

## COMPLEX STRUCTURES ON RULED SURFACES

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We study the twistor space  $Z$  of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$ . If the scalar curvature of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  is zero, then it is known that  $Z$  is a complex manifold, so every almost complex structure of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$ , compatible with the metric is integrable. Our main result is that the set of all integrable structures of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  is a real quadric, which we describe explicitly. As a corollary we get the same result for ruled surfaces of genus  $g \geq 2$  and of an even degree.

**1. Preliminaries.** Here we introduce the twistor space of an oriented even dimensional Riemannian manifold  $M$ , following the notations of [2], [3] and [5].

Let  $(M, g)$  be an oriented connected Riemannian manifold of real dimension  $2n$ . Let  $P$  be the  $SO(2n)$ -principle bundle of oriented  $g$ -orthonormal frames on  $M$ . Denote by  $\pi : P \rightarrow M$  the canonical projection. Then  $SO(2n)$  acts on the right on  $P$ .

Consider local coordinates  $\{x_1, \dots, x_{2n}\}$  in a neighborhood  $U$  of  $x \in M$ , and let  $\{\theta_1, \dots, \theta_{2n}\}$  be a local oriented  $g$ -orthonormal frame.

The fibre  $\pi^{-1}(x)$  is diffeomorphic to  $SO(2n)$ . Let us denote by  $i : \pi^{-1}(x) \rightarrow P$  the fibre's inclusion, then

$$\tilde{V}_a = i_{*|a}(T_a\pi^{-1}(x))$$

is called the vertical tangent space at the point  $a$ .

Let  $\{\theta_1^*, \dots, \theta_{2n}^*\}$  be the local coframe dual to  $\{\theta_1, \dots, \theta_{2n}\}$ , then the covariant derivative  $\nabla$  on  $M$  defined by the Levi-Civita connection of  $g$  is locally expressed by:  $\nabla\theta_j = \Gamma_{ij}^k\theta_i^* \otimes \theta_k$ , and the Christoffel's symbols satisfy  $\Gamma_{ij}^k = -\Gamma_{ik}^j$ , so the matrix  $(\Gamma_i^{\cdot}) \in so(2n)$ . Hence (according to [4]), the Riemannian connection on  $P$  at the point  $a = (x; \tilde{X}) = (x; (X_j^i))$ , induced by  $g$ , can be expressed by:

$$(1) \quad \omega_j^i(x; \tilde{X}) = \frac{1}{2}(X_i^r dX_j^r - X_j^r dX_i^r) + X_i^r \Gamma_{ml}^r(x) X_j^l \theta_m^*(x)$$

The connection  $\omega = (\omega_j^i)$  on  $P$  induces a splitting of the tangent bundle in horizontal and vertical subbundles, at the point  $a$ :

$$T_a P = \tilde{H}_a \oplus \tilde{V}_a,$$

where

$$\tilde{H}_a := \{Y \in T_a P \mid \omega(Y) = 0\}$$

is the horizontal tangent space at the point  $a$ .

$SO(2n)$  acts transitively on  $\frac{SO(2n)}{U(n)}$ . Then we have an action of  $SO(2n)$  on  $P \times \frac{SO(2n)}{U(n)}$ , defined by:

$$(2) \quad \begin{aligned} SO(2n) \times P \times \frac{SO(2n)}{U(n)} &\rightarrow P \times \frac{SO(2n)}{U(n)}, \\ (A, a, XU(n)) &\rightarrow (aA, A^{-1}XU(n)). \end{aligned}$$

**Definition 1.** *The twistor space of  $(M, g)$  is the associated bundle to  $P$  defined as the quotient of  $P \times \frac{SO(2n)}{U(n)}$  with respect to the action (2). It will be denoted by  $Z(M, g)$ , or simply by  $Z$ , when the manifold  $(M, g)$  is understood.*

