## MAT 531

Geometry/Topology II

# Introduction to Smooth Manifolds 

Claude LeBrun
Stony Brook University
April 2, 2020

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This map is called the flow of $V$.

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Notice that

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\Phi_{-t}=\left(\Phi_{t}\right)^{-1}
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When $V$ not compactly supported, "flow" only defined on neighborhood of $M \times\{0\} \subset M \times \mathbb{R}$ :

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where dashed arrow means "not defined everywhere."

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Remark. Of course, since $\frac{\partial}{\partial x^{1}} \neq 0$ everywhere, this can actually be done if and only if $V(p) \neq 0$ !

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Inverse function theorem: local diffeo near $p$. Introduce local coordinates $\left(x^{2}, \ldots, x^{n}\right)$ on $N$, set $x^{1}=t$ on $\mathbb{R}$, pull back to $\mathscr{U} \subset M$ via $F^{-1}$.

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However, $\Phi_{t}^{*} W=W \forall t \Longleftrightarrow[V, W]=0$.

Corollary. Let $V, W \in \mathfrak{X}(M)$,

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V=\frac{\partial}{\partial x^{1}} \quad \text { and } \quad W=\frac{\partial}{\partial x^{2}}
$$

