

MAT 307 LECTURE 18

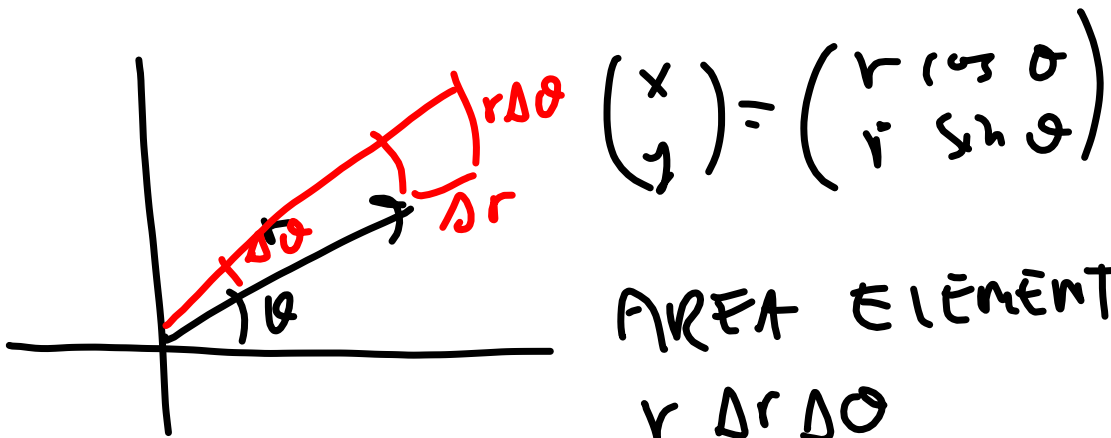
PROOF:

$$\int_a^b \int_c^y \frac{\partial}{\partial y} g(x, y) dy dx$$
$$= \int_a^b g(x, y) - g(x, c) dx$$

TAKING THE DERIVATIVE OUTSIDE
WITH RESPECT TO y OBTAINS
THE RESULT.

CHANGE OF VARIABLES:

POLAR COORDINATES:



$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} r \cos \theta \\ r \sin \theta \end{pmatrix}$$

AREA ELEMENT

$$r \Delta r \Delta \theta$$

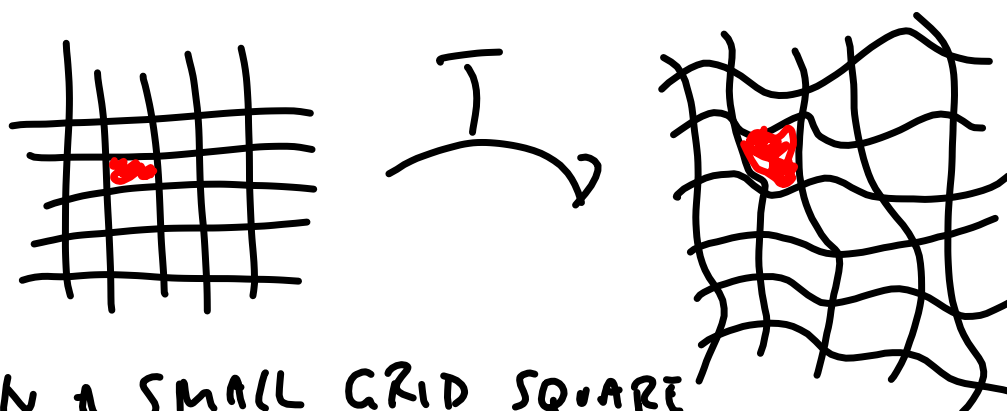
$$\int_D f(x, y) dx dy = \int_E f(r \cos \theta, r \sin \theta) r dr d\theta$$

CYLINDRICAL COORDINATES:

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} r \cos \theta \\ r \sin \theta \\ z \end{pmatrix}$$

AREA ELEMENT: $r \, dr \, d\theta \, dz$.