$Z$  is a bundle over  $M$  with fibre  $\frac{SO(2n)}{U(n)}$  and structure group  $SO(2n)$ . Denote by  $\Pi : P \rightarrow Z$  and by  $r : Z \rightarrow M$  the bundle projections, and by  $Z_x := r^{-1}(x)$  the fibre of  $Z$  at the point  $x \in M$ . The geometric meaning of  $Z$  is clear from the following:

**Theorem 1.1.**  *$Z_x$  parametrizes the complex structures on  $T_x M$  compatible with the metric  $g$  and the orientation.*

The splitting  $T_a P = \tilde{H}_a \oplus \tilde{V}_a$ , via  $\Pi$  induces a corresponding splitting of  $T_p Z$  for  $p \in Z$ . Let  $a \in \Pi^{-1}(p)$ . Then

$$T_p Z = (\Pi)_*|_a(\tilde{H}_a) \oplus (\Pi)_*|_a(\tilde{V}_a) := H_p \oplus V_p.$$

We have immediately that  $r_{*|p}(H_p) = T_{r(p)}M$ . Then for every  $p \in Z$  and for every tangent vector  $X \in T_p Z$ , we have a decomposition of  $X$  in horizontal and vertical component:

$$X = X_h + X_v, X_h \in H_p, X_v \in V_p.$$

Let us define an almost complex structure  $J$  on  $Z$ : for  $X = X_h + X_v \in T_p Z$ , we set:

$$J(X) = r_{*|r(p)}^{-1} \circ p \circ r_{*|p}(X_h) + J_V(X_v),$$

where  $p$  acts on  $T_{r(p)}M$  according to Theorem 1.1, and  $J_V$  is the almost complex structure of the symmetric space  $Z_{r(p)} \cong \frac{SO(2n)}{U(n)}$ .

**2. Main results.** We explore the complex inclusions of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  in its twistor space and in consequence we get the explicit record of its complex structures.

We use the notations of the previous section. Let  $\mathbf{D}$  be the one-dimensional disc equipped with Poincare metric with scalar curvature  $-1 - \varepsilon$ , ( $\varepsilon > -1$ ), and  $\mathbb{C}\mathbb{P}^1$  denotes the projective 1-dimensional space with Fubini-Study metric with scalar curvature  $+1$ . We denote the real local coordinates on  $\mathbf{D}$  and  $\mathbb{C}\mathbb{P}^1$  with  $x_1, y_1$  and  $x_2, y_2$ , respectively. According to [8] their metrics are:

$$g_{\mathbf{D}} = \frac{dx_1 \otimes dx_1 + dy_1 \otimes dy_1}{1 - \frac{1+\varepsilon}{4}(x_1^2 + y_1^2)}, \quad g_{\mathbb{C}\mathbb{P}^1} = \frac{dx_2 \otimes dx_2 + dy_2 \otimes dy_2}{1 + \frac{1}{4}(x_2^2 + y_2^2)}.$$

We set:

$$A := \frac{1}{1 - \frac{1+\varepsilon}{4}(x_1^2 + y_1^2)}, \quad B := \frac{1}{1 + \frac{1}{4}(x_2^2 + y_2^2)}.$$

We choose  $x = (x_1, y_1, x_2, y_2) \in \mathbf{D} \times \mathbb{C}\mathbb{P}^1$ . An orthonormal frame for  $T_x(\mathbf{D} \times \mathbb{C}\mathbb{P}^1)$  is

$$\left\{ \theta_1 = \frac{1}{A} \frac{\partial}{\partial x_1}, \theta_2 = \frac{1}{A} \frac{\partial}{\partial y_1}, \theta_3 = \frac{1}{B} \frac{\partial}{\partial x_2}, \theta_4 = \frac{1}{B} \frac{\partial}{\partial y_2} \right\}$$

and an orthonormal frame for  $T_x^*(\mathbf{D} \times \mathbb{C}\mathbb{P}^1)$  is

$$\{\theta_1^* = A dx_1, \theta_2^* = A dy_1, \theta_3^* = B dx_2, \theta_4^* = B dy_2\}.$$

