

MAT 552

Introduction to

Lie Groups and Lie Algebras

Claude LeBrun

Stony Brook University

March 25, 2021

Definition. A Riemannian metric g on a smooth manifold M is a smooth symmetric tensor field

$$g \in C^\infty(\odot^2 T^*M)$$

Definition. A Riemannian metric g on a smooth manifold M is a smooth symmetric tensor field

$$g \in C^\infty(\odot^2 T^*M)$$

which defines a positive-definite inner product on each tangent space $T_p M$:

Definition. A Riemannian metric g on a smooth manifold M is a smooth symmetric tensor field

$$g \in C^\infty(\odot^2 T^*M)$$

which defines a positive-definite inner product on each tangent space $T_p M$:

$$v \neq 0 \implies g(v, v) > 0.$$

For any piece-wise smooth path

$$\gamma : [a, b] \rightarrow M$$

in (M, g) we define its length to be

$$L(\gamma) = \int_a^b |\gamma'(t)|_g dt$$

For any piece-wise smooth path

$$\gamma : [a, b] \rightarrow M$$

in (M, g) we define its length to be

$$L(\gamma) = \int_a^b \sqrt{g \left(\frac{d\gamma(t)}{dt}, \frac{d\gamma(t)}{dt} \right)} dt$$

For any piece-wise smooth path

$$\gamma : [a, b] \rightarrow M$$

in (M, g) we define its length to be

$$L(\gamma) = \int_a^b |\gamma'(t)|_g dt$$

For any piece-wise smooth path

$$\gamma : [a, b] \rightarrow M$$

in (M, g) we define its length to be

$$L(\gamma) = \int_a^b |\gamma'(t)|_g dt.$$

We say that γ is a path from p to q if

$$\gamma(a) = p \quad \text{and} \quad \gamma(b) = q.$$

Definition. *Let (M, g) be a connected Riemannian manifold.*

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

$$\text{dist}(p, q) = \inf\{L(\gamma) \mid \gamma \text{ piece-wise smooth path from } p \text{ to } q\}$$

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

$$\text{dist}(p, q) = \inf\{L(\gamma) \mid \gamma \text{ piece-wise smooth path from } p \text{ to } q\}$$

Proposition. This definition makes (M, dist) into a metric space.

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

$$\text{dist}(p, q) = \inf\{L(\gamma) \mid \gamma \text{ piece-wise smooth path from } p \text{ to } q\}$$

Proposition. This definition makes (M, dist) into a metric space.

$$\text{dist}(p, q) \geq 0$$

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

$$\text{dist}(p, q) = \inf\{L(\gamma) \mid \gamma \text{ piece-wise smooth path from } p \text{ to } q\}$$

Proposition. This definition makes (M, dist) into a metric space.

$$\text{dist}(p, q) \geq 0$$

$$\text{dist}(p, q) = \text{dist}(q, p)$$

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

$$\text{dist}(p, q) = \inf\{L(\gamma) \mid \gamma \text{ piece-wise smooth path from } p \text{ to } q\}$$

Proposition. This definition makes (M, dist) into a metric space.

$$\text{dist}(p, q) \geq 0$$

$$\text{dist}(p, q) = \text{dist}(q, p)$$

$$\text{dist}(p, r) \leq \text{dist}(p, q) + \text{dist}(q, r)$$

Definition. Let (M, g) be a connected Riemannian manifold. For any $p, q \in M$ we define

$$\text{dist}(p, q) = \inf\{L(\gamma) \mid \gamma \text{ piece-wise smooth path from } p \text{ to } q\}$$

Proposition. This definition makes (M, dist) into a metric space.

$$\text{dist}(p, q) \geq 0$$

$$\text{dist}(p, q) = \text{dist}(q, p)$$

$$\text{dist}(p, r) \leq \text{dist}(p, q) + \text{dist}(q, r)$$

$$\text{dist}(p, q) = 0 \iff p = q$$

Theorem. Let g be a Riemannian metric on M . Then M admits a unique affine connection ∇ such that

- $\nabla_v w - \nabla_w v = [v, w]$
- $\nabla_u g(v, w) = g(\nabla_u v, w) + g(v, \nabla_u w)$.

Theorem. *Let g be a Riemannian metric on M .
Then M admits a unique affine connection ∇
such that*

Theorem. *Let g be a Riemannian metric on M . Then M admits a unique affine connection ∇ such that*

- $\nabla_v w - \nabla_w v = [v, w]$

Theorem. Let g be a Riemannian metric on M . Then M admits a unique affine connection ∇ such that

- $\nabla_v w - \nabla_w v = [v, w]$; and
- $u g(v, w) = g(\nabla_u v, w) + g(v, \nabla_u w)$.

