

Recall: • Orientation on $M = k$ -manifold in \mathbb{R}^n is collection of positively overlapping coord charts.

• M manifold w/ ∂

↳ restricted orientation on ∂M by restricting coord charts:



The restricted orientation on ∂M is in fact not always what we prefer.

Def: Let M be a k -manifold in \mathbb{R}^n w/ $\partial M \neq \emptyset$. Given an orientation on M , the induced orientation on ∂M is defined as follows:

- If k is even it's the restricted orientation
 - If k is odd it's the opposite of the restricted orientation
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Ex Consider $B^3 \subset \mathbb{R}^3$
(the closed unit ball). Its boundary is $S^2 \subset \mathbb{R}^3$.

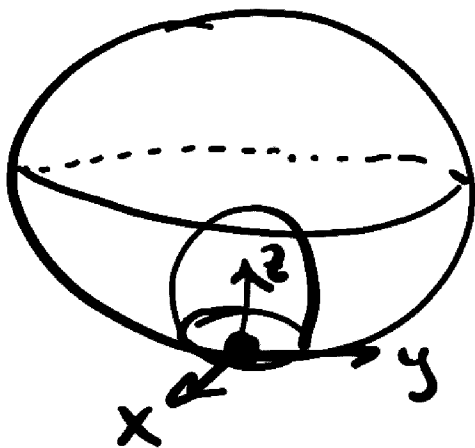
It turns out that the induced orientation on S^2 is the one corresponding to the outwards pointing normal vector field on S^2 .

$\alpha: U \rightarrow V$ Coord chart around $x \in \partial M$. $U \subset \mathbb{H}^3$. The restricted coord chart is given by

$$\alpha_2(x, y) = \alpha(x, y, 0)$$

Since $\dim M = 3$, the induced ori is the one opposite to the restricted one. The normal ν_f $P \mapsto (P, \vec{n})$ on ∂M that corresp to the induced ori is the one so that

$(-\vec{n}, \frac{\partial \alpha}{\partial x}, \frac{\partial \alpha}{\partial y})$ is a right-handed frame.



the restricted frame

$$\left(\frac{\partial \alpha}{\partial x}, \frac{\partial \alpha}{\partial y}, \frac{\partial \alpha}{\partial z} \right)$$

is right-handed

$\Rightarrow \left(\frac{\partial \alpha}{\partial z}, \frac{\partial \alpha}{\partial x}, \frac{\partial \alpha}{\partial y} \right)$ is
right-handed
and $\frac{\partial \alpha}{\partial z}$ is inwardly normal

In general, one can describe
the induced orientation on ∂M
to be the one determined by

(outwards, restricted
normal, frame) should
be
right-handed.

Def: M compact, oriented k -manifold in \mathbb{R}^n
 $M \subset A \subset \mathbb{R}^n$, $\omega \in \Omega^k(A)$

$C := M \cap (\text{supp } \omega) \leftarrow \begin{array}{|l} \text{this} \\ \text{is} \\ \text{compact} \end{array}$

Suppose \exists coord chart $\alpha: U \rightarrow V$ belonging to the given ori on M such that $C \subset V$. Define

$$\int_{M, \alpha} \omega := \int_{\text{int } U} \alpha^* \omega$$

$$\text{int } U = \begin{cases} U & \text{if } U \overset{\text{open}}{\subset} \mathbb{R}^k \\ U \cap \mathbb{H}_+^k & \text{if } U \overset{\text{open}}{\subset} \mathbb{H}^k \end{cases} .$$

Remark: $\int_{M, \alpha} \omega$ is independent of coord chart, as long as its chosen from the given orientation on M !

Recall

$$\int_{M, \alpha} \omega = \varepsilon \int_{M, \beta} \omega$$

from 2 lectures ago; the sign $\varepsilon = \det D(\text{transition fun})$ is $+1$

if α, β both belong to the same ori on M , by definition.

Motivated by this we write $\int_M \omega$ instead of $\int_{M, \alpha} \omega$.

In general we now use a partition of unity:

Def M compact, oriented k -manifold in \mathbb{R}^n . Choose partition of unity $\{\phi_i\}_{i=1}^N$ wrt the cover of M determined by coord charts in the given orientation on M .

Def

$$\int_M \omega = \sum_{i=1}^N \int_M \phi_i \omega$$

Rank

- ① This agrees with the previous definition when the support of ω is covered by a single coord chart.
- ② The definition is independent of choice of partition of unity. The proof is the same as previously seen for $\int_M f dV$
-

Thm, M cpt oriented k -mfcd
in \mathbb{R}^n .

