#### MAT 531

Geometry/Topology II

Introduction to Smooth Manifolds

Claude LeBrun Stony Brook University

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Let's not confuse one twin for the other!

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# In fact, ∃ contravariant functor from category ({vector spaces over $\mathbb{R}$ }, { $\mathbb{R}$ -linear maps}) to itself, given by $\mathbb{V} \leadsto \mathbb{V}^*$ . Namely, if $A: \mathbb{V} \to \mathbb{W}$ any linear map, $\exists$ adjoint map $A^*: \mathbb{W}^* \to \mathbb{V}^*$ , defined by $(A^*\varphi)(\mathbf{v}) = \varphi(A(\mathbf{v})).$ $\mathbb{V}^* \stackrel{A^*}{\longleftarrow} \mathbb{W}^*$ $\mathbb{V} \xrightarrow{A} \mathbb{W}$

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$$(B \circ A)^* = A^* \circ B^*$$

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So  $\mathbb{V}$  and  $\mathbb{V}^*$  are like mirror images.

Or mirror twins!

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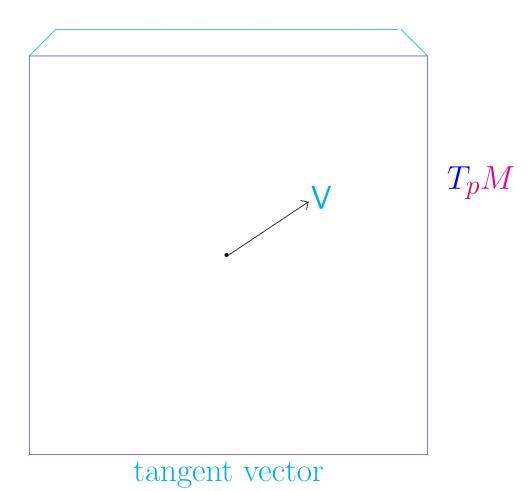
Elements  $\varphi \in T_p^*M$  are called covectors.

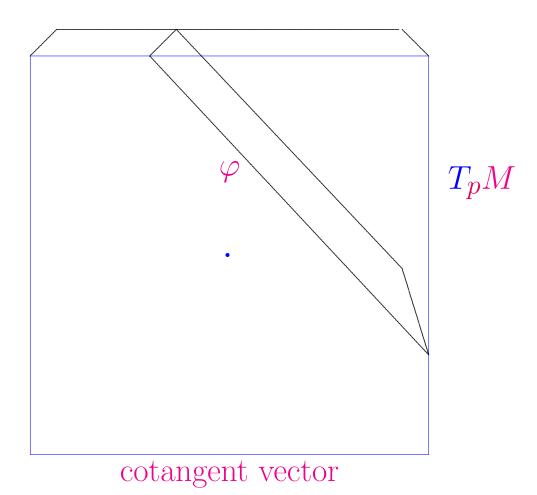
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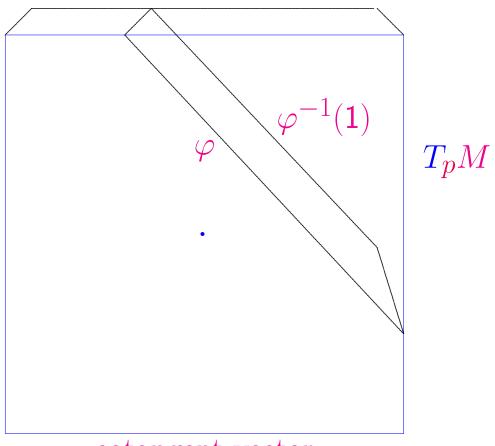
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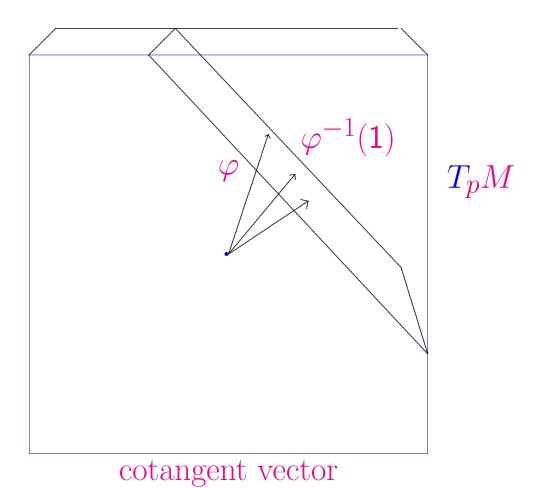
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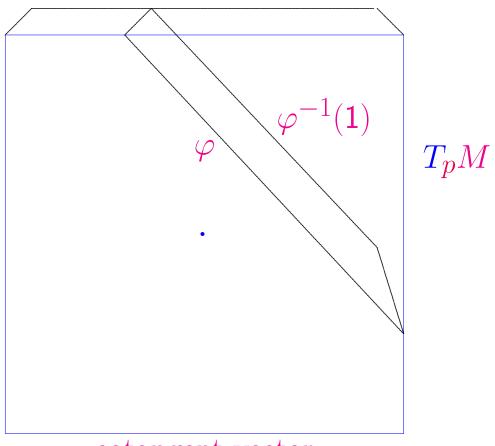




