# 1 Basis and Dimension

Recall that S is a **subspace** of  $\mathbb{R}^n$  if:

1) S contains 0;

2+3) a linear combination of vectors from S is in S.

Equivalently, S is a subspace if and only if  $S = \text{span}(v_1, v_2, \ldots, v_k)$ . If  $v_1, v_2, \ldots, v_k$  are linearly independent, then  $v_1, v_2, \ldots, v_k$  is a **basis** for S. In this case k is the **dimension** of S.

Example: lines and planes through the origin are subspaces.

The dimension of a subspace is independent of the choice of a basis because:

Theorem. Any two bases for a subspace have the same number of vectors.

### 1.1 row(A)

Consider the following **problem**: find a basis for

span 
$$\begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \\ \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}, \\ \begin{bmatrix} 3 & 1 & 3 \end{bmatrix}, \end{pmatrix}$$

Note that  $\begin{bmatrix} 3 & 1 & 3 \end{bmatrix} = 2 \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$ . By definition, span  $\begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \\ \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}, \\ \begin{bmatrix} 3 & 1 & 3 \end{bmatrix}, \end{pmatrix}$  is

$$c_{1} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} + c_{2} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} + c_{3} \begin{bmatrix} 3 & 1 & 3 \end{bmatrix} = c_{1} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} + c_{2} \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} + c_{3}(2 \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} + \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}) = (c_{1} + 2c_{3}) \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} + (c_{2} + c_{3}) \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}.$$

Since  $c_1, c_2, c_3$  are any numbers,  $c_1 + 2c_3$  and  $c_2 + c_3$  are also any numbers. Therefore,

$$(c_1 + 2c_3) \begin{bmatrix} 1 & 0 & 1 \end{bmatrix} + (c_2 + c_3) \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$$

is

$$\operatorname{span}\left(\begin{bmatrix}1 & 0 & 1\\ 1 & 1 & 1\end{bmatrix},\right)$$

Clearly,  $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$  are linearly independent (they are not parallel). Thus,  $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$  is a basis for span  $\begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$ , and this subspace has dimension 2.

Recall next that span 
$$\begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \\ \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}, \\ \begin{bmatrix} 3 & 1 & 3 \end{bmatrix} \end{pmatrix}$$
 is row  $\begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \end{pmatrix}$ . Hence  $\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 & 1 \end{bmatrix}$  is also a basis for row  $\begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \end{pmatrix}$ .

**Remark.** Let A be a matrix. Then elementary row operations do not change row(A). In particular, we can remake the previous example using the elementary row operations as follows:

$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \xrightarrow{R_3 - 2R_1} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \xrightarrow{R_3 - R_2} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$
thus
$$\operatorname{row} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} = \operatorname{row} \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$
and
$$\begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \text{ is a basis for row} \left( \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \right).$$
We can also continue
$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 - R_1} \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$
elimination the first 1 in the second row. We obtain a matrix in reduced of

eliminating the first 1 in the second row. We obtain a matrix in reduced echelon form. The dimension of row  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  is clearly two.

## 1.2 null(A) and col(A)

Recall that elementary row operations of a matrix do not change solutions of the associated system of linear equations. Therefore, if A is a matrix, then elementary row operations of A do not change null(A).

In our example:

null 
$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}$$
 = null  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ 

For the last matrix, the corresponding system is

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

or

We conclude that null(A), or the set of solutions, is  $t \begin{bmatrix} 1\\0\\-1 \end{bmatrix}$  or span  $\begin{bmatrix} 1\\0\\-1 \end{bmatrix}$ .

We can also double-check that  $\begin{vmatrix} 1\\0\\-1\end{vmatrix}$  is a solution for the original system of equations

$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \text{ we have: } \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

**Remark.** Elementary row operations change col(A) but do not change the di-

In our example, we see that the first two columns of  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  are linearly independent, therefore the first two columns of  $\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}$  are also linearly independent. On the other hand, the last column of  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  is equal to its first column. Similarly, the last column of  $\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}$  is equal to its first column.

#### 1.3Rank.

**Definition.** The **rank** of a matrix is the dimension of its row space. The rank of a matrix is also equal to the dimension of its column space. The rank of a matrix is equal to the number of non-zero rows in its echelon form. The **nullity** of a matrix is the dimension of its null space.

The Rank Theorem. If A is an  $m \times n$  matrix, then

$$\operatorname{rank}(A) + \operatorname{nullity}(A) = n.$$

Explanation. Consider a system of linear equations Ax = 0, where x is a column vector. Assume that A is in row echelon form. Then rank(A) is equal to the number of non-free variables, while  $\operatorname{nullity}(A)$  is equal to the number of free variables. The number of all variables is n.

In our example,

rank 
$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}$$
 = rank  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  = 2

and

nullity 
$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}$$
 = nullity  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$  = 1.

The rank theorem takes form:

$$2 + 1 = 3.$$

# 1.4 Another example

**Question:** Find bases for row(A), null(A), col(A), and find rank(A), where

$$A = \begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix}.$$

Solution. Applying the elimination method, we obtain:

$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix} \xrightarrow{R_2 - 2R_1} \begin{bmatrix} 1 & 2 & 4 \\ 0 & -4 & -4 \\ 0 & -1 & -1 \end{bmatrix} \xrightarrow{R_2/(-4)} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \xrightarrow{R_2 - R_2} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$
Therefore, row  $\begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix} = \operatorname{row} \begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$  and  $\begin{bmatrix} 1 & 2 & 4 \end{bmatrix}$ ,  $\begin{bmatrix} 0 & 1 & 1 \end{bmatrix}$  is a basis for row  $\begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix}$ .  
We can also continue
$$\begin{bmatrix} 1 & 2 & 4 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$
(reduced echelon form is more convenient than just echelon form). We see that  $\begin{bmatrix} 1 & 0 & 2 \end{bmatrix}$ ,  $\begin{bmatrix} 0 & 1 & 1 \end{bmatrix}$   
is also a basis for row  $\begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix}$ .  
We have null  $\begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix} = \operatorname{null} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$  and we need to solve
$$\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_1 - 2R_2} \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

We have

null 
$$\begin{bmatrix} 1 & 2 & 4 \\ 2 & 0 & 4 \\ 1 & 1 & 3 \end{bmatrix}$$
 = null  $\begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$  = span  $\left( \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \right)$ .

Since x and y are leading (non-free) variables, the first two columns of A form a basis for col(A). In particular,

$$\operatorname{col}(A) = \operatorname{span}\left(\begin{bmatrix}1\\2\\1\end{bmatrix}, \begin{bmatrix}2\\0\\1\end{bmatrix}\right).$$
  
Finally, rank  $\begin{bmatrix}1 & 2 & 4\\2 & 0 & 4\\1 & 1 & 3\end{bmatrix} = \operatorname{rank}\begin{bmatrix}1 & 0 & 2\\0 & 1 & 1\\0 & 0 & 0\end{bmatrix} = 2.$  The Rank Theorem "rank(A)+nullity(A) =   
n" takes form  $2 + 1 = 3.$