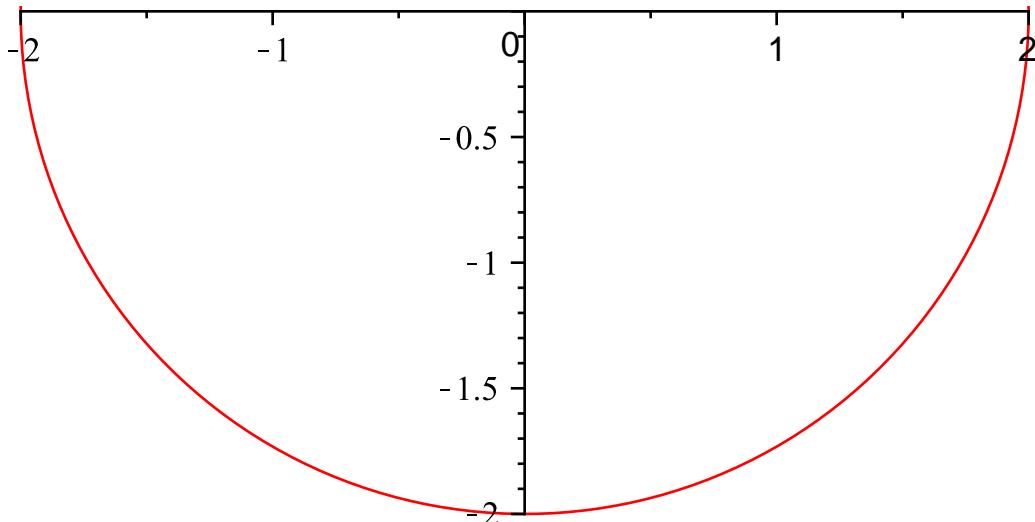


► Load from web stuff is here.

This is **text mode** with some math coming now $\left(\frac{x^2}{\sin\left(\frac{2 \partial f}{\partial x}\right)} \cdot x_4 \right)$

```
> plot([2*cos(t), 2*sin(t), t=0..2*Pi],  
view=[-2..2, -2..0], scaling=constrained);
```



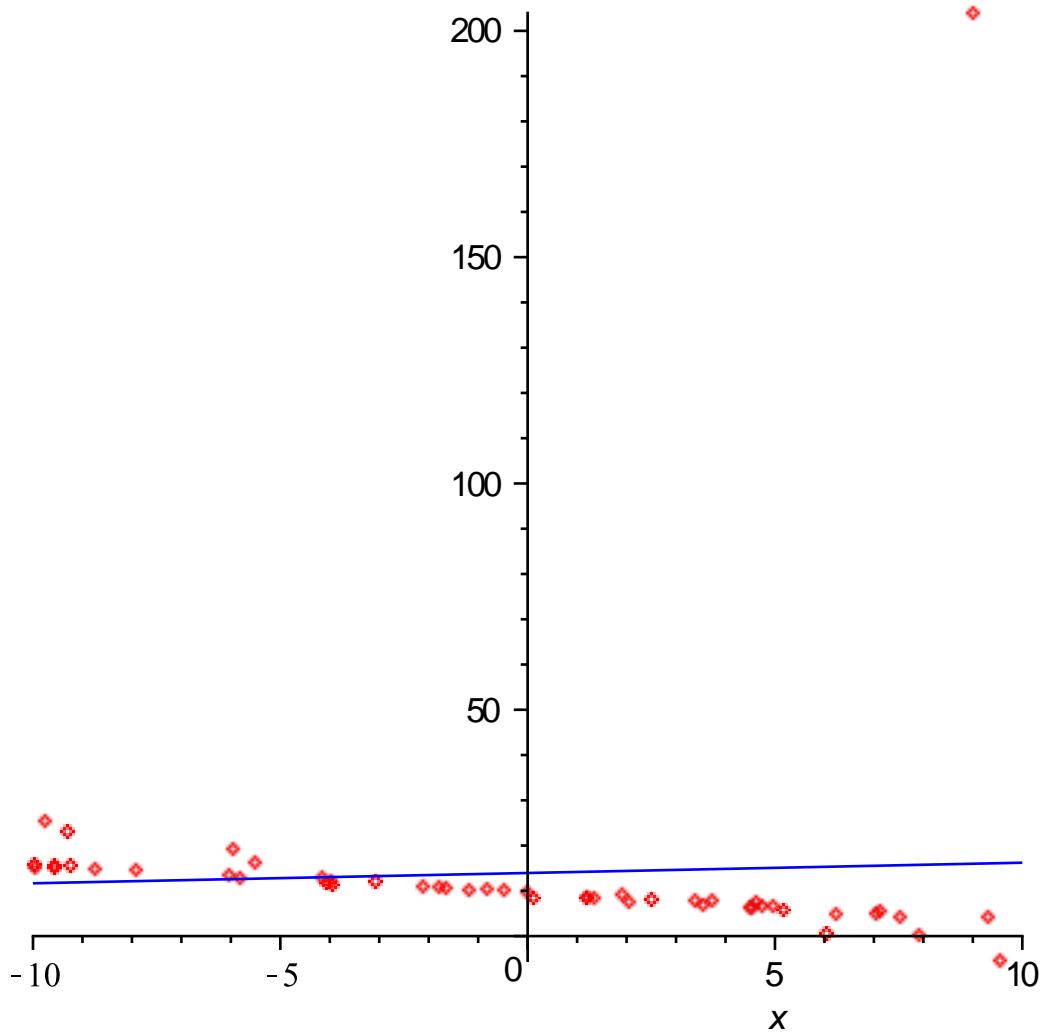
```
> this is green bold stuff.
```

```
> x[3];
```

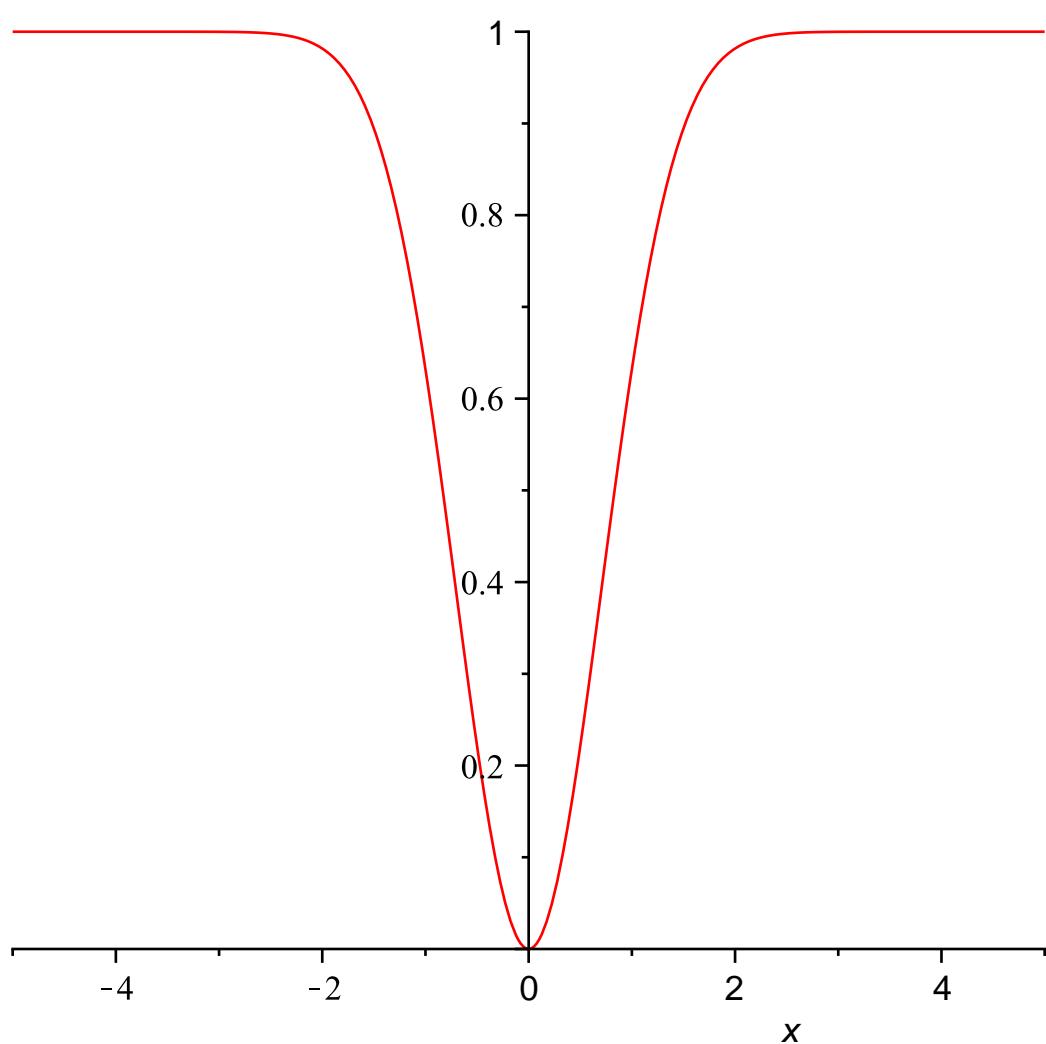
$$x_3 \quad (1)$$

```
> ReadFromWeb(cat(prefix,"lsq_data.txt"));  
with(CurveFitting):  
defined set_seed(s), line_pts(), bad_line_pts(), quadratic_pts()  
