

Recall: If $T: \mathbb{R}^m \rightarrow \mathbb{R}^p$, $S: \mathbb{R}^p \rightarrow \mathbb{R}^n$ are two linear transformations with

$$T(\vec{x}) = A\vec{x} \text{ and } S(\vec{y}) = B\vec{y} \text{ where}$$

A is a $(p \times m)$ -matrix, and B is a $(n \times p)$ -matrix, then the composition of T and S is a linear transformation

$$S \circ T: \mathbb{R}^m \rightarrow \mathbb{R}^n \text{ with}$$

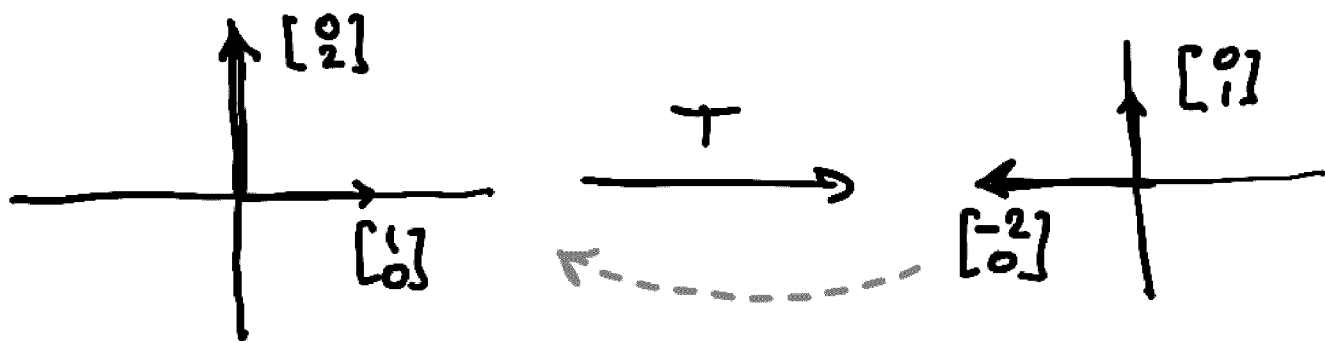
$$(S \circ T)(\vec{x}) = (BA)\vec{x}$$

matrix multiplication

§2.4 Inverse of a linear transformation

Ex: Consider $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with

$$T(\vec{x}) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \vec{x}$$



rotation 90° counterclockwise.

How do we undo T ? We rotate 90° clockwise.

A rotation 90° CW should send $[1]$ to $[0]$ and $[0]$ to $[-1]$.

$$S([1]) = [0], \quad S([0]) = [-1]$$

so its matrix is $\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$.

$$S(\vec{x}) = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \vec{x}.$$

When we now apply T first, followed by S , nothing should happen

$$(S \circ T)(\vec{x}) = \vec{x} \text{ for all vectors } \vec{x}$$

because first rotating 90° ccw
and then rotating 90° cw undoes
the rotation...

Indeed, we can also find the
matrix for $S \circ T$:

$$\begin{aligned}(S \circ T)(\vec{x}) &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \vec{x} \\ &= \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}_{= I_2 \text{ (the identity matrix)}} \vec{x} = \vec{x}\end{aligned}$$

In this example, if $A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$
we found a matrix $B = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$
so that $BA = I$.

B is called the inverse to A
(and we will write $B = A^{-1}$)

Recall from Calculus that if f is a function it sometimes has an inverse f^{-1} so that

$$f^{-1}(f(x)) = x, \quad f(f^{-1}(y)) = y.$$

If such f^{-1} exists, f is called invertible.

Def: An $(n \times n)$ -matrix A is invertible if there is a matrix B so that $AB = I_n = BA$.

In this case we say A is invertible and write $B = A^{-1}$.

Condition for invertability:

An $(n \times n)$ -matrix A is invertible
 $\iff \text{ref}(A) = I_n \iff \text{rank}(A) = n$.

Matrices being invertible are also important for systems of equations:

Remember that we can write the system

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ \vdots \\ a_{n1}x_1 + \dots + a_{nn}x_n = b_n \end{cases}$$

as the matrix equation

$$\begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$$

$$A \vec{x} = \vec{b}.$$

Now if the coefficient matrix A has an inverse A^{-1} we can solve for $\vec{x}$

$$A\vec{x} = \vec{b} \Leftrightarrow A^{-1}A\vec{x} = A^{-1}\vec{b}$$

↖ multiply with A^{-1} from
the left

$$\Leftrightarrow I_n \vec{x} = A^{-1}\vec{b} \Leftrightarrow \boxed{\vec{x} = A^{-1}\vec{b}}$$

So if A is invertible, there is
a unique solution to the system!

How do we compute A^{-1} ?

