

Recall: Smooth k -mfd in \mathbb{R}^n

is $M \subset \mathbb{R}^n$: at every pt it looks like \mathbb{R}^k .

$$\forall \vec{x} \in M \quad \exists \begin{array}{l} U \subset \mathbb{R}^k \\ V \subset M \end{array} \begin{array}{l} \text{open} \\ \text{open} \end{array}, \quad \alpha: U \rightarrow V \\ \text{diffeo}$$

Coord.
Chart

A k -mfd with boundary is as above but we have $U \subset \mathbb{H}^k$

$$\mathbb{H}^k = \{(x_1, \dots, x_k) \mid x_k \geq 0\}.$$

Boundary of a manifold (§24)

Def. M k -mfd in \mathbb{R}^n , $\vec{p} \in M$.

We say that $\vec{p} \in M$ is an interior point if \exists coord chart at \vec{p}

$$\alpha: U \rightarrow V \quad \text{where } U \subset \mathbb{R}^k \text{ open}$$

Otherwise, we say that \vec{p} is a boundary point.

$\partial M =$ set of bdry pts

$M - \partial M =$ set of interior pts

Lma: M k -mfd in \mathbb{R}^n , $\alpha: U \rightarrow V$
coord chart at $\vec{p} \in M$.

(a) If $U \stackrel{\text{open}}{\subset} \mathbb{R}^k$, $\vec{p} \in M - \partial M$

(b) If $U \stackrel{\text{open}}{\subset} \mathbb{H}^k$, $\vec{p} = \alpha(\vec{x}_0)$
for $\vec{x}_0 \in \mathbb{H}_+^k$

then $\vec{p} \in M - \partial M$

(c) If $U \stackrel{\text{open}}{\subset} \mathbb{H}^k$, $\vec{p} = \alpha(\vec{x}_0)$
for $\vec{x}_0 \in \partial \mathbb{H}^k$

then $\vec{p} \in \partial M$

Thm: If M is a k -mfd with boundary
in \mathbb{R}^n . Then ∂M is a $(k-1)$ -mfd
without boundary in \mathbb{R}^n .

Proof: Let $\vec{p} \in \partial M$, $\alpha: U \rightarrow V$
coord chart, $U \subset \mathbb{H}^k$ &
 $\alpha(\vec{x}_0) = \vec{p}$ for $\vec{x}_0 \in \partial \mathbb{H}^k$

By the previous lemma, every pt
in $U \cap \mathbb{H}_+^k$ maps to $M - \partial M$.

Therefore

$$\alpha(U \cap (\partial \mathbb{H}^k)) \subset \partial M.$$

$U' := U \cap (\partial \mathbb{H}^k)$, then

$$\alpha|_{U'}: U' \rightarrow V',$$

$V' := V \cap \partial M$ is

a coordinate chart, where

$$U' = U \cap (\partial \mathbb{H}^k) \subset \mathbb{R}^{k-1}$$

$$V' \subset \partial M.$$

□

Now we consider a very useful theorem that we can use to construct manifolds.

Thm: Let $U \subset \mathbb{R}^n$, $f: U \rightarrow \mathbb{R}$ smooth. Let $M := f^{-1}(0)$

$$N := f^{-1}([0, \infty))$$

If $M \neq \emptyset$ and $\text{rk } Df(\bar{x}) = 1$
 $\forall \bar{x} \in M$

then N is an n -mfd in \mathbb{R}^n
and $\partial N = M$.

Proof: We construct coord charts at every pt.

If $\bar{p} \in N \setminus \partial N$ it means by definition $f(\bar{p}) > 0$.

We have

$N \setminus \partial N = f^{-1}(0, \infty)$ & this is open (since f cts & $(0, \infty)$ open in \mathbb{R})

So $\alpha: N \setminus \partial N \xrightarrow{\text{id}} N \setminus \partial N$ is
 $\bar{x} \mapsto \bar{x}$

a coord chart around any pt
 $\bar{x} \in N \setminus \partial N$.

Now if $\bar{p} \in M = \partial N = f^{-1}(0)$
& since $Df(\bar{p}) \neq 0$, at least
one $\frac{\partial f}{\partial x_i}(\bar{p}) \neq 0$. Define

$$F(\bar{x}) := (x_1, \dots, x_{n-1}, f(\bar{x}))$$
$$\Rightarrow DF(\bar{x}) = \begin{pmatrix} I_{n-1} & 0 \\ * & D_n f(\bar{x}) \end{pmatrix}$$

non-singular. So by inverse fun
thm \exists nghd $A \overset{\text{open}}{\subset} \mathbb{R}^n$, $\bar{p} \in A$
and $B \overset{\text{open}}{\subset} \mathbb{R}^k$:

$F|_A: A \xrightarrow{-1} B$ diffeo.

Then $(F|_{A \cap M})^{-1}: B \cap \mathbb{H}^k \rightarrow A \cap M$

is a coord chart around $\bar{p} \in M$. \square

Def: Let $r > 0$

$$B^n(r) := \{ \vec{x} \in \mathbb{R}^n \mid \|\vec{x}\| \leq r \}$$

n -ball (centered at $\vec{0} \in \mathbb{R}^n$) of radius r

$$S^{n-1}(r) := \{ \vec{x} \in \mathbb{R}^n \mid \|\vec{x}\| = r \}$$

$(n-1)$ -sphere of radius r .

