## homework assignment 4

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**Exercise 8**. Let V be the space of  $2 \times 2$  matrices over F. Find a basis  $\{A_1, A_2, A_3, A_4\}$  for V such that  $A_j^2 = A_j$  for each j.

**Solution** If we start with the canonical basis for V, namely

$$\mathfrak{B} = \left\{ B_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, B_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, B_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, B_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

we notice that the first and the last elements satisfy the required condition. Therefore we only need to find other two matrices, such that the four matrices generate V. Let

$$\mathfrak{A} = \left\{ A_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, A_2 = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, A_3 = \begin{pmatrix} 0 & 0 \\ 1 & 1 \end{pmatrix}, A_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

Notice that  $A_j^2 = A_j$  and  $A_2 - A_1 = B_2$  and  $A_3 - A_1 = B_3$ . Therefore  $\mathfrak{A}$  is a basis for V

**Bonus exercise 14**. Let V be the set of real numbers. Regard V as a vector space over the field of *rational* numbers, with the usual operations. Prove that this vector space is *not* finite-dimensional.

**Solution**: By contradiction. Suppose that V is finite dimensional, this implies that V is a countable set (see the lemma below), but the set of real numbers is not countable!

**Lemma 1.** A finite dimensional vector space V over the rational numbers is a countable set.

*Proof.* By induction on n = the number of elements in a basis for V. **Base:** n = 1 Let  $\{\alpha\}$  be a basis for V.

Let  $\{a_1, a_2, \ldots, a_n, \ldots\}$  be an enumeration of the rational numbers, then any element of V may be written as  $a_i\alpha$ . That is,  $V \subset \{a_1\alpha, a_2\alpha, \ldots, a_n\alpha, \ldots\}$  (actually the two sets are equal, but we don't need that fact). Therefore V is countable.

**Inductive Step:** Suppose that *V* is countable if its dimension is less than or equal to *n*. We will prove then that *if the dimension of V is* n + 1 *then it is a countable set.* Let  $\{\beta_1, \ldots, \beta_n, \alpha\}$  be a basis for *V*. By the induction hypothesis we know that the subspace *W* generated by  $\{\beta_1, \ldots, \beta_n\}$  is a countable set. Let



 $\{w_1, w_2, \ldots, w_n, \ldots\}$  be an enumeration for W. Consider the following infinite array:

Following the diagonals we obtain an enumeration of the array. Notice that any element  $v \in V$  may be expressed as  $v = a_{i_1}\beta_1 + \ldots + a_{i_n}\beta_n + a_{i_{n+1}}\alpha$  but the first n summands of the right hand side of the equality equal some  $w_j \in W$  therefore we may rewrite the equation as  $v = w_j + a_{i_{n+1}}\alpha$ , but this element is contained in the array, i.e. V is contained in a countable set, therefore it is countable.

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 $e_{xepcise} i$ . Show that the vectors

$$\begin{aligned} \alpha_1 &= (1, 1, 0, 0) \quad \alpha_2 &= (0, 0, 1, 1) \\ \alpha_3 &= (1, 0, 0, 4) \quad \alpha_4 &= (0, 0, 0, 2). \end{aligned}$$

form a basis in  $\mathbb{R}^4$ . Find the coordinates of each of the standard basis vectors in the ordered basis  $\{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$ .

**Solution:** Write the  $4 \times 4$  matrix A whose columns are 4-tuples  $\alpha_1, \alpha_2, \alpha_3$  and  $\alpha_4$ . Check that this matrix is row (or column) equivalent to the identity matrix. Then its columns are linearly independent which means that  $\alpha_1, \alpha_2, \alpha_3$  and  $\alpha_4$  form a basis in  $\mathbb{R}^4$  (since any n linearly independent vectors in an n-dimensional space form a basis). Note that the matrix A is the transition matrix from the standard basis  $e_1 = (1, 0, 0, 0), e_2 = (0, 1, 0, 0), e_3 = (0, 0, 1, 0), e_4 = (0, 0, 0, 1)$  to the basis  $\{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$ , i.e. its *i*-th column gives coordinates of the vector  $\alpha_i$  relative to the standard basis. Or in the matrix form:

$$(\alpha_1, \alpha_2, \alpha_3, \alpha_4) = (e_1, e_2, e_3, e_4)A.$$

Multiplying both sides by  $A^{-1}$  from the right, we get that the inverse matrix  $A^{-1}$  is the transition matrix from the basis  $\{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$  to the standard basis, i.e. its

*i*-th column gives coordinates of the vector  $e_i$  relative to the basis  $\{\alpha_1, \alpha_2, \alpha_3, \alpha_4\}$ . It remains to compute  $A^{-1}$ .