Given an $(n \times n)$ -matrix A , we form
the matrix

$[A \mid I_n]$ & perform row
operations until we arrive at

$[I_n \mid B]$. Then $B = A^{-1}$.

Ex: $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$. Find A^{-1} . We first form $[A | I_2]$:

$$\begin{array}{cc|cc} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{array} \xrightarrow{R_1 \leftarrow R_1 - R_2} \begin{array}{cc|cc} 1 & 0 & 1 & -1 \\ 0 & 1 & 0 & 1 \end{array}$$

$A \qquad I_2 \qquad I_2 \quad B$

So $B = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$. Let's confirm that this is the inverse!

$$AB = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = I_2 \quad \checkmark$$

So $A^{-1} = \begin{bmatrix} 1 & -1 \\ 0 & 1 \end{bmatrix}$.

Ex: $A = \begin{bmatrix} 1 & 2 & 2 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{bmatrix}$ Find A^{-1} if it exists!

$$\begin{array}{l} \xrightarrow{-1} \left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 1 & 3 & 1 & 0 & 1 & 0 \\ 1 & 1 & 3 & 0 & 0 & 1 \end{array} \right]^{-1} \\ \rightarrow \left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & -1 & 1 & -1 & 0 & 1 \end{array} \right] \xrightarrow{+1} \end{array}$$

$$\rightarrow \left[\begin{array}{ccc|ccc} 1 & 2 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 1 & 0 \\ 0 & 0 & 0 & -2 & 1 & 1 \end{array} \right]$$

Now we got a zero row, so $\text{ref}(A) \neq I_n$ and we can never arrive at $[I_n | B]$ so A has no inverse.

Algebraic rule:

If A and B are $(n \times n)$ -matrices that are both invertible, then AB and BA are both invertible, and

$$(AB)^{-1} = B^{-1}A^{-1}$$

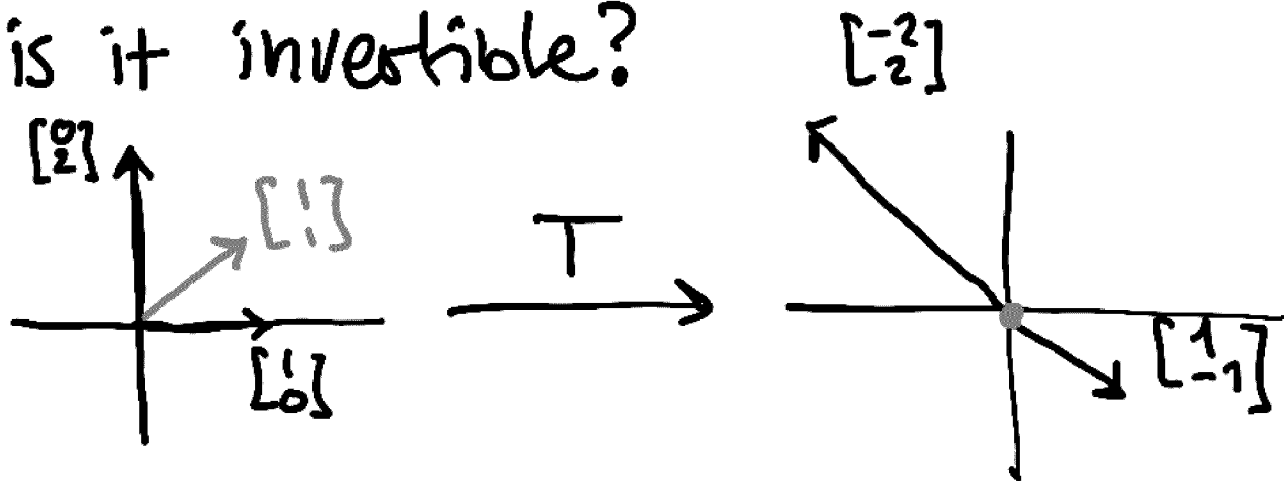
$$(BA)^{-1} = A^{-1}B^{-1}$$

Note how the order of A, B changes!

Ex: Consider the linear transformation

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2, T(\vec{x}) = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \vec{x}$$

What does it do geometrically & is it invertible?



This is an orthogonal projection to the line $y = -x$.

It is not invertible, because both vectors $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$ for example gets sent to $\vec{0}$

$$T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = T\left(\begin{bmatrix} -1 \\ 1 \end{bmatrix}\right)$$

and starting with $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$, there is

no way of undoing this!

We can also come to the same conclusion by showing that the matrix $A = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$ is not invertible.

$$\begin{array}{l} \text{"} \\ \hookrightarrow \end{array} \left[\begin{array}{cc|cc} 1 & -1 & 1 & 0 \\ -1 & 1 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & -1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{array} \right]$$

$\hookrightarrow$ zero row

$$\leadsto \text{ref}\left(\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}\right) \neq \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

So we can't continue

& A^{-1} does not exist.