(1) Find the projection of the vector
$$\vec{u} = \begin{bmatrix} 1\\2 \end{bmatrix}$$
 onto the vector $\vec{v} = \begin{bmatrix} -1\\3 \end{bmatrix}$.

$$Proj_{\vec{v}}(\vec{u}) = \frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \cdot \vec{v} = \frac{-1+6}{1+4} \cdot \binom{r_3}{2} = \binom{r_1}{3}$$

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(2) Find a single equation for the plane \mathcal{P} in \mathbb{R}^3 which passes through the $P = \begin{bmatrix} 1\\2\\0 \end{bmatrix}$ and has normal

vector $\vec{n} = \begin{bmatrix} -1\\ 3\\ 1 \end{bmatrix}$. The equation of a plane normal to \vec{n} has the form $\vec{n} \left(\frac{y}{2} \right) = c$ where c is a scalar. Since P is in the plane then $c = n \cdot P = \begin{pmatrix} -1 \\ 3 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 0 \end{pmatrix} = -1 + 6 = 5$ Then the equation is -x+3y+2=5 is an equation for the plane P.

(3) and (9) solved in class

(5) Find the vector form of the line in \mathbb{R}^2 passing through $P = \begin{vmatrix} 2 \\ 2 \end{vmatrix}$ and perpendicular to the line with general equation 3x - 2y = 33.

A line puperdicula to the line of equation 3x - 2y = 33 has direction vector $\binom{3}{-2}$ (which is the normal vector to the given line)

Thus, the required equation can be written as $\binom{2}{2} + \frac{1}{2} \cdot \binom{3}{-2}$ where the R

6) done in clos

(7) Determine which of the equations below are linear. If any equation is not linear, explain why.

- (a) $x + y + \sin z = 3$. Not linear because of the term sind
- (b) $x+y^2=0.$ Not linear because of the term of
- (c) 2x + 2y = 2. Linea.
- (d) x.y = 2. Not line because of the term x.y

(8) Determine geometrically whether each of the systems has a unique solution, infinitely many solutions, or no solutions. Then solve the systems algebraically to confirm your answer.

(a) x + y = 1 x - 2y = 1 } These equations can be interpreted as the linear. Since the corresponding normal vectors are x - 2y = 1 } (1) and (1/2) are linearly independent, the linear intersect at a unique point. Thus, the system has a unique solution.
(b) x + y = 1 2x + 2y = 2 } Since the sirst equation multiplied by 2 gives the second, the two equation represent the source set of points. Thus set of points is the solution of the system. Thus the system (c) x + y = 1 2x + 2y = -2 } has inginitely many solutions.
(c) x + y = 1 2x + 2y = -2 } Since two porcelled lines ((1) is a normal vector to both directions)
These are two porcelled lines because the Sicsl equation is equivalent to 2x + 2y = 2. Thus, the lines are displicit and the system has no solutions.

(9) in dass

(10) Solve the given system of equations.

$$\begin{aligned} x + y + 2z &= 0 \\ x + z &= -1 \\ 4x - 2y + z &= 2 \\ \begin{pmatrix} 4 & 4 & 2 & | & 0 \\ \lambda & 0 & 4 & | & -1 \\ 4 & -2 & 4 & | & 2 \\ \end{pmatrix} \xrightarrow{R_1 \cdot R_2 \cdot R_1} \xrightarrow{R_1 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 4 & 2 & | & 0 \\ 0 & -1 & -1 & | & -1 \\ 4 & -2 & 4 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_1} \xrightarrow{R_1 \cdot R_1 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -1 & -1 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & -6 & -7 & | & 2 \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 4 & | & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & -1 \\ 0 & 0 & -1 & R \\ \end{pmatrix} \xrightarrow{R_2 \cdot R_2} \begin{pmatrix} A & 0 & -1 \\ 0 & 0 & -1 & R$$

(11) Determine by inspection (that is, without performing any calculations) whether a linear system with each of the given augmented matrices has a unique solution, no solution or infinitely many solutions. Justify your answer.

(a)
$$\begin{pmatrix} 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & 2 \end{pmatrix}$$
 The ted. now each lon form has 2 leading variables
and a gree on. Thus, the system has infinitely many sol'h.
(b) $\begin{pmatrix} 0 & 0 & 1 & | & 1 \\ 0 & 1 & 0 & | & -2 \\ 1 & 0 & 0 & | & 2 \end{pmatrix}$ By applying elementary now operation (swapping now)
two obtain a risk. now echelon form with a unique
solution
(c) $\begin{pmatrix} 0 & 1 & 0 & | & 1 \\ 0 & 0 & 1 & | & -2 \\ 0 & 0 & 0 & | & 2 \end{pmatrix}$ The last now of the matrix can be translated
to $0 = 2$. Thus the system has no sol'h.

