

Projection of \mathbf{u} onto \mathbf{v} : $\text{proj}_{\mathbf{v}} \mathbf{u} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \right) \mathbf{v}$

Identities: $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\| \|\mathbf{v}\| \cos(\theta)$ and $\|\mathbf{u} \times \mathbf{v}\| = \|\mathbf{u}\| \|\mathbf{v}\| \sin(\theta)$

Unit tangent vector: $\mathbf{T}(t) = \frac{\mathbf{r}'(t)}{\|\mathbf{r}'(t)\|}$, if $\mathbf{r}'(t) \neq \mathbf{0}$

Principal unit normal vector: $\mathbf{N}(t) = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$, if $\mathbf{T}'(t) \neq \mathbf{0}$

Tangential component of acceleration: $a_{\mathbf{T}} = \frac{d}{dt} \|\mathbf{r}'(t)\| = \frac{\mathbf{r}'(t) \cdot \mathbf{r}''(t)}{\|\mathbf{r}'(t)\|}$

Normal component of acceleration: $a_{\mathbf{N}} = \|\mathbf{r}'(t)\| \|\mathbf{T}'(t)\| = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|}$

Arc length: $s = \int_a^b \|\mathbf{r}'(t)\| dt$, Curvature: $K = \left\| \frac{d\mathbf{T}}{ds} \right\| = \frac{\|\mathbf{T}'(t)\|}{\|\mathbf{r}'(t)\|} = \frac{\|\mathbf{r}'(t) \times \mathbf{r}''(t)\|}{\|\mathbf{r}'(t)\|^3}$

Second derivative test: $d = \begin{vmatrix} f_{xx}(a, b) & f_{xy}(a, b) \\ f_{yx}(a, b) & f_{yy}(a, b) \end{vmatrix} = f_{xx}(a, b)f_{yy}(a, b) - (f_{xy}(a, b))^2$.

Cylindrical coordinates: $x = r \cos(\theta)$, $y = r \sin(\theta)$, $z = z$.

Spherical coordinates: $x = \rho \sin(\phi) \cos(\theta)$, $y = \rho \sin(\phi) \sin(\theta)$, $z = \rho \cos(\phi)$.

Integration in cylindrical coordinates example:

$$\iiint_R f(x, y, z) dV = \int_a^b \int_{f_1(\theta)}^{f_2(\theta)} \int_{g_1(r, \theta)}^{g_2(r, \theta)} f(r \cos(\theta), r \sin(\theta), z) r dz dr d\theta.$$

Integration in spherical coordinates example:

$$\iiint_R f(x, y, z) dV = \int_a^b \int_{f_1(\theta)}^{f_2(\theta)} \int_{g_1(\phi, \theta)}^{g_2(\phi, \theta)} f(\rho \sin(\phi) \cos(\theta), \rho \sin(\phi) \sin(\theta), \rho \cos(\phi)) \rho^2 \sin(\phi) d\rho d\phi d\theta.$$

Jacobian for the change of variables $x = g(u, v)$, $y = h(u, v)$: $\left| \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial x}{\partial v} \frac{\partial y}{\partial u} \right|$

Line integral of the vector field $\mathbf{F} = \langle M, N, P \rangle$ over C :

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C M dx + N dy + P dz = \int_C \mathbf{F} \cdot \mathbf{T} ds = \int_a^b \mathbf{F}(x(t), y(t), z(t)) \cdot \mathbf{r}'(t) dt$$

Surface integral of $f(x, y, z)$ over S : $\iint_S f(x, y, z) dS = \iint_R f(x(u, v), y(u, v), z(u, v)) \|\mathbf{r}_u \times \mathbf{r}_v\| dA$.

Flux of \mathbf{F} across S : $\iint_S \mathbf{F} \cdot \mathbf{N} dS = \iint_D \mathbf{F} \cdot (\mathbf{r}_u \times \mathbf{r}_v) dA$.

$$\text{curl } \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix}, \quad \text{div } \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}$$

Divergence theorem: $\iint_S \mathbf{F} \cdot \mathbf{N} dS = \iiint_Q \text{div } \mathbf{F} dV$.

Stokes's theorem: $\int_C \mathbf{F} \cdot d\mathbf{r} = \iint_S (\text{curl } \mathbf{F}) \cdot \mathbf{N} dS$.