**EXERCISE** 2. Find the coordinate matrix of the vector v = (1, 0, 1) in the basis  $\mathcal{B}$  of  $\mathbb{C}^3$  consisting of the vectors (2i, 1, 0), (2, -1, 1), (0, 1 + i, 1 - i) in that order. **Solution:** Let  $\mathcal{A}$  denote the canonical basis for  $\mathbb{C}^3$ . Then we know that  $[v]_{\mathcal{B}} = P[v]_{\mathcal{A}}$  where the columns of P are given by the coordinates in  $\mathcal{B}$  of the elements in  $\mathcal{A}$ . Therefore

$$P^{-1} = \begin{pmatrix} 2i & 2 & 0\\ 1 & -1 & 1+i\\ 0 & 1 & 1-i \end{pmatrix}, P = \begin{pmatrix} \frac{1}{2} - \frac{1}{2}i & -i & -1\\ -\frac{1}{2}i & -1 & i\\ \frac{1}{4} + \frac{1}{4}i & \frac{1}{2} + \frac{1}{2}i & 1 \end{pmatrix}$$

and thus, the coordinates of v are  $\left(-\frac{1}{2}(1+i), \frac{1}{2}i, \frac{1}{4}(3+i)\right)$ .

**EXERCISE 4**. Let W be the subspace of  $\mathbb{C}^3$  spanned by  $\alpha_1 = (1,0,i)$  and  $\alpha_2 = (1+i,1,-1)$ .

(a) Show that  $\alpha_1$  and  $\alpha_2$  form a basis for W.

(b) Show that the vectors  $\beta_1 = (1, 1, 0)$  and  $\beta_2 = (1, i, 1 + i)$  are in W

and form another basis for  $\boldsymbol{W}$ 

(c) What are the coordinates of  $\alpha_1$  and  $\alpha_2$  in the ordered basis  $\{\beta_1, \beta_2\}$ ?

**Solution 1**: (a) Form the  $3 \times 2$  matrix  $A(\alpha)$  whose columns are triples  $\alpha_1$  and  $\alpha_2$ . Check that its row (or column) reduced form does contain two nonzero rows (or columns). This proves that  $\alpha_1, \alpha_2$  are linearly independent. Hence, they form a basis for W.

(b)(c) To show that  $\beta_1, \beta_2$  are linearly independent repeat the argument of part (a).

The vector  $\beta_1$  lies in *W* if and only if there exist scalars  $x_1, x_2$  such that  $x_1\alpha_1 + x_2\alpha_2 = \beta_1$ . In other words, the system of 3 equations in 2 unknowns

$$A(\alpha) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \beta_1 \tag{1}$$

is consistent (here the triple  $\beta_1$  is written as column). The same is for  $\beta_2$ . Hence, to show that system (1) and the corresponding system for  $\beta_2$  are consistent, and to find their solutions one needs to row reduce a  $3 \times 4$  matrix whose columns are triples  $\alpha_1, a_2, \beta_1, \beta_2$ . Then the coefficients of the row reduced matrix give the solutions of the systems, i.e. the coordinates of  $\beta_1, \beta_2$  relative to the basis  $\alpha_1, \alpha_2$ . Conversely, to find the coordinates of  $\alpha_1, \alpha_2$  relative to the basis  $\beta_1, \beta_2$  row reduce the  $3 \times 4$  matrix whose columns are triples  $\beta_1, \beta_2, \alpha_1, \alpha_2$  (or find the inverse of the  $2 \times 2$  transition matrix from  $\alpha_1, \alpha_2$  to  $\beta_1, \beta_2$ ).