( ), exp_pts(), cubic_pts(), and circle_pts()  
> data:=bad_line_pts();  
plot([data, LeastSquares(data,x)], x=-10..10, style=[point, line],  
color=[red, blue]);  
data := [[-5.818106482, 12.77212553], [-0.818076106, 10.32993747], [-3.978311906, 12.22404227], [-1.652874364, 10.66471126],
```

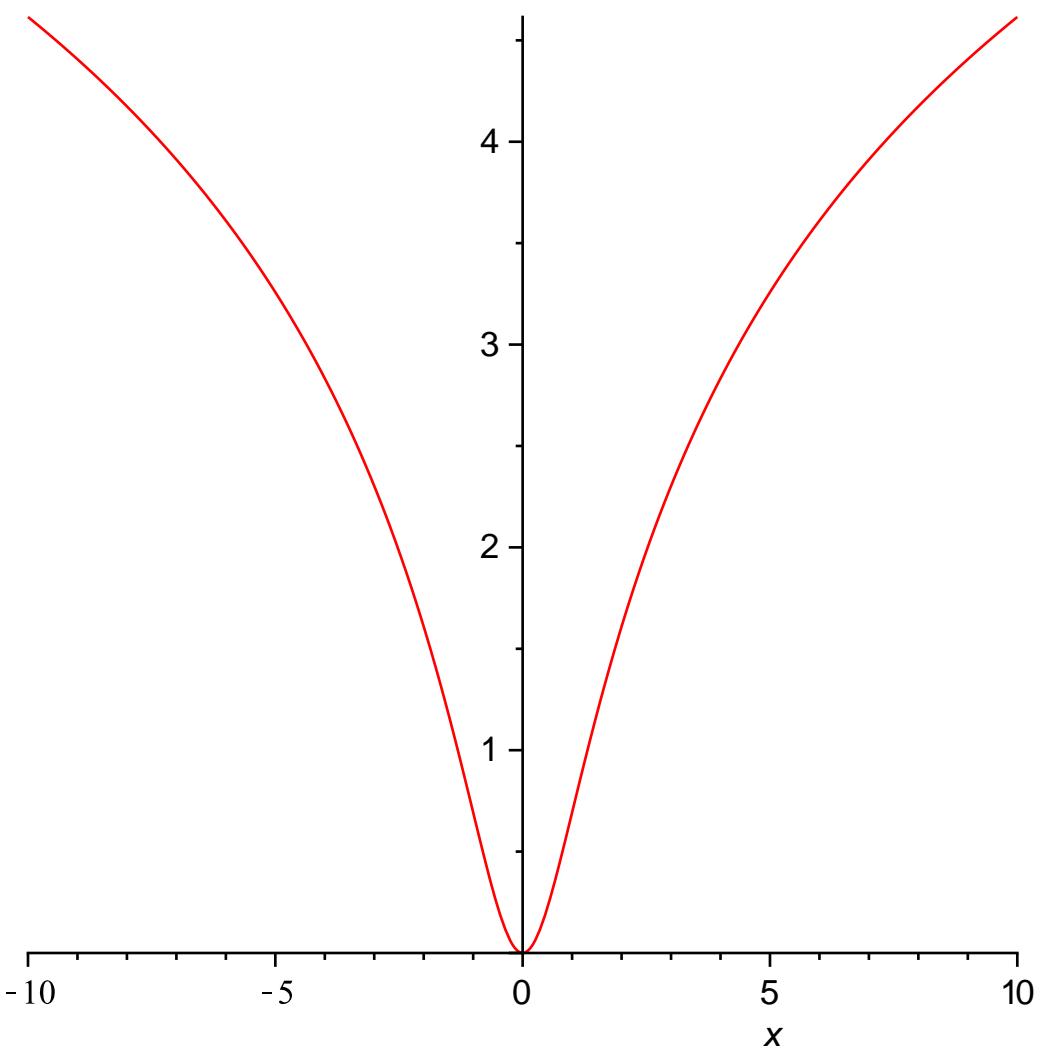
```
[4.74100921, 6.629799700], [-4.161209104, 12.97065701], [-9.244878967, 15.58880592], [3.73215737, 7.888272588], [-9.966969382, 15.84750500], [-8.751836722, 14.80480497], [-9.568251031, 15.58892855], [6.22812174, 4.808403058], [-1.795496706, 10.81573930], [1.90087358, 9.193253168], [-0.483809740, 