Cor $B^n(r)$ is an n -mfd in \mathbb{R}^n
and $S^{n-1}(r) = \partial B^n(r)$.

Proof: Apply the theorem to the function $f(\vec{x}) = r^2 - \|\vec{x}\|^2$.

Note $f(\vec{x}) \geq 0 \Leftrightarrow r^2 - \|\vec{x}\|^2 \geq 0$
 $\Leftrightarrow r \geq \|\vec{x}\|$

Also

$$Df(\vec{x}) = (-2x_1 \quad \dots \quad -2x_n)$$

$$\left[f(x_1, \dots, x_n) = r^2 - \sum_{i=1}^n x_i^2 \right]$$

So $Df(\vec{x}) \neq \vec{0}$ for any pt
in $S^{n-1}(r)$.

□

Before defining integrals of fcs
on manifolds, we need to take a
closer look at volumes.

Volume of parallelepipeds (§21)

Let's recall some linear algebra:

Lma (Gram-Schmidt)

$W \subset \mathbb{R}^n$ dim k linear subspace.
Then \exists orthonormal basis of \mathbb{R}^n so
that first k vectors form a basis
for W .

Assembling the Gram-Schmidt
on-basis into a matrix yields:

COR: $W \subset \mathbb{R}^n$ dim k linear subspace

\exists orthogonal transformation

$h: \mathbb{R}^n \rightarrow \mathbb{R}^n$ so that $h(W) = \mathbb{R}^k \times \{\vec{0}\}$

Thm (k -dim volume) The k -dim
volume is the function

$V: \{(\vec{x}_1, \dots, \vec{x}_k) \mid \vec{x}_i \in \mathbb{R}^n\} \rightarrow \mathbb{R}_{\geq 0}$

$$V(\vec{x}_1, \dots, \vec{x}_k) = \sqrt{\det(X^T X)}$$

$$X := \begin{pmatrix} | & & | \\ \vec{x}_1 & \dots & \vec{x}_k \\ | & & | \end{pmatrix}.$$

It's the unique function satisfying:

(1) If $h: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is orthogonal, then

$$V(h(\vec{x}_1), \dots, h(\vec{x}_k)) = V(\vec{x}_1, \dots, \vec{x}_k)$$

(2) If $\vec{y}_1, \dots, \vec{y}_k$ are vectors in the subspace $\mathbb{R}^k \times \{\vec{0}\} \subset \mathbb{R}^n$

$$\vec{y}_i = \begin{pmatrix} \vec{z}_i \\ \vec{0} \end{pmatrix}, \text{ then}$$

$$V(\vec{y}_1, \dots, \vec{y}_k) = |\det(\vec{z}_1, \dots, \vec{z}_k)|$$

$$(3) V(\vec{x}_1, \dots, \vec{x}_k) = 0 \Leftrightarrow \vec{x}_1, \dots, \vec{x}_k \text{ lin dep}$$

Volume of manifolds (§22)

Def: Assume M k -mfd in \mathbb{R}^n such that $M = \alpha(A)$, $\alpha: A \rightarrow \mathbb{R}^n$

Then its volume is $A \overset{\text{open}}{\subset} \mathbb{R}^k$

$$\text{vol } M := \int_A V(D\alpha), \text{ provided}$$

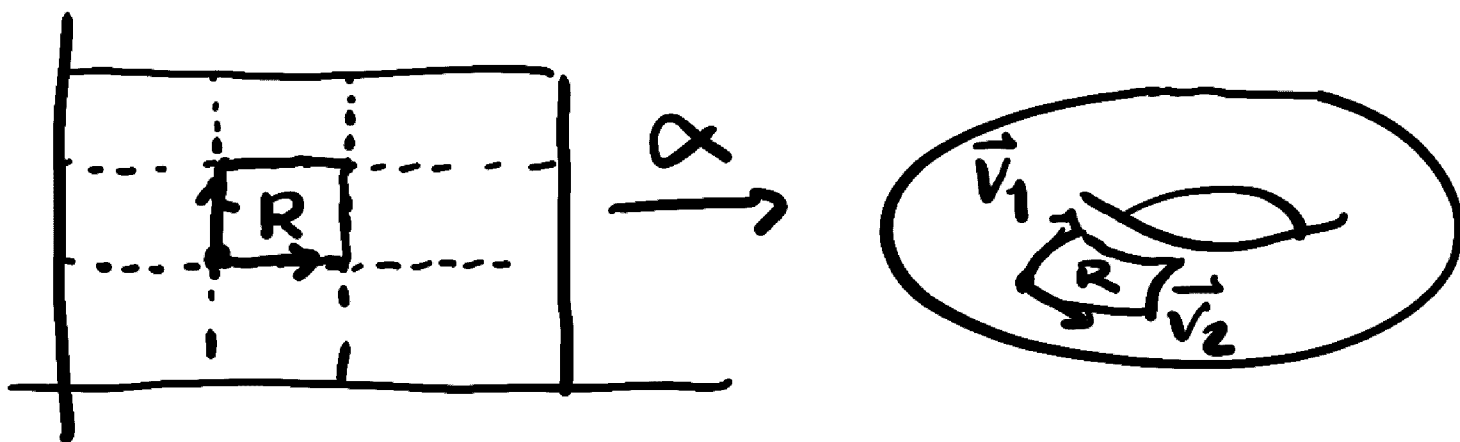
that it exists.