$\omega, \eta \in \Omega^k(A)$, $M \subset A \subset \mathbb{R}^n$ ^{open}

then

$$\textcircled{1} \int_M a\omega + b\eta = a \int_M \omega + b \int_M \eta$$

② If $-M$ denotes M with the opposite orientation, then

$$\int_{-M} \omega = - \int_M \omega.$$

Proof: ② $\alpha: U \rightarrow V$ and the opposite coord chart

$$\alpha \circ \sigma: U \rightarrow V$$

$$r: \mathbb{R}^k \longrightarrow \mathbb{R}^k$$

$$(x_1, \dots, x_k) \mapsto (-x_1, x_2, \dots, x_k)$$

overlap negatively, so

$$\int_{M, \alpha} \omega = - \int_{M, \alpha \circ \sigma} \omega.$$

If α belongs to one ori of M $\alpha \circ \sigma$ always belongs to the other.

$$\int_M \omega = \sum_{i=1}^N \int_{M \alpha_i} \phi_i \omega = \sum_{i=1}^N - \int_{M \alpha_{i+1}} \phi_i \omega$$

$$= - \int_{-M} \omega$$

□

Stokes' theorem

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$I^k := [0,1]^k \subset \mathbb{R}^k$ unit k -cube

$\text{int } I^k = (0,1)^k \subset \mathbb{R}^k$

$\partial I^k = I^k \setminus \text{int } I^k$.

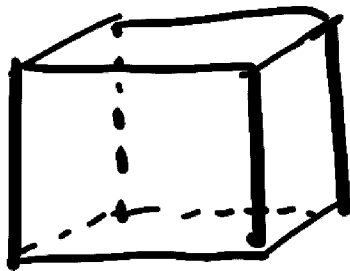
Lma: Let $k > 1$. $I^k \subset U \subset \mathbb{R}^k$ ^{open}

$\eta \in \Omega^{k-1}(U)$ and assume

$\eta(\vec{x}) = 0$ at all $\vec{x} \in \partial I^k$ except possibly at points of

$(\text{int } I^{k-1}) \times \{0\}$

← interior of one particular boundary face



Then

$$\int_{\text{int } I^k} d\eta = (-1)^k \int_{\text{int } I^{k-1}} b^* \eta$$

Where

$$b: I^{k-1} \rightarrow I^k$$

$$(x_1, \dots, x_{k-1}) \mapsto (x_1, \dots, x_{k-1}, 0)$$

Proof: $\vec{x} \in \mathbb{R}^k$, $\bar{u} \in \mathbb{R}^{k-1}$

$$j \in \{1, \dots, k\}$$

$$I_j := (1, \dots, \hat{j}, \dots, k) = (1, \dots, j-1, i, \dots, k)$$

Basis for $A^{k-1}(T_{\vec{x}} \mathbb{R}^k)$ is given by

$$\{dx_{I_j} = dx_1 \wedge \dots \wedge \widehat{dx_j} \wedge \dots \wedge dx_k\}_{j=1}^k$$

We prove it for $\eta = f dx_{I_j}$
for some $j \in \{1, \dots, k\}$.

Step 1: Let's compute $\int_{\text{int } I^k} d\eta$.

$$\begin{aligned} d\eta &= df \wedge dx_{I_j} \\ &= \sum_{i=1}^k \frac{\partial f}{\partial x_i} dx_i \wedge dx_{I_j} \\ &= \frac{\partial f}{\partial x_j} dx_j \wedge dx_{I_j} \\ &= (-1)^{j-1} \frac{\partial f}{\partial x_j} dx_1 \wedge \dots \wedge dx_k. \end{aligned}$$

$$\int_{\text{int } I^k} d\eta = \int_{\text{int } I^k} (-1)^{j-1} \frac{\partial f}{\partial x_j} = (-1)^{j-1} \int_{I^k} \frac{\partial f}{\partial x_j}$$

$$= (-1)^{j-1} \int_{I^{k-1}} \int_{x_j \in I} \frac{\partial f}{\partial x_j}(x_1, \dots, x_k)$$

Fubini

$$= (-1)^{j-1} \int_{I^{k-1}} \left[f(x_1, \dots, \overset{\text{Position } j}{1}, \dots, x_k) - f(x_1, \dots, \underset{\text{Position } j}{0}, \dots, x_k) \right] (t)$$

Fund. thm of calculus

This $I^{k-1} \ni (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_k)$

Recall assumption that

$$\eta(\vec{x}) = \int_{I_j} f(\vec{x}) dx_{I_j} = 0$$

unless $\vec{x} \in (\text{int } I^{k-1}) \times \{0\}$.

It follows that

$$(t) = 0 \text{ if } j < k.$$

If $j = k$

$$(t) = (-1)^{k-1} \int_{I^{k-1}} -f(x_1, \dots, x_{k-1}, 0)$$

CLAIM

$$= (-1)^k \int_{I^{k-1}} f \circ b = (-1)^k \int_{I^{k-1}} b^* \eta$$

We'll continue w/ the proof of the claim next time.