

MAT303: Calc IV with applications

Lecture 14 - March 24 2021

Last time:

$my'' + cy' + ky = f(t)$
 in terms of mass-spring systems

mass m
 resistance c
 spring constant k
 external force $f(t)$

- When $f(t) = 0$, saw that there are 3 regimes, depending on whether $c < 4km$:
 - Underdamped
 - Critically damped
 - Overdamped

Today:

- Solving nonhomogeneous linear DEs

Principle of superposition for homogeneous linear equations:

If y_1 and y_2 are solutions to

$$ay'' + by' + cy = 0$$

Then $Ay_1 + By_2$ is also a solution.

Principle of superposition for homogeneous equations

Let y_1 and y_2 be solutions to $ay'' + by' + cy = 0$. Then $Ay_1 + By_2$ is also a solution.

Proof: Let $y = Ay_1 + By_2$. Then $y'' = Ay_1'' + By_2''$, $y' = Ay_1' + By_2'$, and $y = Ay_1 + By_2$. Substituting into the equation:

$$a(Ay_1'' + By_2'') + b(Ay_1' + By_2') + c(Ay_1 + By_2) = A(ay_1'' + by_1' + cy_1) + B(ay_2'' + by_2' + cy_2) = A \cdot 0 + B \cdot 0 = 0$$

Using operator notation:

Let $Ly = ay'' + by' + cy$
 if $Ly_1 = 0$ and $Ly_2 = 0$

Then

$$L(Ay_1 + By_2) = L(Ay_1) + L(By_2) = A Ly_1 + B Ly_2 = A \cdot 0 + B \cdot 0 = 0$$

Principle of superposition for non-homogeneous linear equations:

If y_1 is a solution to

$$ay'' + by' + cy = f_1(x)$$

and y_2 is a solution to

$$ay'' + by' + cy = f_2(x)$$

Then $Ay_1 + By_2$ is a solution to

$$ay'' + by' + cy = Af_1(x) + Bf_2(x)$$

Proof: $Ly_1 = f_1$, $Ly_2 = f_2$

so

$$L(Ay_1 + By_2) = L(Ay_1) + L(By_2) = A Ly_1 + B Ly_2 = A f_1 + B f_2$$

How do we deal with external force, e.g.

$$y'' - 4y = 2e^{3x}?$$

Recall (lecture 11)

THEOREM 5 Solutions of Nonhomogeneous Equations

Let y_p be a particular solution of the nonhomogeneous equation in (2) on an open interval I where the functions p_i and f are continuous. Let y_1, y_2, \dots, y_n be linearly independent solutions of the associated homogeneous equation in (3). If Y is any solution whatsoever of Eq. (2) on I , then there exist numbers c_1, c_2, \dots, c_n such that

$$Y(x) = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x) + y_p(x) \quad (16)$$

for all x in I .

Roughly speaking:

- All solutions are of the form $Y(x) = y_c + y_p$ where y_c is a solution to the homogeneous version of the equation.

complementary solution

Solution:

① Solution to homogeneous version:

$$y'' - 4y = 0$$

\Rightarrow characteristic eqn is $r^2 - 4 = 0$

$$y = C_1 e^{2x} + C_2 e^{-2x}$$

$$r = \pm 2$$

② Find a particular solution:

Guess $y = A e^{3x}$, sub into eqn.

solve for A

$$9A e^{3x} - 4A e^{3x} = 2e^{3x}$$

$$\text{So } 5A = 2. \quad \text{So } A = \frac{2}{5}$$

$$\text{So } y_p = \frac{2}{5} e^{3x}$$

③ General solution $y_c + y_p$

$$y = C_1 e^{2x} + C_2 e^{-2x} + \frac{2}{5} e^{3x}$$

How do we deal with external force, e.g.

$$y'' + 3y' + 4y = 3x + 2?$$

Recall (lecture 11)

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Roughly speaking:

- All solutions are of the form $Y(x) = y_c + y_p$
where y_c is a solution to the homogeneous version of the equation.