**Solution 2**: Row reducing the matrix with  $\alpha_1$  and  $\alpha_2$  and (0,0,1) as rows, we can check that they are linearly independent, this proves (a). Notice that the solution of (c) implies (b). Let  $\mathcal{B}_1$  be the basis  $\{\alpha_1, \alpha_2, (0,0,1)\}$  for  $\mathbb{C}^3$  and let

 $\mathcal{B}_2 = \{\beta_1, \beta_2, (0, 0, 1)\}$  be another basis for  $\mathbb{C}^3$ . Notice that a change of basis from  $\mathcal{B}_1$  to  $\mathcal{B}_2$  will map W into W, i.e. it will induce the change of bases we want. Let  $\mathcal{A}$  denote the canonical basis for  $\mathbb{C}^3$ . Then we have the following equations:

$$[v]_{\mathcal{B}_1} = P[v]_{\mathcal{B}_2}$$
$$[v]_{\mathcal{B}_1} = S[v]_{\mathcal{A}}$$
$$[v]_{\mathcal{B}_2} = Q[v]_{\mathcal{A}}$$

These equations imply the following equation  $[v]_{\mathcal{B}_1} = SQ^{-1}[v]_{\mathcal{B}_2}$ . Calculating we obtain:

$$S = \begin{pmatrix} 1 & -1-i & 0\\ 0 & 1 & 0\\ -i & i & 1 \end{pmatrix}, Q^{-1} = \begin{pmatrix} 1 & 1 & 0\\ 1 & i & 0\\ 0 & 1+i & 1 \end{pmatrix}, SQ^{-1} = \begin{pmatrix} -i & 2-i & 0\\ 1 & i & 0\\ 0 & 0 & 1 \end{pmatrix}$$

Therefore the matrix which yields the change of bases we want is

$$\begin{pmatrix} -i & 2-i \\ 1 & i \end{pmatrix}$$

This means that  $\beta_1 = -i \cdot \alpha_1 + 1 \cdot \alpha_2$  and  $\beta_2 = (2-i) \cdot \alpha_1 + i \cdot \alpha_2$ .

**EXERCISE** 7. Let *V* be the (real) vector space of all polynomial functions from  $\mathbb{R}$  into  $\mathbb{R}$  of degree 2 or less, i.e. the space of functions of the form

$$f(x) = c_0 + c_1 x + c_2 x^2$$

Let t be a fixed real number and define

$$g_1(x) = 1$$
,  $g_2(x) = x + t$ ,  $g_3(x) = (x + t)^2$ .

Prove that  $\mathcal{B} = \{g_1, g_2, g_3\}$  is a basis for *V*. If

$$f(x) = c_0 + c_1 x + c_2 x^2$$

what are the coordinates of f in the ordered basis  $\mathcal{B}$ ?

solation: Since

$$x^{2} = ((x+t) - t)^{2} = (x+t)^{2} - 2t(x+t) + t^{2}, \quad x = x+t-t$$

we get that

$$f(x) = c_2(x+t)^2 + (c_1 - 2tc_2)(x+t) + (c_0 - tc_1 + t^2c_2)$$

Thus,  $\mathcal{B}$  span the space V, so  $\mathcal{B}$  is a basis. The coordinates of f relative to  $\mathcal{B}$  are  $(c_2, c_1 - 2tc_2, c_0 - tc_1 + t^2c_2)$ , respectively.

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Exercise 2. Let

$$\alpha_1 = (1, 1, -2, 1), \quad \alpha_2 = (3, 0, 4, -1), \quad \alpha_3 = (-1, 2, 5, 2).$$

Let

$$\alpha = (4, -5, 9, -7), \quad \beta = (3, 1, -4, 4), \quad \gamma = (-1, 1, 0, 1).$$

(a) Which of the vectors  $\alpha, \beta, \gamma$  are in the subspace of  $\mathbb{R}^4$  spanned by the  $\alpha_i$ ?

(b) Which of the vectors  $\alpha, \beta, \gamma$  are in the subspace of  $\mathbb{C}^4$  spanned by the  $\alpha_i$ ?