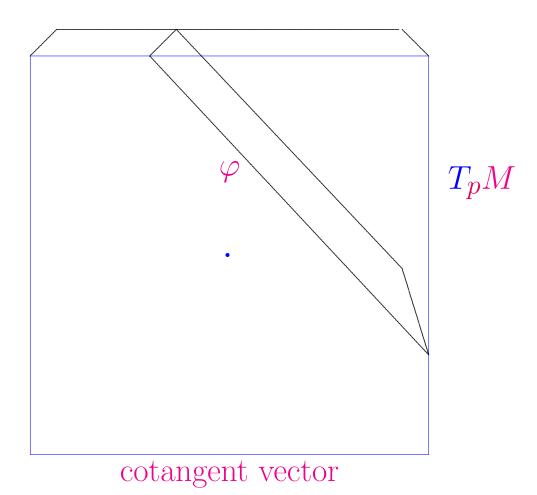


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Zero covector  $\leftrightarrow \varnothing$ : "hyperplane at infinity."

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when p is clear from context.

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Thus, for  $v \in T_pM$ , we have

$$(df)(v) := vf.$$

$$dx^1, \dots, dx^n \in T_p^*M$$

provide a basis for  $T_p^*M$ .

Exactly dual basis of coordinate basis for  $T_pM$ :

$$(dx^{j})\left(\frac{\partial}{\partial x^{k}}\right) = \delta_{k}^{j} = \begin{cases} 1 & \text{if } j = k, \\ 0 & \text{if } j \neq k. \end{cases}$$

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In particular, df is linear combination of  $dx^{j}$ :

$$df = \frac{\partial f}{\partial x^1} dx^1 + \dots + \frac{\partial f}{\partial x^n} dx^n$$

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Why? Taylor expansion allows one to prove that

$$\mathscr{I}_{p}^{2} = \{ f \in C^{\infty}(M) \mid f(p) = 0, (df)_{p} = 0 \}.$$

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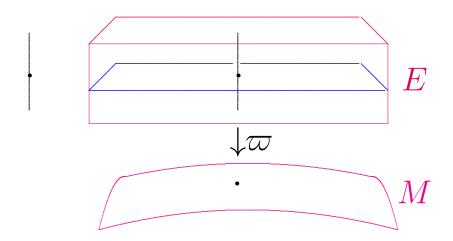
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can be made into a rank n vector bundle over  $M^n$ .

A smooth rank-k vector bundle over M is

- a smooth (n + k)-manifold E;
- a smooth map  $\varpi : E \to M$ ; and
- a real vector space structure on every "fiber"

$$E_p := \varpi^{-1}(p);$$

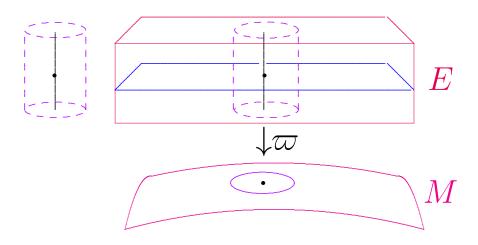


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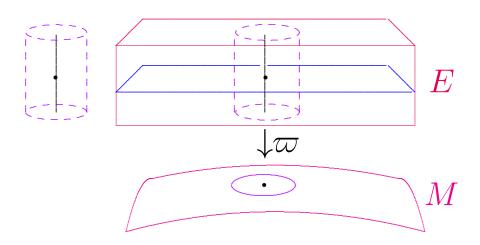
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**Key observation.** If  $(x^1, \ldots, x^n)$  are coordinates on an open set  $U \subset M$ , then

$$T^*U \cong U \times \mathbb{R}^n$$

by using  $dx^1, \ldots, dx^n$  as basis for  $T_p^*M, \forall p \in U$ .

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$$U_{\beta} \times \mathbb{R}^k \ni (p, \mathbf{v}) \sim (p, \tau_{\alpha\beta}(p)\mathbf{v}) \in U_{\alpha} \times \mathbb{R}^k \quad \forall p \in U_{\alpha} \cap U_{\beta}.$$

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$$\begin{bmatrix} \frac{\partial y^1}{\partial x^1} & \cdots & \frac{\partial y^n}{\partial x^1} \\ \vdots & & \vdots \\ \frac{\partial y^1}{\partial x^n} & \cdots & \frac{\partial y^n}{\partial x^n} \end{bmatrix} = \mathcal{J}^t$$

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Thus, if

$$\tau_{\alpha\beta}: U_{\alpha} \cap U_{\beta} \xrightarrow{C^{\infty}} \mathbf{GL}(n, \mathbb{R})$$

is the system of transition functions used to build TM from a coordinate atlas for  $M^n$ , and if

$$\tilde{\tau}_{\alpha\beta}: U_{\alpha} \cap U_{\beta} \xrightarrow{C^{\infty}} \mathbf{GL}(n, \mathbb{R})$$

is the system of transition functions used to build  $T^*M$ , then one system is obtained from the other by taking the transpose-inverses:

$$\tilde{\tau}_{\alpha\beta} = \left[ \left( \tau_{\alpha\beta} \right)^t \right]^{-1}$$
.