SKETCH OF THE IDEA:



ON A SMALL GRID SQUARE

T IS WELL APPROXIMATED BY
THE DERIVATIVE T' , WHICH IS
LINEAR

$$\text{AREA}(T(\text{SQUARE})) \approx |\det T'|$$

AREA SQUARE.

POLAR COORDINATES:

$$T: \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} r \cos \theta \\ r \sin \theta \end{pmatrix}$$

$$T' = \begin{pmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{pmatrix}$$

$$\det T' = r \cos^2 \theta + r \sin^2 \theta \\ = r$$

SPHERICAL COORDINATES:

$$T: \begin{pmatrix} p \sin \varphi \cos \theta \\ p \sin \varphi \sin \theta \\ p \cos \varphi \end{pmatrix}$$

$$T': \begin{pmatrix} \sin \varphi \cos \theta & -p \sin \varphi \sin \theta & p \cos \varphi \cos \theta \\ \sin \varphi \sin \theta & p \sin \varphi \cos \theta & p \cos \varphi \sin \theta \\ \cos \varphi & 0 & -p \sin \varphi \end{pmatrix}$$

$$\det T' = p^2 \left\{ \begin{array}{l} \sin \varphi \sin \theta \\ \sin \varphi \cos \theta \\ \cos \varphi \end{array} \middle| \begin{array}{l} \sin \varphi \sin \theta \cos \varphi \cos \theta \\ \cos \varphi - \sin \varphi \end{array} \right\}$$

$$+ \sin \varphi \cos \theta \left\{ \begin{array}{l} \sin \varphi \cos \theta \cos \varphi \cos \theta \\ \cos \varphi - \sin \varphi \end{array} \right\}$$

$$= p^2 \left\{ \begin{array}{l} \sin \varphi \sin^2 \theta \\ \sin \varphi \cos^2 \theta \end{array} \left(\begin{array}{l} \sin^2 \varphi - \cos^2 \varphi \\ \sin^2 \varphi - \cos^2 \varphi \end{array} \right) \right\}$$

$$= -p^2 \sin \varphi.$$

$$|\det T'| = p^2 \sin \varphi.$$

CENTROIDS AND MOMENTS:

$\underline{x}_1, \underline{x}_2, \dots, \underline{x}_N$, POSITIONS.

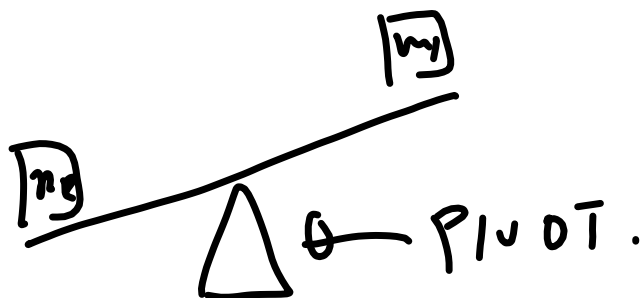
m_1, m_2, \dots, m_N MASSES.

TOTAL MASS: $M = m_1 + \dots + m_N$.

CENTER OF MASS IS THE WEIGHTED AVERAGE OF POSITIONS

$$\underline{\bar{x}} = \frac{1}{M} (m_1 \underline{x}_1 + m_2 \underline{x}_2 + \dots + m_N \underline{x}_N).$$

This is the location in space on which the masses placed on a weightless plate would balance.



THEOREM: LET P AN
ARBITRARY PLANE CONTAINING
CENTER OF MASS \bar{X} , THEN
 $M_P = 0$.

FOR A MASS DENSITY

$$\rho(x) \geq 0$$

THE CENTER OF MASS IS

$$\bar{x} = \frac{1}{M(B)} \cdot \int_B \rho(x) \cdot x \, dx.$$

$$M(B) = \int_B \rho(x) \, dx.$$

E.G. IN 3 DIMENSIONS:

