#### MAT 552

Introduction to

Lie Groups and Lie Algebras

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**Definition.** A Riemannian metric g on a smooth manifold M is a smooth symmetric tensor field  $g \in C^{\infty}(\odot^2 T^*M)$  **Definition.** A Riemannian metric g on a smooth manifold M is a smooth symmetric tensor field  $g \in C^{\infty}(\odot^2 T^*M)$ 

which defines a positive-definite inner product on each tangent space  $T_pM$ : **Definition.** A Riemannian metric g on a smooth manifold M is a smooth symmetric tensor field  $g \in C^{\infty}(\odot^2 T^*M)$ 

which defines a positive-definite inner product on each tangent space  $T_pM$ :

 $v \neq 0 \implies \mathbf{g}(v,v) > 0.$ 

**Example.** Since  $T_p \mathbb{R}^n = \mathbb{R}^n$ , usual dot product  $\langle , \rangle$  defines a Riemannian metric on  $\mathbb{R}^n$ :

$$\langle , \rangle = dx^1 \otimes dx^1 + \dots + dx^n \otimes dx^n$$

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Restricting dot product  $\langle , \rangle$  to TM defines a Riemannian metric on M:

$$g = j^* (dx^1 \otimes dx^1 + \dots + dx^n \otimes dx^n).$$

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$$\nabla_{u}(fw) = (uf)w + f\nabla_{u}w$$

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$$D_u v = (uv^j) \frac{\partial}{\partial x^j} = \left( u^i \frac{\partial v^j}{\partial x^i} \right) \frac{\partial}{\partial x^j}$$

That is, if

$$u = \sum_{j=1}^{n} u^{j} \frac{\partial}{\partial x^{j}}, \quad v = \sum_{j=1}^{n} v^{j} \frac{\partial}{\partial x^{j}}$$

then

$$D_{u}v = \sum_{i,j=1}^{n} \left( u^{i} \frac{\partial v^{j}}{\partial x^{i}} \right) \frac{\partial}{\partial x^{j}}$$

That is, if

$$v = v^j \frac{\partial}{\partial x^j}$$

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May then define an affine connection  $\nabla$  on M by  $\nabla_u v = (D_u v)^{\parallel}$  **Theorem.** Let g be a Riemannian metric on M.

• 
$$\nabla_v w - \nabla_w v = [v, w]$$

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 and

•  $ug(v,w) = g(\nabla_u v,w) + g(v,\nabla_u w).$ 

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$$\mathcal{T}_{\nabla}(v,w) := \nabla_v w - \nabla_w v - [v,w]$$

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$$(\nabla g)(u, v, w) := ug(v, w) - g(\nabla_u v, w) - g(v, \nabla_u w)$$

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 and

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$$\nabla_u g(v, w) = g(\nabla_u v, w) + g(v, \nabla_u w).$$

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 and

•  $ug(v,w) = g(\nabla_u v,w) + g(v,\nabla_u w).$ 

### **Proof.**

$$ug(v,w) = g(\nabla_u v, w) + g(v, \nabla_u w)$$

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$$u \mathbf{g}(v, w) + v \mathbf{g}(w, u) - w \mathbf{g}(u, v) =$$

$$g(\nabla_u v, w) + g(v, \nabla_u w) + g(\nabla_v w, u)$$

$$+g(w, 
abla_v u) - g(
abla_w u, v) - g(u, 
abla_w v)$$

$$ug(v, w) + vg(w, u) - wg(u, v) =$$
$$g(\nabla_u v, w) + g(v, \nabla_u w) + g(\nabla_v w, u)$$

$$+g(w,\nabla_{v}u)-g(\nabla_{w}u,v)-g(u,\nabla_{w}v)$$

#### **Proof.** Torsion-free:

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$$g(\nabla_u v, w) + g(v, \nabla_u w) + g(u, \nabla_v w)$$

$$+g(w,\nabla_v u) - g(v,\nabla_w u) - g(u,\nabla_w v)$$

$$ug(v, w) + vg(w, u) - wg(u, v) =$$
$$g(\nabla_u v, w) + g(v, [u, w]) + g(u, [v, w])$$
$$+g(w, \nabla_v u)$$

$$ug(v, w) + vg(w, u) - wg(u, v) =$$
$$g(\nabla_u v, w) + g(v, [u, w]) + g(u, [v, w])$$
$$+g(w, [v, u]) + g(w, \nabla_u v)$$

$$ug(v, w) + vg(w, u) - wg(u, v) =$$

$$2g(w, \nabla_u v) + g(v, [u, w]) + g(u, [v, w])$$

$$-g(w, [u, v])$$

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$$2g(w, \nabla_u v) - g(v, [w, u]) + g(u, [v, w])$$

$$-g(w, [u, v])$$

$$2g(w, \nabla_u v) = ug(v, w) + vg(w, u) - wg(u, v) +g(v, [w, u]) + g(w, [u, v]) - g(u, [v, w])$$

$$g(w, \nabla_u v) = \frac{1}{2} \Big[ ug(v, w) + vg(w, u) - wg(u, v) \\ + g(v, [w, u]) + g(w, [u, v]) - g(u, [v, w]) \Big]$$