Definition. *A parameterized curve*

Definition. *A parameterized curve*

$$\gamma : (a, b) \rightarrow M$$

Definition. *A parameterized curve*

$$\gamma : (a, b) \rightarrow M$$

in a Riemannian manifold (M, g)

Definition. *A parameterized curve*

$$\gamma : (a, b) \rightarrow M$$

in a Riemannian manifold (M, g) is said to be a geodesic if

Definition. *A parameterized curve*

$$\gamma : (a, b) \rightarrow M$$

in a Riemannian manifold (M, g) is said to be a geodesic if

$$\nabla_{\gamma'} \gamma' = 0$$

Definition. A parameterized curve

$$\gamma : (a, b) \rightarrow M$$

in a Riemannian manifold (M, g) is said to be a geodesic if

$$\nabla_{\gamma'} \gamma' = 0$$

for every $t \in (a, b)$, where ∇ denotes the Riemannian connection determined by g .

Example.

Example. Let G be a compact Lie group,

Example. Let G be a compact Lie group, and let g be a bi-invariant metric.

Example. Let G be a compact Lie group, and let g be a bi-invariant metric.

Let X be a left-invariant vector field on G .

Example. Let \mathbf{G} be a compact Lie group, and let g be a bi-invariant metric.

Let X be a left-invariant vector field on \mathbf{G} .

Then $\nabla_X X = \frac{1}{2}[X, X] = 0$, since

Example. Let \mathbf{G} be a compact Lie group, and let g be a bi-invariant metric.

Let X be a left-invariant vector field on \mathbf{G} .

Then $\nabla_X X = \frac{1}{2}[X, X] = 0$, since

$$\nabla_X Y = \frac{1}{2}[X, Y] \quad \forall X, Y \in \mathfrak{g}.$$

Example. Let \mathbf{G} be a compact Lie group, and let g be a bi-invariant metric.

Let X be a left-invariant vector field on \mathbf{G} .

Then $\nabla_X X = \frac{1}{2}[X, X] = 0$, since

$$\nabla_X Y = \frac{1}{2}[X, Y] \quad \forall X, Y \in \mathfrak{g}.$$

Hence any flow-line of X is a geodesic of g .

Example. Let \mathbf{G} be a compact Lie group, and let g be a bi-invariant metric.

Let X be a left-invariant vector field on \mathbf{G} .

Then $\nabla_X X = \frac{1}{2}[X, X] = 0$, since

$$\nabla_X Y = \frac{1}{2}[X, Y] \quad \forall X, Y \in \mathfrak{g}.$$

Hence any flow-line of X is a geodesic of g .

In particular, the curves

$$t \mapsto \exp(tX)$$

are exactly the geodesics through \mathbf{e} .

Example. Let \mathbf{G} be a compact Lie group, and let g be a bi-invariant metric.

Let X be a left-invariant vector field on \mathbf{G} .

Then $\nabla_X X = \frac{1}{2}[X, X] = 0$, since

$$\nabla_X Y = \frac{1}{2}[X, Y] \quad \forall X, Y \in \mathfrak{g}.$$

Hence any flow-line of X is a geodesic of g .

In particular, the curves

$$t \mapsto \exp(tX)$$

are exactly the geodesics through \mathbf{e} .

These are the “one-parameter subgroups” of \mathbf{G} .

Let (M, g) be a Riemannian n -manifold, $p \in M$.

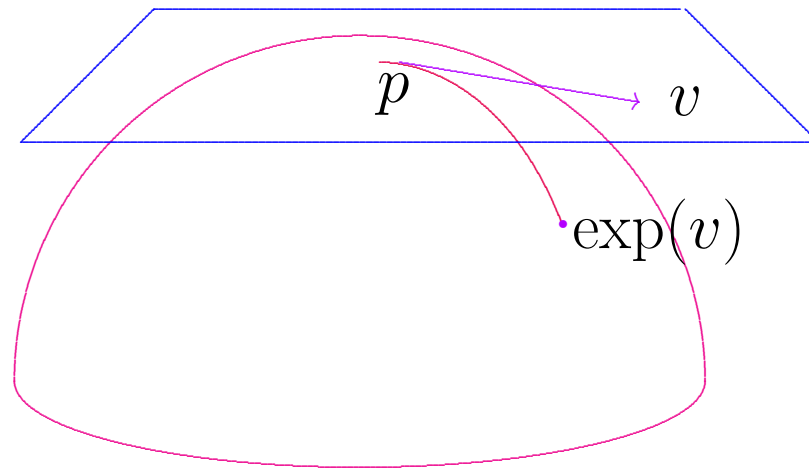
Let (M, g) be a Riemannian n -manifold, $p \in M$.
Metric defines preferred curves, called *geodesics*.
Following geodesics from p defines a map

