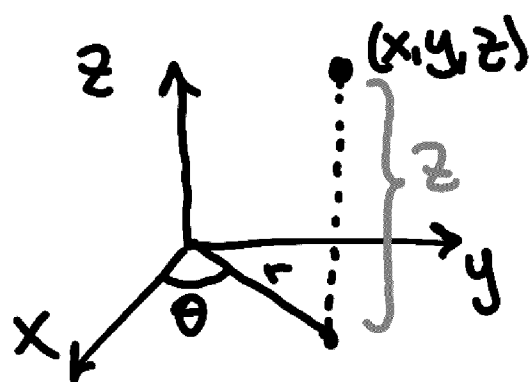
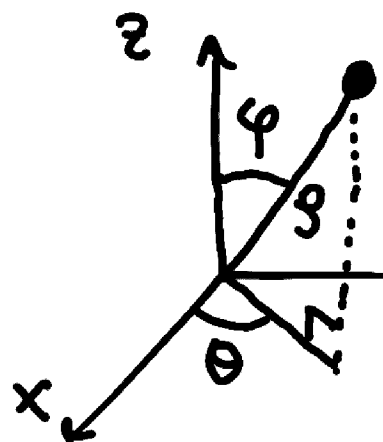


Recall: • Cylindrical coords (r, θ, z)



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

• Spherical coords (ρ, θ, ϕ)



$$\begin{cases} x = \rho \sin \phi \cos \theta \\ y = \rho \sin \phi \sin \theta \\ z = \rho \cos \phi \end{cases}$$

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$$

$$\bullet \lim_{t \rightarrow a} \vec{r}(t) = \left\langle \lim_{t \rightarrow a} x(t), \lim_{t \rightarrow a} y(t), \lim_{t \rightarrow a} z(t) \right\rangle$$

$$\bullet \vec{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$$

Later, it will be convenient to normalize the tangent vector $\vec{r}'(t)$ of a parametrized curve.

Define

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|}, \text{ provided}$$

that $\|\vec{r}'(t)\| \neq 0$.

It is called the "principal tangent vector."

Integrals

Let $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$. If

$x(t)$, $y(t)$, and $z(t)$ are continuous functions over $[a, b]$, then

$$\int_a^b \vec{r}(t) dt = \left\langle \int_a^b x(t) dt, \int_a^b y(t) dt, \int_a^b z(t) dt \right\rangle$$

Also, this is of course true for indefinite integrals, too:

$$\int \vec{r}(t) dt = \left\langle \int x(t) dt, \int y(t) dt, \int z(t) dt \right\rangle$$

Ex: $\vec{r}(t) = \langle 3t^2 + 2t, 3t - 6, 8t^3 \rangle$

$$\int \vec{r}(t) dt = \left\langle \int 3t^2 + 2t, \int 3t - 6 dt, \int 8t^3 dt \right\rangle$$

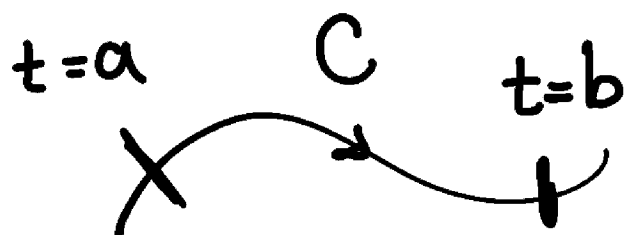
$$= \left\langle t^3 + t^2 + C_1, \frac{3t^2}{2} - 6t + C_2, 4t^4 + C_3 \right\rangle$$

Note: We need 3 different constant (one in each component).

§3.3 Arc length and Curvature

Recall from lecture 4 that we derived the following formula for the arc length of a curve C with parametrization

$$\vec{r}(t) = \langle x(t), y(t), z(t) \rangle :$$



$$A = \int_a^b \|\vec{r}'(t)\| dt$$

$$= \int_a^b \sqrt{(x'(t))^2 + (y'(t))^2 + (z'(t))^2} dt$$

Ex: If $y=f(x)$, then $\begin{cases} x=t \\ y=f(t) \end{cases}$ gives a parametrization of its graph:

$\vec{r}(t) = \langle t, f(t) \rangle$. Then $\vec{r}'(t) = \langle 1, f'(t) \rangle$, so the arc length between $t=a$ and $t=b$ is

$$\int_a^b \|\vec{r}'(t)\| dt = \int_a^b \sqrt{1 + (f'(t))^2} dt.$$

Ex: Find the arc length of
 $\vec{r}(t) = \langle \cos t, \sin t, t \rangle$ (helix) for:
 $0 \leq t \leq 2\pi$.