Suppose $A = \text{int}(Q)$ Q rectangle

P partition of Q &

$$R = [a_1, a_1 + h_1] \times \dots \times [a_k, a_k + h_k]$$

one of its subrectangles.



First order approx of the
vectors \vec{v}_i is

$$\vec{v}_i = D\alpha(\vec{a}) \cdot h_i \vec{e}_i = \frac{\partial \alpha}{\partial x_i} \cdot h_i$$

It's therefore reasonable to consider
the volume of the parallelepiped
spanned by \vec{v}_i . Its volume is

$$V(\vec{v}_1, \dots, \vec{v}_k) = V\left(\frac{\partial \alpha}{\partial x_1}, \dots, \frac{\partial \alpha}{\partial x_k}\right) \cdot \begin{pmatrix} h_1 \\ \vdots \\ h_k \end{pmatrix}$$

$$= V(D\alpha(\tilde{a})) \cdot \text{vol}(R)$$

Summing over all R etc, it approximates

$$\int_A V(D\alpha).$$

A

Def: Assume M k -mfd in \mathbb{R}^n such that $M = \alpha(A)$, $\alpha: A \rightarrow \mathbb{R}^n$

$f: M \rightarrow \mathbb{R}$ cts.

$A \stackrel{\text{open}}{\subset} \mathbb{R}^k$

$$\int_M f dV := \int_A (f \circ \alpha) V(D\alpha)$$

M

A

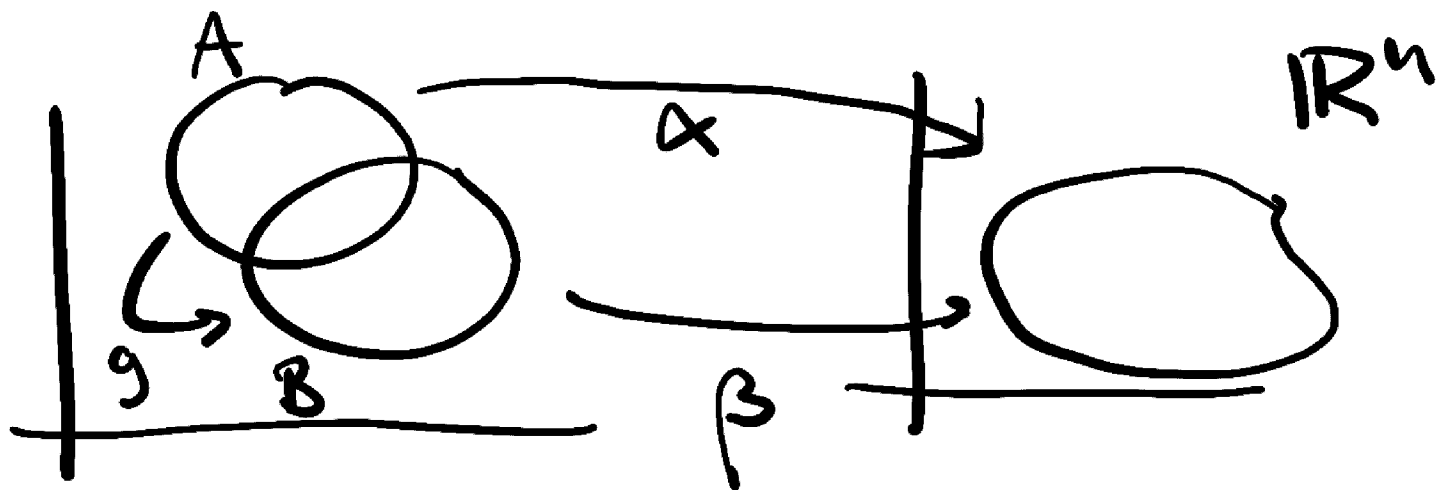
provided it exists.

Integrals with respect to volume are invariant under coord changes:

Thm: Let $A, B \stackrel{\text{open}}{\subset} \mathbb{R}^k$, $g: A \rightarrow B$ diffeo

$\beta: B \rightarrow \mathbb{R}^n$ class C^r , $Y := \beta(B)$.

Let $\alpha := \beta \circ g: A \rightarrow \mathbb{R}^n$.



If $f: Y \rightarrow \mathbb{R}$ continuous
then

$$\int_A (f \circ \alpha) V(D\alpha) = \int_B (f \circ \beta) V(D\beta)$$

& one integral exists iff the other does.

Rmk:

Sometimes to emphasize that we use the map $\beta: B \rightarrow \mathbb{R}^n$ we will use the notation

$$\int_{Y, \beta} f dV := \int_B (f \circ \beta) V(D\beta)$$