10.20954010], [4.62224188, 7.480511874], [5.17254288, 5.751833858], [1.33864773, 8.362658071], [4.49864442, 6.349101244], [-3.945185484, 11.28261858], [7.53082987, 4.229521738], [3.54784565, 6.917151108], [-0.007054776, 9.729999636], [7.03834320, 5.016859239], [-7.914202782, 14.541192611], [2.50473190, 8.068621782], [-2.121873998, 10.98432108], [3.37859998, 7.831814257], [-9.566885949, 15.02955044], [2.05517497, 7.588419783], [4.95622739, 6.677813947], [-6.036594624, 13.45127081], [-3.073018440, 12.05459222], [9.30365148, 4.144406666], [0.11753379, 8.350491064], [-1.179301340, 10.20303836], [-4.068629672, 11.75336320], [-9.964646894, 15.12404073], [1.19156213, 8.422833607], [7.12928358, 5.558137021], [4.52889004, 6.319315304], [1.20194762, 8.587981108], [-9.760082609, 25.49495061], [-9.303682212, 23.10665064], [-5.958013710, 19.23827142], [-5.506327605, 16.24163082], [7.914762572, 0.175488813], [6.043252816, 0.602078588], [9.546060889, -5.425573476], [9, 203.93918001]
```



```
> plot(1-exp(-x^2), x=-5..5);
```



```
> plot( log(1+x^2), x=-10..10);
```



```

> log(1+100^2);
                                         ln(10001)                                     (2)
=
> evalf(%);
                                         9.210440367                                (3)