(c) Does this suggest a theorem?

**Solution**: (a)(b) This problem is analogous to part (b) of Exercise 4 (p.55) above. Namely, consider the  $4 \times 6$  matrix whose columns are vectors  $\alpha_1, \alpha_2, \alpha_3, \alpha, \beta, \gamma$ . Row reduce this matrix to see if the systems  $x_1\alpha_1 + x_2\alpha_2 + x_3\alpha_3 = \alpha(=\beta,=\gamma)$  are consistent.

(c) Theorem: Let V be a complex vector space with some basis, and  $v_1, \ldots, v_n$ and v vectors with *real* coordinates with respect to this basis. Then if v is a linear combination of  $v_1, \ldots, v_n$  with *complex* coefficients, then v can also be represented as a linear combination of  $v_1, \ldots, v_n$  with *real* coefficients.

**Exercise 3**. Consider the vectors in  $\mathbb{R}^4$  defined by  $\alpha_1 = (-1, 0, 1, 2), \alpha_2 =$  $(3,4,-2,5), \alpha_3 = (1,4,0,9)$  Find a system of homogeneous linear equations for which the space of solutions is exactly the subspace of  $\mathbb{R}^4$  spanned by the three given vectors.

**Solution** Row reducing the matrix whose rows are the  $\alpha_i$ 's we get

$$\begin{pmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & \frac{1}{4} & \frac{11}{4} \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Therefore we need to find a matrix whose kernel is the space V spanned by  $\{\alpha_1 = (1, 0, -1, -2), \alpha_2 = (0, 1, \frac{1}{4}, \frac{11}{4})\}.$  The set  $\mathcal{B} = \{\alpha_1, \alpha_2, (0, 0, 1, 0), (0, 0, 0, 1)\}$  is a basis for  $\mathbb{R}^4$ . The kernel of the matrix

is exactly the space generated by  $e_1$  and  $e_2$ . Thus, the matrix which maps the canonical basis to the basis  $\mathcal{B}$  will map the kernel of S to the space spanned by  $\alpha_1$  and  $\alpha_2$ . Let P be the change of basis, then the previous assertion expressed in terms of matrices is  $P(\ker(S)) = V$  therefore  $\ker(S) = P^{-1}(V)$ . This means that if we apply S to any vector in  $P^{-1}(V)$  we get 0, that is, if we apply  $P^{-1}$  to any vector in V and then we apply S, we get zero. But this is exactly what we want, to find a transformation whose kernel is V, such a transformation is given by  $SP^{-1}$ . Explicitly a transformations whose kernel is V is

$$SP^{-1} = \begin{pmatrix} 0 & 0 & 0 & 0\\ 0 & 0 & 0 & 0\\ 1 & \frac{1}{4} & 1 & 0\\ -2 & -\frac{11}{4} & 0 & 1 \end{pmatrix}$$

**Exercise 6**. Let V be the real vector space spanned by the rows of the matrix

$$A = \begin{pmatrix} 3 & 21 & 0 & 9 & 0 \\ 1 & 7 & -1 & -2 & -1 \\ 2 & 14 & 0 & 6 & 1 \\ 6 & 42 & -1 & 13 & 0 \end{pmatrix}.$$

(a) Find a basis for V.

(b) Tell which vectors  $v = (x_1, x_2, x_3, x_4, x_5)$  are elements of V.

(c) If  $v = (x_1, x_2, x_3, x_4, x_5)$  is in V what are its coordinates in the basis chosen in part (a)?

**Solution**:(a)(c) Row reduce the matrix A. The nonzero rows of the row reduced matrix  $\tilde{A}$  give the basis in V. It is easy to check that the coordinates of v relative to this basis form an ordered subset of coordinates  $x_1, x_2, x_3, x_4, x_5$ . This subset consists of all  $x_i$  such that i coincides with the number of a column of  $\tilde{A}$  that contains the leading coefficient of a nonzero row.

(b) (The same as part (b) of Exercise 4 (p.55) above.) Take the matrix A whose columns are the basis from part (a) and the vector v. Row reduce it to write the condition on v for the system with augmented matrix A to be consistent.