$$\exp : T_p M \dashrightarrow M$$

Let (M, g) be a Riemannian n -manifold, $p \in M$.
Metric defines preferred curves, called *geodesics*.
Following geodesics from p defines a map

$$\exp : T_p M \dashrightarrow M$$

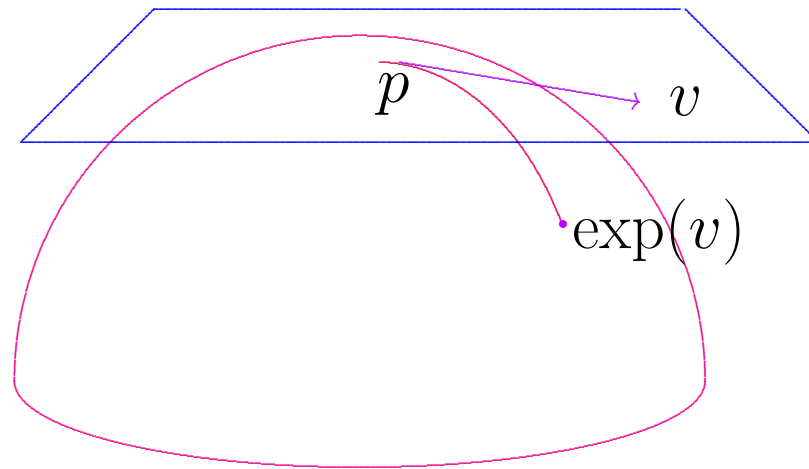
which is at least defined in a neighborhood of 0:



Let (M, g) be a Riemannian n -manifold, $p \in M$.
Metric defines preferred curves, called *geodesics*.
Following geodesics from p defines a map

$$\exp : T_p M \dashrightarrow M$$

which is at least defined in a neighborhood of 0:

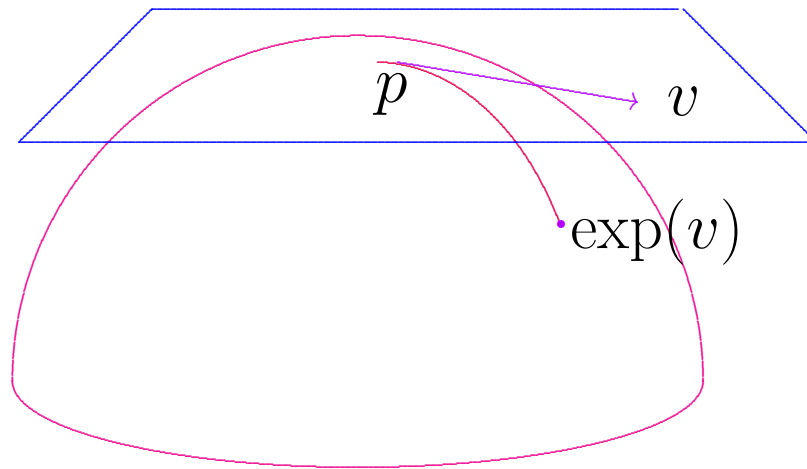


This is a diffeomorphism on a neighborhood of 0.

Let (M, g) be a Riemannian n -manifold, $p \in M$.
Metric defines preferred curves, called *geodesics*.
Following geodesics from p defines a map

$$\exp : T_p M \dashrightarrow M$$

which is at least defined in a neighborhood of 0:



This is a diffeomorphism on a neighborhood of 0.

For G with bi-invariant g , equals Lie-theoretic \exp .

Definition. A Riemannian manifold (M, g) is called *geodesically complete at $p \in M$* if

$$\exp : T_p M \rightarrow M$$

is defined on the entire tangent space.

Definition. A Riemannian manifold (M, g) is called *geodesically complete at* $p \in M$ if

$$\exp : T_p M \rightarrow M$$

is defined on the entire tangent space.

Definition. A Riemannian manifold (M, g) is called *geodesically complete* if

$$\exp : TM \rightarrow M$$

is defined on the entire tangent bundle.