=
> epsilon:= (m,b,pt) -> ( m*pt[1]+b - pt[2]);
                                         ε := (m, b, pt) → m pt1 + b - pt2          (4)
=
> H:= (m,b, data)-> sum(epsilon(m,b,data[i])^2
                           , i=1..nops(data));
                                         nops(data)
                                         H := (m, b, data) → ∑ ε(m, b, datai)2           (5)
                           i=1
=
> K:=(m,b, data)->sum(ln(1+epsilon(m,b,data[i])^2)
                           , i=1..nops(data));
                                         nops(data)
                                         K := (m, b, data) → ∑ ln(1 + ε(m, b, datai)2)      (6)
                           i=1
=
> mtaylor(ln(1+x^2),x);
                                         x2 − 1/2 x4                                     (7)

```

```

> solve( { diff(K(m,b,data),m)=0,
    diff(K(m,b,data),b)=0});
Warning, computation interrupted
> J:=(m,b, data)->sum(1-exp(-epsilon(m,b,data[i])^2)
    , i=1..nops(data));

```

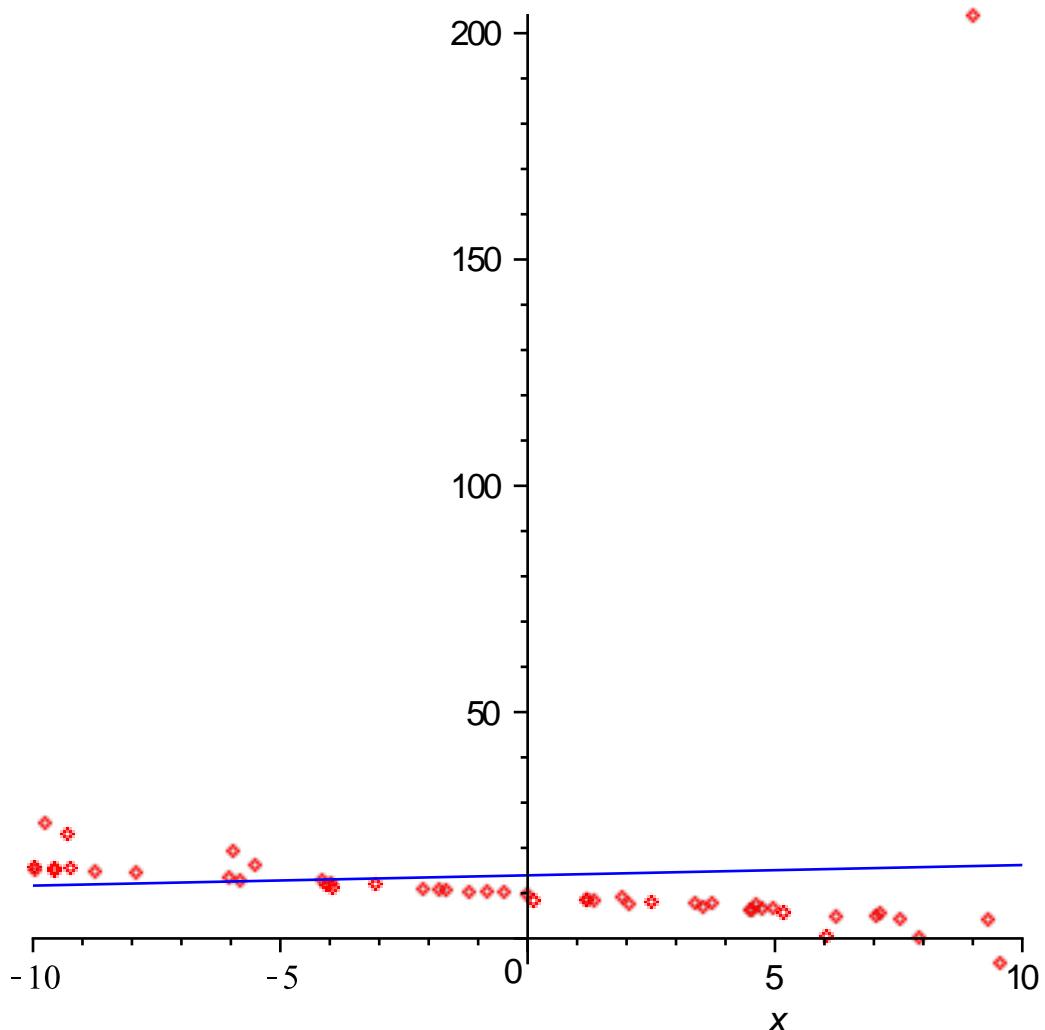
$$J := (m, b, \text{data}) \rightarrow \sum_{i=1}^{\text{nops}(\text{data})} \left(1 - e^{-\epsilon(m, b, \text{data}_i)^2} \right) \quad (8)$$

```

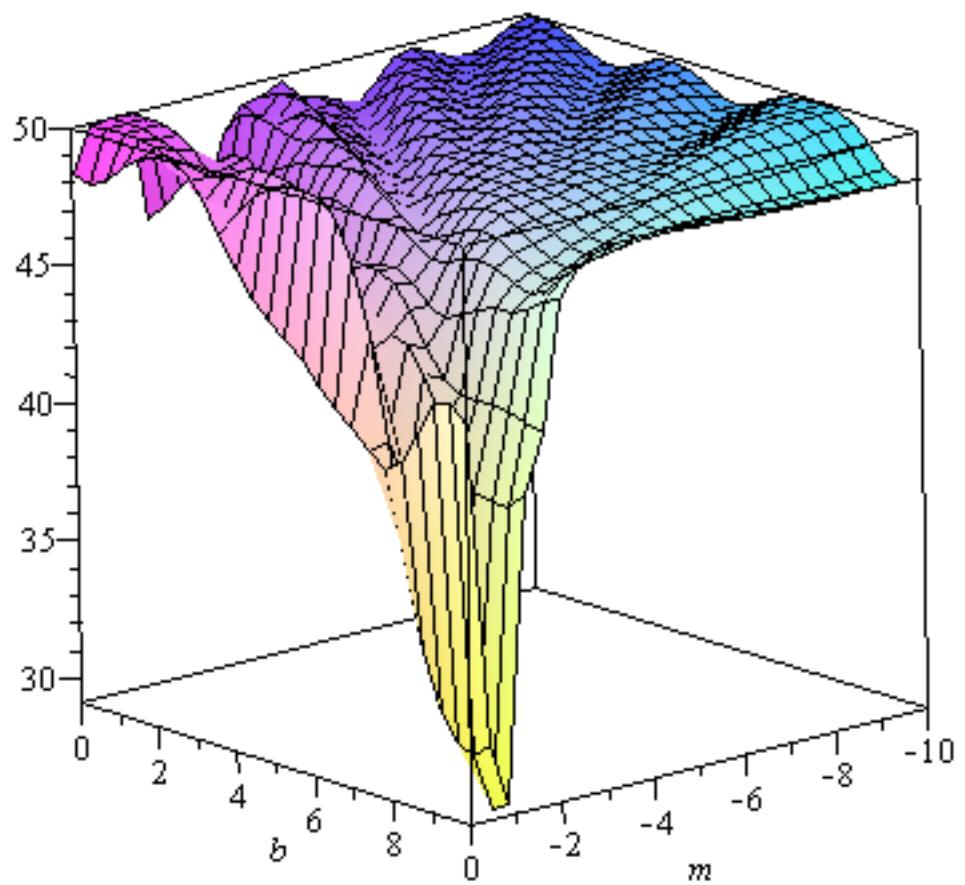