(15) Given $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ find all matrices B such that AB = BA, (16) Given the matrix $a = \begin{pmatrix} 1 & 1 \\ 2 & -4 \end{pmatrix}$. (a) Find A^{-1} .

(b) Use A^{-1} found in (a). to solve the system $A\begin{bmatrix} x\\ y\end{bmatrix} = \begin{bmatrix} 2\\ 3\end{bmatrix}$

(12) (a) Show that $\mathbb{R}^3 = \operatorname{span}(\vec{u}, \vec{v}, \vec{w})$, where $\vec{u} = \begin{bmatrix} -1 \\ -2 \\ 1 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 0 \\ 2 \\ -1 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} -2 \\ 3 \\ -1 \end{bmatrix}$.

(b) Write
$$z = \begin{bmatrix} -1\\ 3\\ 1 \end{bmatrix}$$
 as a linear combination of \vec{u}, \vec{v} and \vec{u} .

$$\begin{pmatrix} -1 & 0 & -2 & \times \\ -2 & 2 & 3 & 0 \\ 1 & -1 & -1 & 2 \end{pmatrix} \xrightarrow{R_{2} \to R_{2} - 2R_{1}} \begin{pmatrix} -4 & 0 & -2 & \times \\ 0 & 2 & 7 & -2x + 0 \\ 1 & -1 & -1 & 2 \end{pmatrix}$$

$$\stackrel{R_{3}}{\longrightarrow} \begin{pmatrix} -1 & 0 & 2 & \times \\ 0 & 2 & 7 & -2x + 0 \\ 0 & -1 & -3 & x + 2 \end{pmatrix} \xrightarrow{R_{1} \to R_{1}} \begin{pmatrix} A & 0 & 2 & -x \\ 0 & 2 & 7 & -2x + 0 \\ 0 & -1 & -3 & x + 2 \end{pmatrix} \xrightarrow{R_{3} \to R_{4} + R_{1}} \begin{pmatrix} A & 0 & 2 & -x \\ 0 & 2 & 7 & -2x + 0 \\ 0 & -1 & -3 & x + 2 \end{pmatrix} \xrightarrow{R_{3} \to R_{4} + R_{2}} \begin{pmatrix} 1 & 0 & 2 & -x \\ 0 & 1 & 72 & -x + 9/2 \\ 0 & -1 & -3 & x + 2 \end{pmatrix} \xrightarrow{R_{3} \to R_{4} + R_{2}} \begin{pmatrix} 1 & 0 & 2 & -x \\ 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ 0 & 0 & 1 & 72 & -x + 9/2 \\ R_{1} = R_{1} - \frac{2R_{3}}{2} \begin{pmatrix} A & 0 & 0 & -x & -2g^{-4}R_{1} \\ 0 & 1 & 72 & -x + \frac{9}{2} \\ 0 & 0 & 1 & 9 + 22 \end{pmatrix} \xrightarrow{R_{1} = R_{1} - 2R_{3} / 1} \xrightarrow{R_{1} = R_{1} - 2R_{3} / 1} \xrightarrow{R_{2} - 2R_{3} / 1} \xrightarrow{R_{2} - 2R_{3} / 1} \xrightarrow{R_{1} = R_{1} - 2R_{3} / 1} \xrightarrow{R_{2} / 1} \xrightarrow{R_{2} - 2R_{3}$$

(14) Determine whether the vectors $\vec{u} = \begin{bmatrix} -1\\1\\1 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 0\\2\\-1 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} 0\\3\\3 \end{bmatrix}$ are linearly independent.

If then exists
$$x, y, z$$
 such that
 $x.\overline{u} + y\overline{v} + z\overline{w} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$
then $-1x + 0y + 0\overline{z} = 0$

Thus
$$x = 0$$
.
1 2 y + 3 z = 0 Then y=0
- y + 3 z = 0 and z=0.
Thus the vector are linearly independent since the only
way of obtaining (°) as a linear combination is with all
the coefficients equal to 0.

(15) Given $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ find all matrices B such that AB = BA, Set B = (ab) Is AB=BA then c=0 and a=d Thus B = (ab)