MAT 552

Introduction to

Lie Groups and Lie Algebras

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Definition. A Lie group G is a smooth manifold that is also equipped with a group structure,

• The group multiplication operation

 $\begin{array}{rrr} \mathsf{G}\times\mathsf{G} &\longrightarrow \;\mathsf{G} \\ (\mathsf{a},\;\mathsf{b}) &\mapsto \;\mathsf{ab} \end{array}$

is a smooth map; and

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I'll typically denote identity element by $e \in G$.

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So as $\mathbf{a} \in \mathbf{G}$ varies, we get an isomorphism $\mathbf{G} \times T_{\mathbf{e}}\mathbf{G} \longrightarrow T\mathbf{G}.$

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$$\mathfrak{g}=T_{\mathsf{e}}\mathsf{G}.$$

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Thus, we have now shown that every Lie group G has an associated Lie algebra \mathfrak{g} , with underlying vector space $T_{e}G$.

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Definition. The Lie algebra \mathfrak{g} of the Lie group G is by definition

 $\mathfrak{g} = \{ \text{left-invariant vector fields on } \mathsf{G} \}.$

 $\mathfrak{g} = \mathfrak{gl}(n, \mathbb{R}) = \{n \times n \text{ real matrices } \mathsf{A}\}$ equipped with the operation [,] defined by $[\mathsf{A}, \mathsf{B}] = \mathsf{A}\mathsf{B} - \mathsf{B}\mathsf{A}.$

As a vector space, the tangent space of $\mathbf{GL}(n, \mathbb{R})$ at $\mathbf{e} = \mathbf{I}$ can of course be identified with

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because $\mathbf{GL}(n, \mathbb{R})$ is an open set in the $n \times n$ real matrices. But there is still something to check, because this doesn't tell us what the bracket operation is!

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Coordinatize $\mathbf{GL}(n, \mathbb{R})$ by $Y = \begin{bmatrix} Y_1^1 \cdots Y_n^1 \\ \vdots & \vdots \\ Y_1^n \cdots Y_n^n \end{bmatrix}.$

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Left-invariant vector fields:

$$Y_j^k \mathsf{A}_i^j \frac{\partial}{\partial Y_i^k}$$

with value at the matrix Y given by matrix YA.

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 $\left[Y_{j}^{k}\mathsf{A}_{i}^{j}\frac{\partial}{\partial Y_{i}^{k}},Y_{b}^{c}\mathsf{B}_{a}^{b}\frac{\partial}{\partial Y_{a}^{c}}\right]$

$$\left[Y_{j}^{k}\mathsf{A}_{i}^{j}\frac{\partial}{\partial Y_{i}^{k}},Y_{b}^{c}\mathsf{B}_{a}^{b}\frac{\partial}{\partial Y_{a}^{c}}\right] = Y_{j}^{k}\mathsf{A}_{i}^{j}(\delta_{k}^{c}\delta_{b}^{i})\mathsf{B}_{a}^{b}\frac{\partial}{\partial Y_{a}^{c}} - Y_{b}^{c}\mathsf{B}_{a}^{b}(\delta_{c}^{k}\delta_{j}^{a})\mathsf{A}_{i}^{j}\frac{\partial}{\partial Y_{i}^{k}}$$

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$$\begin{split} \left[Y_{j}^{k}\mathsf{A}_{i}^{j}\frac{\partial}{\partial Y_{i}^{k}}, Y_{b}^{c}\mathsf{B}_{a}^{b}\frac{\partial}{\partial Y_{a}^{c}} \right] &= Y_{j}^{k}\mathsf{A}_{i}^{j}(\delta_{k}^{c}\delta_{b}^{i})\mathsf{B}_{a}^{b}\frac{\partial}{\partial Y_{a}^{c}} - Y_{b}^{c}\mathsf{B}_{a}^{b}(\delta_{c}^{k}\delta_{j}^{a})\mathsf{A}_{i}^{j}\frac{\partial}{\partial Y_{i}^{k}} \\ &= Y_{j}^{k}\mathsf{A}_{b}^{j}\mathsf{B}_{a}^{b}\frac{\partial}{\partial Y_{a}^{k}} - Y_{b}^{k}\mathsf{B}_{a}^{b}\mathsf{A}_{i}^{a}\frac{\partial}{\partial Y_{i}^{k}} \\ &= Y_{j}^{k}\mathsf{A}_{\ell}^{j}\mathsf{B}_{\ell}^{\ell}\frac{\partial}{\partial Y_{i}^{k}} - Y_{j}^{k}\mathsf{B}_{\ell}^{j}\mathsf{A}_{\ell}^{\ell}\frac{\partial}{\partial Y_{i}^{k}} \\ &= Y_{j}^{k}[\mathsf{A},\mathsf{B}]_{i}^{j}\frac{\partial}{\partial Y_{i}^{k}} \end{split}$$

$$\begin{bmatrix} Y_{j}^{k} A_{i}^{j} \frac{\partial}{\partial Y_{i}^{k}}, Y_{b}^{c} B_{a}^{b} \frac{\partial}{\partial Y_{a}^{c}} \end{bmatrix} = Y_{j}^{k} A_{i}^{j} (\delta_{k}^{c} \delta_{b}^{i}) B_{a}^{b} \frac{\partial}{\partial Y_{a}^{c}} - Y_{b}^{c} B_{a}^{b} (\delta_{c}^{k} \delta_{j}^{a}) A_{i}^{j} \frac{\partial}{\partial Y_{i}^{k}} \\ = Y_{j}^{k} A_{b}^{j} B_{a}^{b} \frac{\partial}{\partial Y_{a}^{k}} - Y_{b}^{k} B_{a}^{b} A_{i}^{a} \frac{\partial}{\partial Y_{i}^{k}} \\ = Y_{j}^{k} A_{\ell}^{j} B_{\ell}^{\ell} \frac{\partial}{\partial Y_{i}^{k}} - Y_{j}^{k} B_{\ell}^{j} A_{\ell}^{\ell} \frac{\partial}{\partial Y_{i}^{k}} \\ = Y_{j}^{k} [A, B]_{i}^{j} \frac{\partial}{\partial Y_{i}^{k}} \end{bmatrix}$$
QED

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This now also gives us the right to also represent Lie algebras of Lie subgroups $G \subset \mathbf{GL}(n, \mathbb{R})$ as Lie algebras of matrices...