$$\bar{x} = \frac{1}{M(B)} \int_B x \rho(x, y, z) \, dV$$

$$\bar{y} = \frac{1}{M(B)} \int_B y \rho(x, y, z) \, dV$$

$$\bar{z} = \frac{1}{M(B)} \int_B z \rho(x, y, z) \, dV.$$

TO FIND THE AVERAGE
X-COORDINATE

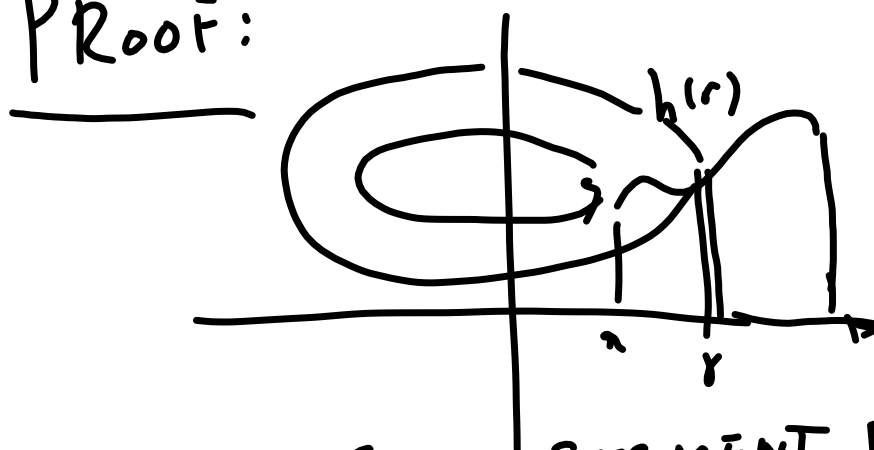
$$\int_Q x \mu(x, y) dx dy = \int_0^a \int_0^{\pi/2} r^3 \cos \theta \cdot r d\theta dr$$

$Q \begin{cases} \downarrow \\ r \cos \theta \end{cases}$

$$= 1 \cdot \int_0^a r^4 dr = \left. \frac{r^5}{5} \right|_0^a = \frac{a^5}{5}$$

$$\bar{x} = \frac{a^5/5}{\frac{\pi a^4}{4}} = \boxed{\frac{8a}{5\pi}}$$

PROOF:



VOLUME OF SMALL SEGMENT ROTATED

$$\text{IS } 2\pi r \cdot h(r) \Delta r.$$

VOLUME: $\int_a^b 2\pi r h(r) dr$

MEANWHILE: THE AVERAGE

X COORDINATE OF THE BODY

$$\bar{x} = \frac{\int_a^b r \cdot h(r) dr}{\int_a^b h(r) dr}$$

$$= \bar{r}$$

$$\int_a^b h(r) dr$$

AREA OF
REGION

VOLUME: $2\pi \bar{r} \cdot \text{AREA OF REGION.}$

$$\begin{aligned}\int_{D_\delta} \frac{1}{\sqrt{x^2+y^2}} dx &= \int_0^{2\pi} \int_\delta^2 \frac{1}{r} r dr d\theta \\ &= 2\pi \cdot \int_\delta^2 dr = 2\pi(2-\delta). \\ \lim_{\delta \downarrow 0} 2\pi(2-\delta) &= \boxed{2\pi}.\end{aligned}$$

EXAMPLE:

$$\int_0^{\infty} e^{-x} dx = \lim_{N \rightarrow \infty} \int_0^N e^{-x} dx$$
$$= \lim_{N \rightarrow \infty} (1 - e^{-N}) = 1.$$

NORMAL DISTRIBUTION:

$$\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} \quad \text{STANDARD NORMAL.}$$

$$\left(\int_{-\infty}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}} dx \right)^2$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-\frac{x^2+y^2}{2}} dx dy.$$

$$= \frac{1}{2\pi} \int_0^{2\pi} \int_0^{\infty} r e^{-\frac{r^2}{2}} dr d\theta.$$

$$= \int_0^{\infty} e^{-u} du = 1.$$

$u = r^2/2$
 $du = r dr.$

THE NORMAL OF MEAN μ ,

VARIANCE σ^2 IS

$$\frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

σ - STANDARD DEVIATION

μ - MEAN, CENTER, TRANSLATED DISTRIBUTION.