$$\vec{r}'(t) = \langle -\sin t, \cos t, 1 \rangle$$

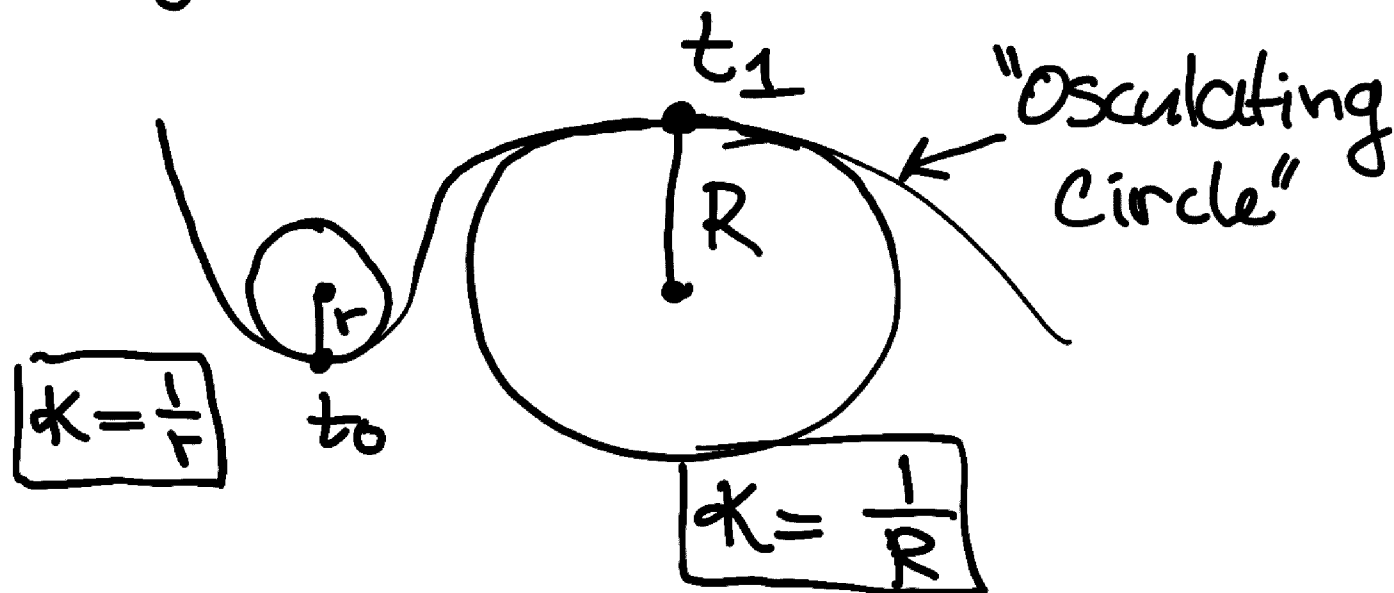
$$\begin{aligned}\|\vec{r}'(t)\| &= \sqrt{(-\sin t)^2 + (\cos t)^2 + 1} \\ &= \sqrt{1+1} = \sqrt{2}\end{aligned}$$

$$\begin{aligned}\int_0^{2\pi} \|\vec{r}'(t)\| dt &= \int_0^{2\pi} \sqrt{2} dt = \sqrt{2} [t+C]_0^{2\pi} \\ &= 2\sqrt{2}\pi.\end{aligned}$$

Definition If C is a smooth
Curve, its curvature at time
 t is

$$\kappa = \frac{\|\ddot{\vec{r}}'(t)\|}{\|\vec{r}'(t)\|^3}$$

The curvature measures how sharply the curve "turns."



The radius of the so-called "osculating circle" is the reciprocal of the curvature.

Ex: Compute the curvature of $\vec{r}(t) = \langle \cos t, \sin t, t \rangle$.

$$\vec{T}(t) = \frac{\vec{r}'(t)}{\|\vec{r}'(t)\|} = \frac{\langle -\sin t, \cos t, 1 \rangle}{\sqrt{2}}$$

$$\vec{T}'(t) = \left\langle -\frac{\cos t}{\sqrt{2}}, -\frac{\sin t}{\sqrt{2}}, 0 \right\rangle$$

$$\begin{aligned}
 \kappa &= \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|} = \frac{\sqrt{\frac{\cos^2 t}{2} + \frac{\sin^2 t}{2}}}{\sqrt{2}} \\
 &= \frac{\sqrt{1/2}}{\sqrt{2}} = \frac{1}{2}
 \end{aligned}$$

The curvature can also be computed as

$$\kappa = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3}.$$

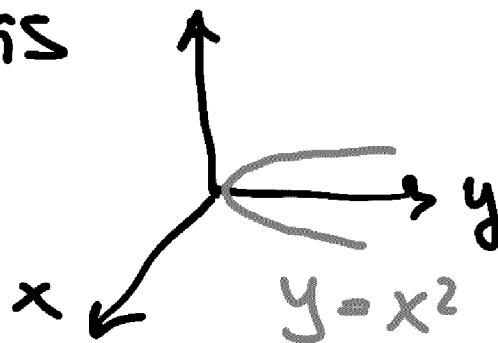
This is assuming that the curve belongs to space.

(Since the cross product only makes sense in space!)