From the condition  $\nabla \theta_j = \Gamma_{ij}^k \theta_i^* \otimes \theta_k$  for the metric of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$ , we compute its Christoffel's symbols and therefore we get the following:

**Lemma 2.1.** *The curvature components of the metric of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  defined above are:*

$$R_{212}^1 = \varepsilon A^2, \quad R_{434}^3 = \varepsilon B^2,$$

$$R_{313}^1 = R_{414}^1 = R_{323}^2 = R_{424}^2 = \varepsilon AB,$$

$R_{jkl}^i = 0$ , else, where  $i < j, k < l$ .

In order to parametrize the fibre in more convenient way, we use the following:

**Lemma 2.2.**

$$\frac{SO(4)}{U(2)} \cong \mathbb{C}\mathbb{P}^1.$$

**Proof.** Let  $\mathbb{H} \cong \mathbb{R}^4$  be the space of quaternions with a basis  $\{\mathbf{1}, \mathbf{i}, \mathbf{j}, \mathbf{k}\}$  over  $\mathbb{R}$  with the relations:

$$\mathbf{i}^2 = \mathbf{j}^2 = \mathbf{k}^2 = -\mathbf{1}, \quad \mathbf{ij} = \mathbf{k} = -\mathbf{ji}, \quad \mathbf{jk} = \mathbf{i} = -\mathbf{kj}, \quad \mathbf{ki} = \mathbf{j} = -\mathbf{ik}.$$

The standart complex structure  $J_2$  of  $\mathbb{R}^4$  is identified with the left multiplication with  $\mathbf{i}$ . Let  $S^3$  be the unit sphere in  $\mathbb{R}^4$ , i.e. the space of unit quaternions. Let  $q \in S^3$ ,  $q = a + \mathbf{i}b + \mathbf{j}c + \mathbf{k}d = z_1 + z_2\mathbf{j}$ , where  $z_1 = a + \mathbf{i}b$ ,  $z_2 = c + \mathbf{i}d$ . We define the following maps:

$$c_1 : \mathbb{C}\mathbb{P}^1 \rightarrow S^3, \quad [z_1 : z_2] \mapsto q; \quad c_2 : S^3 \rightarrow \mathbb{C}\mathbb{P}^1, \quad q \mapsto [z_1 : z_2].$$

For every  $q \in S^3$  we define a matrix  $A_q \in SO(4)$ , which corresponds to a left multiplication with the conjugate of  $q$ , in other words,  $A_q x = \bar{q} \cdot x$ , where  $x \in \mathbb{H} = \mathbb{R}^4$  and “ $\cdot$ ” is the quaternionic multiplication. Reversly, for every matrix  $A \in SO(4)$ , we define a unit quaternion  $q$  with the same equation. We obtain the following maps:

$$s_1 : S^3 \rightarrow SO(4), \quad q \mapsto A_q; \quad s_2 : SO(4) \rightarrow S^3, \quad A_q \mapsto q.$$

Note that for  $q_1, q_2 \in S^3$ ,  $A_{q_1} = A_{q_2}$  if and only if  $\bar{q}_1^{-1} \bar{q}_2 \in U(2)$

Now we can define the maps:

$$p_1 : \mathbb{C}\mathbb{P}^1 \rightarrow \frac{SO(4)}{U(2)}, \quad [z_1 : z_2] \mapsto A_q U(2), \quad p_1 = pr \circ s_1 \circ c_1$$

and

$$p_2 : \frac{SO(4)}{U(2)} \rightarrow \mathbb{C}\mathbb{P}^1, \quad A_q U(2) \mapsto [z_1 : z_2], \quad p_2 = c_2 \circ s_2 \circ i,$$

where  $pr : SO(4) \rightarrow \frac{SO(4)}{U(2)}$  and  $i : \frac{SO(4)}{U(2)} \rightarrow SO(4)$ .

