• Surface area of a graph z = f(x, y) over $R \subset \mathbb{R}^2$:

$$SA = \iint_R \sqrt{1 + [f_x(x, y)]^2 + [f_y(x, y)]^2} \, dA$$

• More generally, surface area of a parametric surface $(x, y, z) = \mathbf{r}(u, v)$ defined on *R*:

$$SA = \iint_{R} \|\mathbf{r}_{u} \times \mathbf{r}_{v}\| \, dA$$

 How is the first formula a special case of the second one?

Surface integrals (the first type)

- We can integrate over surfaces with respect to surface area. This is done simply by adding a function *f* to the previous integral formula.
- Formally, we can derive this definition as a limit of Riemann sums similarly to other integrals in the past. We'll skip these details in class.

Let *S* be a surface parametrized by $\mathbf{r}(u, v)$ on the region *D* and let f(x, y, z) be a continuous function on *S*. Then we define the integral of *f* over *S* by

$$\iint_{S} f(x, y, z) dS = \iint_{R} f(x(u, v), y(u, v), z(u, v)) ||\mathbf{r}_{u} \times \mathbf{r}_{v}|| dA.$$

• If the surface is a graph z = f(x, y), then the previous formula becomes

$$\iint_{S} f(x,y,z) \, dS = \iint_{R} f(x,y,z) \, \sqrt{1 + [f_x(x,y)]^2 + [f_y(x,y)]^2} \, dA.$$

 If *f* represents the density of the surface, then the surface integral can be interpreted as the total mass of the surface.

- The second type of surface integrals are called "flux integrals".
- The difference is that we integrate a <u>vector field</u>, instead of a scalar function. This is similar to the two types of line integrals.
- Physically, the flux integral measures the amount of flow of a fluid across a surface
- Mathematically, we integrate the dot product of the vector field with the <u>unit normal vector</u> at each point of surface

- There is a certain condition needed to define the flux integral:
- An <u>orientation</u> of a surface is a consistent (i.e., continuous) choice of unit normal vector at each point. (Recall that at each point there are *two* choices of unit normal vector.)
- You can think of an orientation as a consistent choice of "inside" and "outside".
- A surface is <u>orientable</u> if it has an orientation.
- The main mathematical significance of the "Möbius strip" is as an example of a non-orientable surface.

- The orientation of a parametric surface is inherited from the parametrization $\mathbf{r}(u, v)$
- The unit normal vectors belonging to the orientation are given by $\mathbf{N} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{\|\mathbf{r}_u \times \mathbf{r}_v\|}$
- Reversing the order of *u* and *v* reverses the orientation

Let $\mathbf{F}(x, y, z) = \langle M, N, P \rangle$ be a vector field with continuous first partial derivatives, and let *S* be a surface oriented by a unit normal vector **N**. The <u>flux</u> or flux integral of **F** across *S* is

$$\iint_{S} \mathbf{F} \cdot \mathbf{N} \, dS.$$