> solve( { diff(J(m,b,data),m)=0,
    diff(J(m,b,data),b)=0});
Warning, solutions may have been lost

```

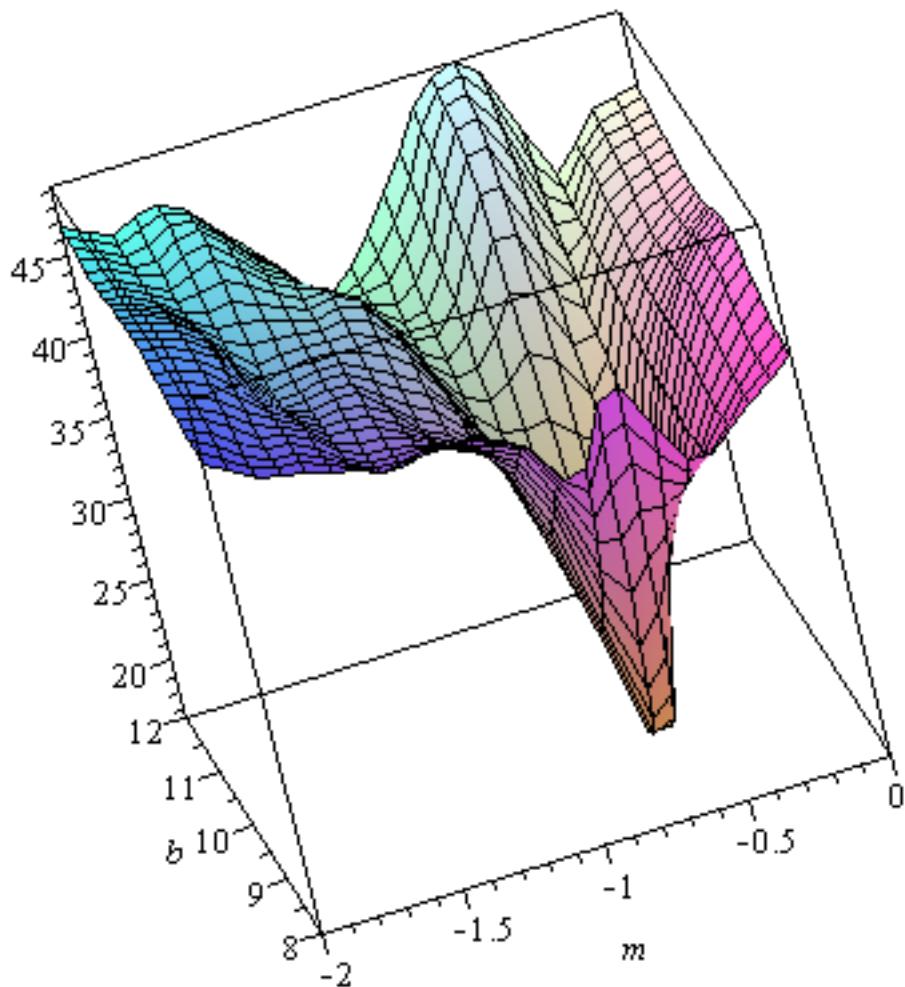
```
> plot([data, LeastSquares(data,x)],x=-10..10,style=[point,line],
color=[red,blue]);
```



```
> plot3d( J(m,b,data), m=-10..0, b=0..10, axes=boxed);
```



```
> plot3d( J(m,b,data), m=-2..0, b=8..12, axes=boxed);
```

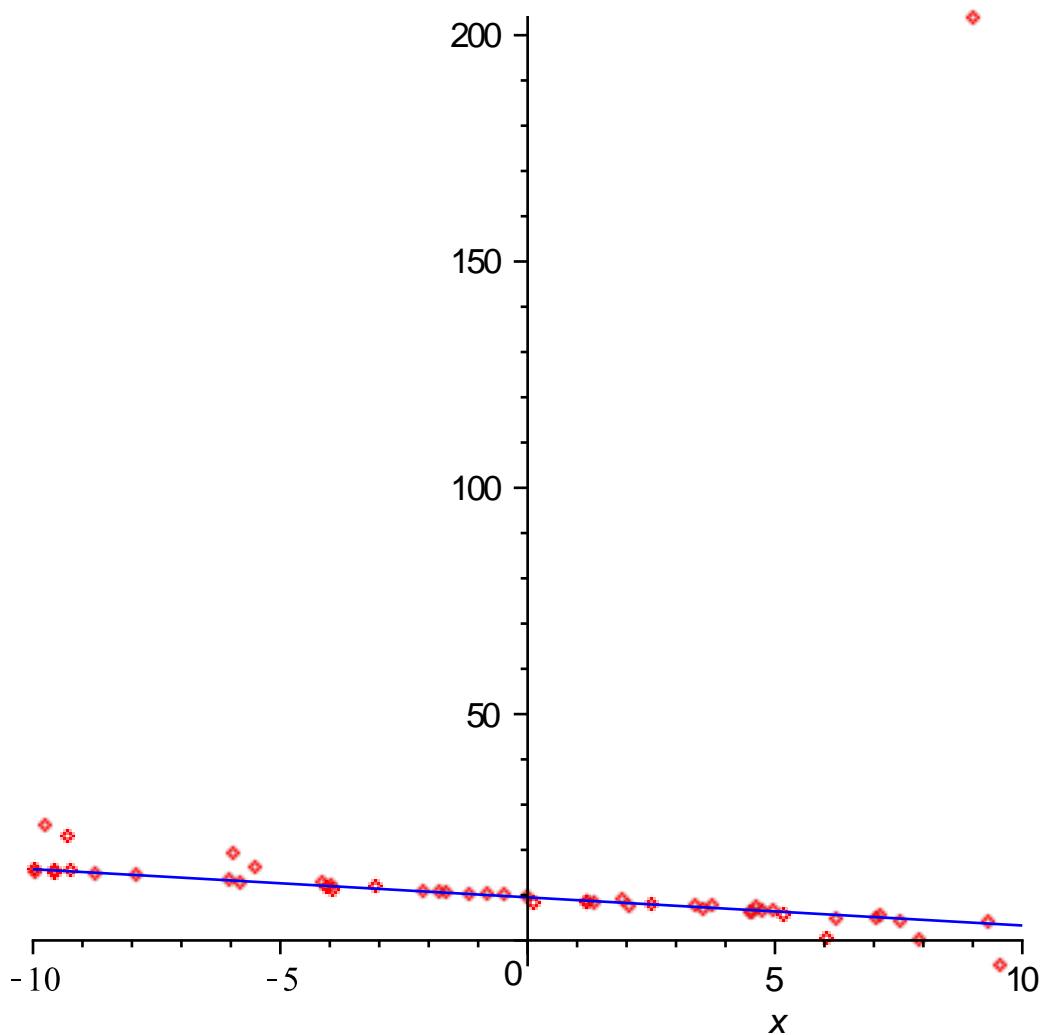


```
> fsolve( { diff(J(m,b,data),m)=0,
    diff(J(m,b,data),b)=0}, {m=-2, b=8});
{b = 2.964483834, m = -2.292699416} (9)
```

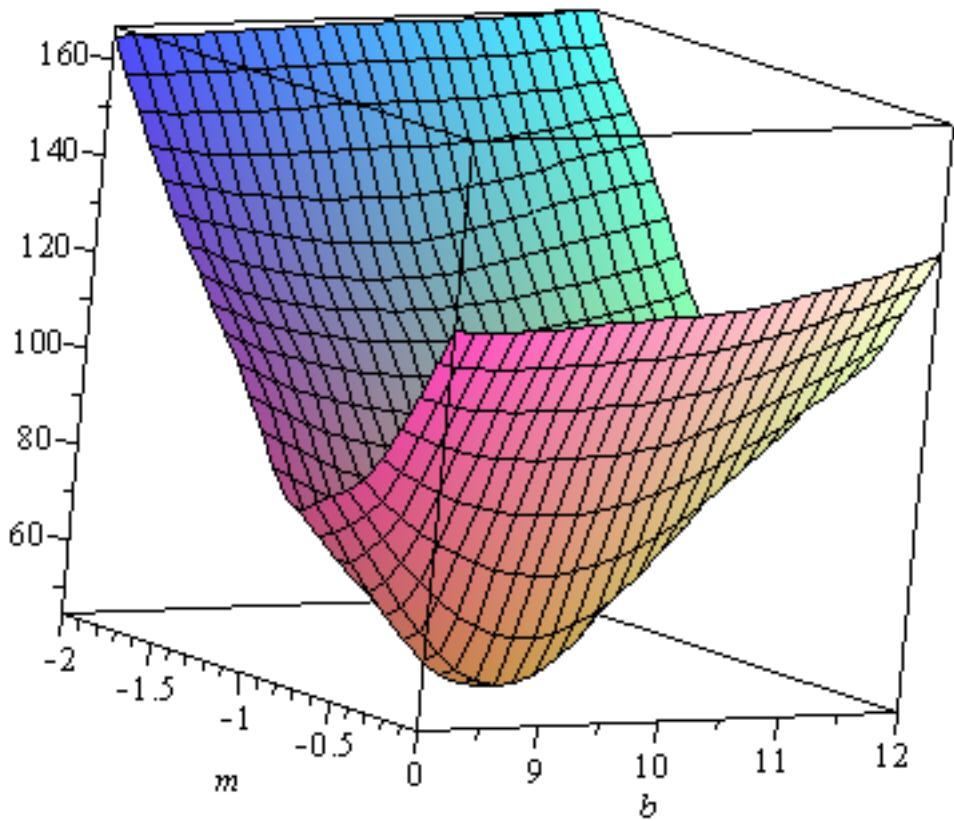
```
> Jsol:=fsolve( { diff(J(m,b,data),m)=0,
    diff(J(m,b,data),b)=0}, {m=-1..0, b=9..10});
Jsol := {b = 9.515628333, m = -0.6220230863} (10)
```

```
> Jline:=subs(Jsol, m*x+b);
Jline := -0.6220230863 x + 9.515628333 (11)
```

```
> plot([data, Jline],x=-10..10,style=[point,line], color=[red,blue]
);
```



```
> plot3d( K(m,b,data), m=-2..0, b=8..12, axes=boxed);
```



```
> Ksol:=fsolve( { diff(K(m,b,data),m)=0,
diff(K(m,b,data),b)=0}, {m=-1..0, b=9..10});
Ksol := {b = 9.508357224, m = -0.6328367475} (12)
```

```
> ?minimize
> Optimization[Minimize](K(m,b,data));
[43.6010402344630066, [b = 9.50835722229077, m = -0.632836747332637]] (13)
```