

MAT 531

Geometry/Topology II

Introduction to Smooth Manifolds

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Lie derivatives:

Lie derivative of tensor field φ w/resp. to V :

Lie derivatives:

φ

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$$\Phi_t^* \varphi$$

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But there is a more efficient formula!

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$$(V \lrcorner \psi)(_, \dots, _) := \psi(V, _, \dots, _).$$

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For example, if $\varphi \in \Omega^1(M)$,

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$$\mathcal{L}_V \varphi = V \lrcorner d\varphi + d(V \lrcorner \varphi).$$

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In these coordinates, the flow Φ_t of V is given by

$$\Phi_t(x^1, \dots, x^n) = (x^1 + t, \dots, x^n),$$

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Proof. Near any point where $V \neq 0$, choose coordinates in which $V = \frac{\partial}{\partial x^1}$.

In these coordinates, the flow Φ_t of V is given by

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$$\mathcal{L}_V \left(\sum \varphi_I dx^I \right) = \sum \frac{\partial \varphi_I}{\partial x^1} dx^I.$$

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$$\mathcal{L}_V \varphi = V \lrcorner d\varphi + d(V \lrcorner \varphi).$$

Proof. Now, consider the special case

$$\varphi = f(x^1, \dots, x^n) dx^{i_1} \wedge \dots \wedge dx^{i_k}$$

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Exercise: RHS is actually bilinear over $C^\infty(M)$...

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Induction!

Orientations.

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The group $\mathbf{GL}(n, \mathbb{R})$ of invertible $n \times n$ matrices

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Definition. *A smooth n -manifold*

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