrt{\frac{1}{R^2 + 1}}\right), v = \left(\frac{1}{R^2 + 1}\right)^{1/4} \right\} \quad (4)$$