

MAT 211: Linear Algebra
Practice problems

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Spring 2021

Problem 1.

Consider a linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ satisfying

$$T \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \text{ and } T \left(\begin{bmatrix} 2 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

Find the standard matrix of T .

Solution. We have:

$$T \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = T \left(-1/3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 2/3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right) = -1/3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 2/3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1/3 \\ 0 \end{bmatrix}$$

$$T \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = T \left(2/3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} - 1/3 \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right) = 2/3 \begin{bmatrix} 1 \\ 2 \end{bmatrix} - 1/3 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 2/3 \\ 1 \end{bmatrix}$$

□

Answer: $\begin{bmatrix} -1/3 & 2/3 \\ 0 & 1 \end{bmatrix}.$

□

Problem 2.

Consider the matrix

$$A = \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 2 & 0 & 0 \\ 2 & 0 & 0 & k \end{bmatrix},$$

where k is a real parameter.

1. Find the determinant of A and say for which values of k the matrix A is invertible.
2. Find the dimensions of $\text{null}(A)$ and $\text{col}(A)$ as k varies.
3. For $k = 4$,
 - find the eigenvalues of A ;
 - find an eigenvector corresponding to the eigenvalue $\lambda = 5$.

Solution. 1. We have

$$\det \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 2 & 0 & 0 \\ 2 & 0 & 0 & k \end{bmatrix} = 16 - 4k.$$

The matrix A is invertible if and only if $k \neq 4$.

2. If $k \neq 4$, then A is invertible, thus the dimension of $\text{col}(A)$ is 4 and the dimension of $\text{null}(A)$ is 0.

Consider the case $k = 4$. Then

$$A = \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0 & 2 & 0 \\ 0 & 2 & 0 & 0 \\ 2 & 0 & 0 & 4 \end{bmatrix}$$

and we can check that the dimension of $\text{col}(A)$ is 3 and the dimension of $\text{null}(A)$ is 1.

3. For $k = 4$, we calculate the characteristic polynomial of A :

$$\det(A - \lambda I) = \det \begin{bmatrix} 1 - \lambda & 0 & 0 & 2 \\ 0 & -\lambda & 2 & 0 \\ 0 & 2 & -\lambda & 0 \\ 2 & 0 & 0 & 4 - \lambda \end{bmatrix} = (\lambda^2 - 5\lambda)(\lambda^2 - 4).$$

Therefore, A has eigenvalues 5, 0, -2, 2.

For $\lambda = 5$, we have

$$A - \lambda I = \begin{bmatrix} -4 & 0 & 0 & 2 \\ 0 & -5 & 2 & 0 \\ 0 & 2 & -5 & 0 \\ 2 & 0 & 0 & -1 \end{bmatrix},$$

and we calculate that $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 2 \end{bmatrix}$ is an eigenvector corresponding to $\lambda = 5$.

□

Problem 3. Consider the matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}.$$

1. Find the eigenvalues and corresponding eigenspaces of A . Conclude that A is diagonalizable.
2. Write down a basis $\mathcal{B} = \{v_1, v_2, v_3\}$ of \mathbb{R}^3 consisting of eigenvectors of A . Using this, find an invertible matrix S such that $S^{-1}AS$ is a diagonal matrix.

3. Find the coordinates of $\begin{bmatrix} 6 \\ -1 \\ -2 \end{bmatrix}$ with respect to the basis \mathcal{B} ; i.e. write $\begin{bmatrix} 6 \\ -1 \\ -2 \end{bmatrix}$ as a linear combination of v_1, v_2 , and v_3 .

4. Compute $A^{456} \begin{bmatrix} 6 \\ -1 \\ -2 \end{bmatrix}$.

Solution. 1. The eigenvalues of A are 0 and 3;

- $\text{span} \left(\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right)$ is the eigenspace corresponding to 0, and $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$ are two linearly independent eigenvectors corresponding to 0,
- $\text{span} \left(\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right)$ is the eigenspace corresponding to 3, and $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$ is an eigenvector corresponding to 3.

2. $\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$ is a basis consisting of eigenvectors of A . Set

$$S = \begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 0 & -1 & 1 \end{bmatrix},$$

then $S^{-1}AS$ is a diagonal matrix.

3. Solving the system

$$\begin{bmatrix} 6 \\ -1 \\ -2 \end{bmatrix} = c_1 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + c_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

we obtain $c_1 = 2, c_2 = 3, c_3 = 1$; i.e.:

$$\begin{bmatrix} 6 \\ -1 \\ -2 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

4. We have:

$$\begin{aligned} A^{456} \begin{bmatrix} 6 \\ -1 \\ -2 \end{bmatrix} &= A^{456} \left(2 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right) = \\ &= 0^{456} \times 2 \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} + 0^{456} \times 3 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + 3^{456} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 3^{456} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}. \end{aligned}$$

□

Problem 4.

Write the matrix representing the linear transformation T on \mathbb{R}^2 that reflects vectors about the line $y = x$. Is it invertible? What about diagonalizability?

Solution. We can compute that

$$T \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad \text{and} \quad T \left(\begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

Therefore, $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ is the standard matrix of T .

The transformation T is invertible.

The transformation T has two linearly independent eigenvectors, thus T is diagonalizable. \square

Problem 5.