It is easily seen that the maps  $p_1$  and  $p_2$  are correctly defined and they are isomorphisms between  $\mathbb{C}\mathbb{P}^1$  and  $\frac{SO(4)}{U(2)}$ .  $\square$

**Remark 1.** We associate to  $A_q$  the almost complex structure  $J_q = A_q^{-1}J_2A_q$ , coming from Theorem 1.1. After some computations we get:

$$J_q = \begin{pmatrix} 0 & -S & 2(ad+bc) & 2(bd-ac) \\ S & 0 & 2(bd-ac) & -2(ad+bc) \\ -2(ad+bc) & 2(ac-bd) & 0 & -S \\ 2(ac-bd) & 2(ad+bc) & S & 0 \end{pmatrix},$$

where  $S = a^2 + b^2 - c^2 - d^2$ .

In order to compute a local frame for  $\tilde{H}_a$ ,  $a \in \pi^{-1}(U)$ , it suffices to compute horizontal lifts  $\tilde{\theta}_j$  of  $\theta_j$  for  $1 \leq j \leq 4$ . In the notations of the previous paragraph,  $\tilde{\theta}_j$  is uniquely determined by:  $\pi_{*|a}(\tilde{\theta}_j) = \theta_j(\pi(a))$  and  $\omega(a)(\tilde{\theta}_j) = 0$  for all  $a \in \pi^{-1}(U)$ , where  $\omega$  is defined by (1). The local frames  $\hat{\theta}_j$ ,  $1 \leq j \leq 4$ , for  $H_p$ ,  $p \in Z$  are the projections of  $\tilde{\theta}_j$ :

$$\hat{\theta}_j = \Pi_{*|a}(\tilde{\theta}_j).$$

We consider local coordinates  $\{u_1, u_2\}$  on the fibre  $\mathbb{C}\mathbb{P}^1$ , where  $u := \frac{z_2}{z_1}$ ,  $u = u_1 + \mathbf{i}u_2$ . So the local coordinates on the twistor space  $Z$  are  $\{x_1, y_1, x_2, y_2, u_1, u_2\}$ . If we choose local coordinates  $\{v_1, v_2\}$  on the fibre  $\mathbb{C}\mathbb{P}^1$ , where  $v := \frac{z_1}{z_2}$ ,  $v = v_1 + \mathbf{i}v_2$ , then the computations will be analogous. Let  $p = (x_1, y_1, x_2, y_2, u_1, u_2) \in Z$ . According to Remark 1, we can compute  $J$  in the chosen local coordinates, as well as  $J\hat{\theta}_j$ ,  $1 \leq j \leq 4$ .

Now we can compute explicitly all terms of the Nijenhuis tensor

$$N(J)(p)(X, Y) = [JX, JY] - J[X, JY] - J[JX, Y] - [X, Y].$$

For convenience we will write  $N(X, Y)$  instead of  $N(J)(p)(X, Y)$ .

**Lemma 2.3.**

$$\begin{aligned} N(\hat{\theta}_1, \hat{\theta}_2) = N(\hat{\theta}_3, \hat{\theta}_4) &= \frac{8\varepsilon(u_2 \frac{\partial}{\partial u_1} - u_1 \frac{\partial}{\partial u_2})((A^2 + B^2)(u_1^2 + u_2^2) - 2AB)}{(1 + u_1^2 + u_2^2)^2}, \\ N(\hat{\theta}_1, \hat{\theta}_3) = -N(\hat{\theta}_2, \hat{\theta}_4) &= -\frac{4\varepsilon(1 + u_1^2 - u_2^2)((A^2 + B^2)(u_1^2 + u_2^2) - 2AB)}{(1 + u_1^2 + u_2^2)^2} \frac{\partial}{\partial u_1} \\ &\quad - \frac{8\varepsilon u_1 u_2 ((A^2 + B^2)(u_1^2 + u_2^2) - 2AB)}{(1 + u_1^2 + u_2^2)^2} \frac{\partial}{\partial u_2}, \\ N(\hat{\theta}_1, \hat{\theta}_4) = N(\hat{\theta}_2, \hat{\theta}_3) &= -\frac{8\varepsilon u_1 u_2 ((A^2 + B^2)(u_1^2 + u_2^2) - 2AB)}{(1 + u_1^2 + u_2^2)^2} \frac{\partial}{\partial u_1} \\ &\quad - \frac{4\varepsilon(1 - u_1^2 + u_2^2)((A^2 + B^2)(u_1^2 + u_2^2) - 2AB)}{(1 + u_1^2 + u_2^2)^2} \frac{\partial}{\partial u_2}. \end{aligned}$$