If $y = f(x)$, a parametrization of its graph in space is

$$\vec{r}(t) = \langle t, f(t), 0 \rangle$$

It is contained



in the xy -plane, meaning $z=0$.

Now, let's compute the curvature:

$$\vec{r}'(t) = \langle 1, f'(t), 0 \rangle$$

$$\vec{r}''(t) = \langle 0, f''(t), 0 \rangle$$

$$\vec{r}'(t) \times \vec{r}''(t) = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & f'(t) & 0 \\ 0 & f''(t) & 0 \end{vmatrix}$$

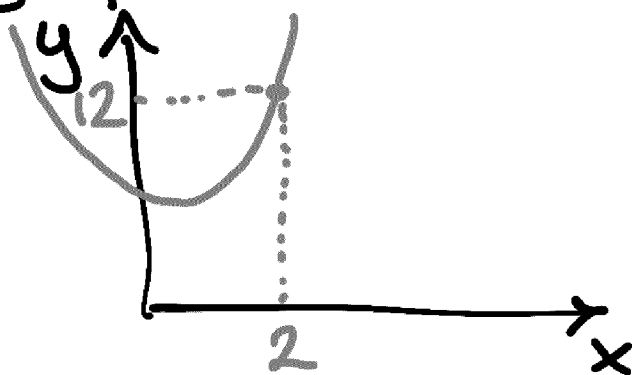
$$= \underbrace{\begin{vmatrix} f'(t) & 0 \\ f''(t) & 0 \end{vmatrix}}_{=0} \vec{i} - \underbrace{\begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix}}_{=0} \vec{j} + \begin{vmatrix} 1 & f'(t) \\ 0 & f''(t) \end{vmatrix} \vec{k}$$

$$= f''(t) \vec{k} = \langle 0, 0, f''(t) \rangle.$$

$$\kappa = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} = \frac{\|\langle 0, 0, f''(t) \rangle\|}{\|\langle 1, f'(t), 0 \rangle\|^3}$$

$$= \frac{|f''(t)|}{(1 + (f'(t))^2)^{3/2}}.$$

Ex: Let's find the curvature of the graph of $f(x) = 3x^2 - 2x + 4$ at $x=2$



$f'(x) = 6x - 2$, $f''(x) = 6$. Therefore, at $x=2$ we have

$$K = \frac{|f'(2)|}{(1+(f'(2))^2)^{3/2}} = \frac{6}{(1+10^2)^{3/2}} = \frac{6}{(101)^{3/2}}$$
$$= \frac{6}{101\sqrt{101}} \approx 0.006$$

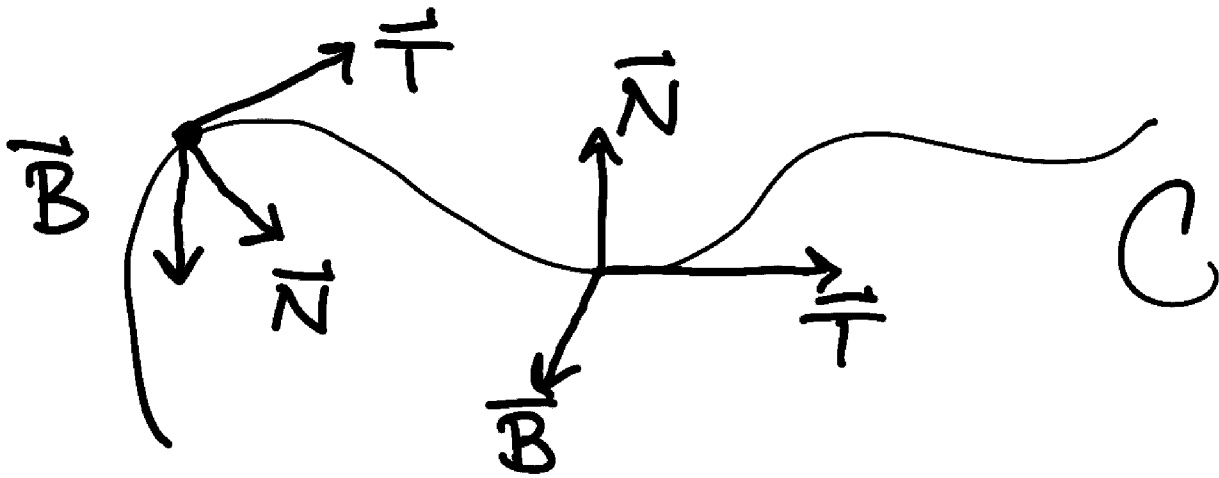
Definition: If C is a smooth curve in space, and $\vec{T}'(t) \neq 0$, then the "Principal unit normal vector" is

$$\vec{N}(t) = \frac{\vec{T}'(t)}{\|\vec{T}'(t)\|}.$$

Definition : The "binormal vector"

is

$$\vec{B}(t) = \vec{T}(t) \times \vec{N}(t).$$



$\vec{r}(t)$ = position

$\vec{T}(t)$ = normalized velocity

$\vec{N}(t)$ = normalized acceleration