Theorem (Hopf-Rinow). *For (M, g) connected Riemannian manifold, the following are equivalent:*

Theorem (Hopf-Rinow). *For (M, g) connected Riemannian manifold, the following are equivalent:*

- (M, dist) is a complete metric space;

Theorem (Hopf-Rinow). *For (M, g) connected Riemannian manifold, the following are equivalent:*

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;

Theorem (Hopf-Rinow). *For (M, g) connected Riemannian manifold, the following are equivalent:*

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Theorem (Hopf-Rinow). *For (M, g) connected Riemannian manifold, the following are equivalent:*

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Moreover, any of these conditions implies

Theorem (Hopf-Rinow). For (M, g) connected Riemannian manifold, the following are equivalent:

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Moreover, any of these conditions implies

- every pair of points $p, q \in M$

Theorem (Hopf-Rinow). *For (M, g) connected Riemannian manifold, the following are equivalent:*

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Moreover, any of these conditions implies

- *every pair of points $p, q \in M$ is joined by a geodesic segment*

Theorem (Hopf-Rinow). For (M, g) connected Riemannian manifold, the following are equivalent:

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Moreover, any of these conditions implies

- every pair of points $p, q \in M$ is joined by a geodesic segment

$$\gamma : [a, b] \rightarrow M$$

Theorem (Hopf-Rinow). For (M, g) connected Riemannian manifold, the following are equivalent:

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Moreover, any of these conditions implies

- every pair of points $p, q \in M$ is joined by a geodesic segment

$$\gamma : [a, b] \rightarrow M$$

of length $L(\gamma) = \text{dist}(p, q)$.

Corollary. *Let M be a compact manifold, g any Riemannian metric on M .*

Corollary. *Let M be a compact manifold, g any Riemannian metric on M . Then, $\forall p \in M$,*

Corollary. *Let M be a compact manifold, g any Riemannian metric on M . Then, $\forall p \in M$,*

$$\exp : T_p M \rightarrow M$$

Corollary. *Let M be a compact manifold, g any Riemannian metric on M . Then, $\forall p \in M$,*

$$\exp : T_p M \rightarrow M$$

is surjective.

Corollary. *Let G be a compact Lie group. Then*

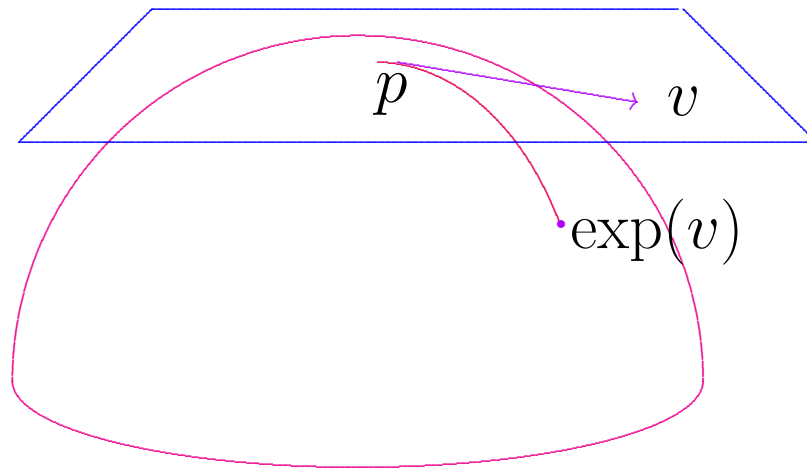
$$\exp : \mathfrak{g} \rightarrow G$$

is surjective.

Let (M, g) be a Riemannian n -manifold, $p \in M$.
Metric defines preferred curves, called *geodesics*.
Following geodesics from p defines a map

$$\exp : T_p M \dashrightarrow M$$

which is at least defined in a neighborhood of 0:



This is a diffeomorphism on a neighborhood of 0.

For G with bi-invariant g , equals Lie-theoretic \exp .

Theorem (Hopf-Rinow). For (M, g) connected Riemannian manifold, the following are equivalent:

- (M, dist) is a complete metric space;
- (M, g) is a geodesically complete;
- (M, g) is a geodesically complete at some p .

Moreover, any of these conditions implies

- every pair of points $p, q \in M$ is joined by a geodesic segment

$$\gamma : [a, b] \rightarrow M$$

of length $L(\gamma) = \text{dist}(p, q)$.

Corollary. *Let G be a compact Lie group. Then*

$$\exp : \mathfrak{g} \rightarrow G$$

is surjective.

Corollary. *Let G be a compact Lie group. Then*

$$\exp : \mathfrak{g} \rightarrow G$$

is surjective.

Not true for non-compact Lie groups!

Corollary. *Let G be a compact Lie group. Then*

$$\exp : \mathfrak{g} \rightarrow G$$

is surjective.

Not true for non-compact Lie groups!

We'll see it's not even true for $\mathbf{SL}(2, \mathbb{R})$!