According to the Newlander-Nirenberg Theorem, an almost complex structure is integrable if and only if its Nijenhuis tensor vanishes. We apply it for the horizontal subbundle of  $Z$  and get the following result:

**Theorem 2.1.** *If  $\varepsilon = 0$ , then  $Z$  is a complex manifold, else  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  embeds in  $Z$*

as a complex submanifold with the help of the section

$$\phi : \mathbf{D} \times \mathbb{C}\mathbb{P}^1 \rightarrow Z,$$

$$(x_1, y_1, x_2, y_2) \mapsto (x_1, y_1, x_2, y_2, u_1, u_2)$$

if and only if

$$u_1^2 + u_2^2 = \frac{2AB}{A^2 + B^2},$$

where  $A$  and  $B$  are defined above.

**Corollary 2.1.1.** *If  $\varepsilon = 0$ , then all almost complex structures of  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$ , compatible with the metric, are integrable, else the set of integrable complex structures is a quadric.*

**Remark 2.** In the case  $\varepsilon \neq 0$ , all integrable almost complex structures, compatible with the metric are in the equivalent class with representative of the form:

$$J = \begin{pmatrix} J_H & 0 \\ 0 & J_V \end{pmatrix}, \text{ where } J_V = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix},$$

$$J_H = \frac{1}{1 + u_1^2 + u_2^2} \begin{pmatrix} 0 & 1 - u_1^2 - u_2^2 & 2u_2 & -2u_1 \\ u_1^2 + u_2^2 - 1 & 0 & -2u_1 & 2u_2 \\ -2u_2 & 2u_1 & 0 & 1 - u_1^2 - u_2^2 \\ 2u_1 & 2u_2 & u_1^2 + u_2^2 - 1 & 0 \end{pmatrix},$$

and moreover  $u_1^2 + u_2^2 = \frac{2AB}{A^2 + B^2}$ .

**Remark 3.** It is interesting that the above properties we got do not depend on the exact value of  $\varepsilon$ , but only on the condition if it is equal or not to zero.

**Remark 4.** Although the submanifolds  $\phi(\mathbf{D} \times \mathbb{C}\mathbb{P}^1)$  of  $Z$  are the same as smooth manifolds for different values of  $\varepsilon$ , their induced metrics are different.

**Remark 5.** Since  $\mathbf{D}^1$  is the universal cover of Riemannian surfaces of genus  $g \geq 2$ , then Theorem 2.1 is true for every ruled surface of genus  $g \geq 2$  and of an even degree (see [6]).

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## КОМПЛЕКСНИ СТРУКТУРИ ВЪРХУ ЛИНИРАНИ ПОВЪРХНИНИ

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Изучаваме твисторното пространство  $Z$  на  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$ . Ако скаларната кривина на  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  се анулира, добре известно е, че  $Z$  е комплексно многообразие, откъдето всяка почти комплексна структура на  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$ , съвместима с метриката е интегрируема. Основният ни резултат е, че множеството от всички интегрируеми структури на  $\mathbf{D} \times \mathbb{C}\mathbb{P}^1$  е реална квадрака, която описваме в явен вид. Като следствие получаваме същият резултат за линирани повърхнини от род  $g \geq 2$  и от четна степен.