Consider the vector subspace $W = \text{span} \left(\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \right)$. Find the projection of $\begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix}$ onto W and onto W^\perp .

Solution. We have:

$$\text{proj}_W \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} = \frac{\begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \frac{4 + 4 + 6}{1 + 4 + 9} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix},$$

and:

$$\text{proj}_{W^\perp} \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} = \text{perp}_W \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} - \text{proj}_W \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ -1 \end{bmatrix}.$$

\square

Problem 6.

Find all a, b, c such that the following matrices are simultaneously non-invertible

$$\begin{bmatrix} a-4 & -2 \\ b & 1 \end{bmatrix}, \quad \begin{bmatrix} 1 & 1 \\ 4-a-c & a+b \end{bmatrix}, \quad \begin{bmatrix} 1 & \frac{1}{2}-c \\ 2 & a+b \end{bmatrix}.$$

Answer: $a = 2, b = 1, c = -1$. \square

Solution. The matrices are non-invertible if and only if their determinants are zero. We need to solve the system:

$$\begin{aligned} \det \begin{bmatrix} a-4 & -2 \\ b & 1 \end{bmatrix} &= 0 \\ \det \begin{bmatrix} 1 & 1 \\ 4-a-c & a+b \end{bmatrix} &= 0 \\ \det \begin{bmatrix} 1 & \frac{1}{2}-c \\ 2 & a+b \end{bmatrix} &= 0 \end{aligned}$$

or:

$$\begin{aligned} a - 4 - (-2)b &= 0 \\ a + b - (4 - a - c) &= 0 \end{aligned}$$

$$a + b - 2\left(\frac{1}{2} - c\right) = 0$$

or:

$$a + 2b = 4$$

$$2a + b + c = 4$$

$$a + b + 2c = 1$$

or:

$$\left[\begin{array}{ccc|c} 1 & 2 & 0 & 4 \\ 2 & 1 & 1 & 4 \\ 1 & 1 & 2 & 1 \end{array} \right] \xrightarrow{\substack{R_2 - 2R_1 \\ R_3 - R_1}} \left[\begin{array}{ccc|c} 1 & 2 & 0 & 4 \\ 0 & -3 & 1 & -4 \\ 0 & -1 & 2 & -3 \end{array} \right] \xrightarrow{R_2 - 3R_3} \left[\begin{array}{ccc|c} 1 & 2 & 0 & 4 \\ 0 & 0 & -5 & 5 \\ 0 & -1 & 2 & -3 \end{array} \right]$$

$$\xrightarrow{-R_3} \left[\begin{array}{ccc|c} 1 & 2 & 0 & 4 \\ 0 & 0 & 1 & -1 \\ 0 & 1 & -2 & 3 \end{array} \right] \xrightarrow{R_3 + 2R_2} \left[\begin{array}{ccc|c} 1 & 2 & 0 & 4 \\ 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 1 \end{array} \right] \xrightarrow{R_1 - 2R_3} \left[\begin{array}{ccc|c} 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & -1 \\ 0 & 1 & 0 & 1 \end{array} \right].$$

Therefore, $a = 2, b = 1, c = -1$. □

Problem 7.

Suppose v_1, v_2, v_3 are linearly independent vectors.

1. Find all scalars a and b such that

$$2av_1 - v_2 = v_1 + bv_2.$$

2. Find all scalars k such that the vectors

$$v_1 + 3v_3, \quad 2v_1 + kv_3, \quad 2v_2$$

are linearly dependent.

Solution. 1. We have:

$$(2a - 1)v_1 + (-1 - b)v_2 = 0.$$

Since v_1, v_2 are linearly independent, we obtain $2a - 1 = 0$ and $-1 - b = 0$. Answer: $a = \frac{1}{2}, b = -1$.

2. The vectors $v_1 + 3v_3, 2v_1 + kv_3, 2v_2$ are linearly independent if and only if there are scalars c_1, c_2, c_3 , at least one of which is not zero, such that

$$c_1(v_1 + 3v_3) + c_2(2v_1 + kv_3) + c_3(2v_2) = 0,$$

or:

$$(c_1 + 2c_2)v_1 + (2c_3)v_2 + (3c_1 + kc_2)v_3 = 0.$$

Since v_1, v_2, v_3 are linearly independent, $(c_1 + 2c_2)v_1 + (2c_3)v_2 + (3c_1 + kc_2)v_3$ is equal to 0 if and only if

$$c_1 + 2c_2 = 0$$

$$2c_3 = 0$$

$$3c_1 + kc_2 = 0.$$

We need to find all k such that the last system has a non-zero solution. Using the determinant test, we have:

$$\det \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 2 \\ 3 & k & 0 \end{bmatrix} = 0,$$

we obtain that $k = 6$. □

Problem 8. Find an orthogonal basis of $\text{span} \left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \right)$.

Solution. Since $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$ are linearly independent, $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$ form a basis of $W = \text{span} \left(\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \right)$.

The vectors $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} - t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ also form a basis for W , and we need to find t so that

$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} - t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ are orthogonal vectors.

We have:

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \cdot \left(\begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} - t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right) = 0,$$

or: $3 - 2t = 0$. Thus $t = 3/2$ and $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1/3 \\ 0 \\ 1/3 \end{bmatrix}$ is an orthogonal basis for W . □