Solution:

① Solution to homogeneous version:

$$r^2 + 3r + 4 = 0 \Rightarrow r = \frac{-3 \pm \sqrt{9 - 16}}{2}$$

$$r = \frac{-3 \pm \sqrt{7}i}{2}$$

$$y_c = e^{-\frac{3}{2}x} \left(C_1 \cos \frac{\sqrt{7}}{2}x + C_2 \sin \frac{\sqrt{7}}{2}x \right)$$

② Find a particular solution:

Guess $y = Ax + B$, plug in, solve:

$$0 + \underline{3A} + \underline{4Ax + B} = \underline{3x + 2}$$

$$\Rightarrow 4A = 3 \Rightarrow A = \frac{3}{4} \Rightarrow \frac{3}{4}x + B = 2 \Rightarrow B = \frac{5}{4}$$

③ General solution $y_c + y_p$

$$y = e^{-\frac{3}{2}t} \left(C_1 \cos \frac{\sqrt{7}}{2}t + C_2 \sin \frac{\sqrt{7}}{2}t \right) + \frac{3}{4}x - \frac{1}{4}$$

How do we deal with external force, e.g.

$$3y'' + 3y' - 2y = 2 \cos x?$$

Take guess to be
linear comb of
 f and all of its
derivatives

Recall (lecture 11)

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$$Y(x) = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x) + y_p(x) \quad (16)$$

for all x in I .

Roughly speaking:

- All solutions are of the form $Y(x) = y_h + y_p$
where y_h is a solution to the homogeneous version of the equation.

① Solution to homogeneous version:
Solution:

$$y_c = \underline{\hspace{2cm}}$$

② Find a particular solution:

Guess $y = A \cos x$, plug in, solve:

$$-3A \cos x - 3A \sin x - 2A \cos x = 2 \cos x$$

Doesn't work. No sin on RHS.

Instead guess $y = A \cos x + B \sin x$

$$\begin{aligned} & \underline{-3A \cos x} - \underline{3A \sin x} - \underline{2A \cos x} \\ & \underline{-3B \sin x} + \underline{3B \cos x} - \underline{2B \sin x} = 2 \cos x \end{aligned}$$

i.e.

$$\begin{aligned} -3A - 2A + 3B &= 2 & -5A + 3B &= 2 \\ -3A - 3B - 2B &= 0 & \Rightarrow -3A - 5B &= 0 \end{aligned}$$

$$\Rightarrow \begin{pmatrix} -5 & 3 \\ -3 & -5 \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

③ General solution $y_c + y_p$:

$$y = y_c + A \cos x + B \sin x.$$

How do we deal with external force, e.g.

$$y'' - 4y = 2e^{2x}?$$

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Roughly speaking:

- All solutions are of the form $Y(x) = y_h + y_p$
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Solution:

① Solution to homogeneous version:

$$y'' - 4y = 0$$

\Rightarrow characteristic eqn is $r^2 - 4 = 0$
 $r = \pm 2$

$$y_h = C_1 e^{2x} + C_2 e^{-2x}$$

② Find a particular solution:

Guess $y = A e^{2x}$, sub into eqn.

solve for A

$$y'' - 4y = 4A e^{2x} - 4A e^{2x} = 0 \neq 2e^{2x}$$

when guess is a homogeneous soln, it's
the wrong guess.

instead, guess $y = Ax e^{2x}$, $y' = Ae^{2x} + 2Ae^{2x}x$

$$\begin{aligned} y'' - 4y &= 2Ae^{2x} + 2Ae^{2x}x + 4Ae^{2x}x - 4Ae^{2x}x = 2e^{2x} \\ &= 4Ae^{2x} = 2e^{2x} \Rightarrow A = 1/2. \end{aligned}$$

③ General solution $y_h + y_p$:

$$y = C_1 e^{2x} + C_2 e^{-2x} + \frac{1}{2} x e^{2x}$$

$$ay'' + by' + cy = f$$

Assume that only finitely many linearly independent functions appears in the sequence f, f', f'', f''', \dots

RULE 1 Method of Undetermined Coefficients

Suppose that no term appearing either in $f(x)$ or in any of its derivatives satisfies the associated homogeneous equation $Ly = 0$. Then take as a trial solution for y_p a linear combination of all linearly independent such terms and their derivatives. Then determine the coefficients by substitution of this trial solution into the nonhomogeneous equation $Ly = f(x)$.

To solve constant coefficient linear differential equation $ay'' + by' + cy = f(x)$,

1. Find the homogeneous (i.e. complementary) solutions y_c
2. Check that f and its derivatives don't satisfy the homogeneous equation
3. Determine y_p by guessing $y_p =$ linear combination of f and its derivatives, and solve for coefficients
4. General solution is $y_c + y_p$

E.g.
 $f = e^{kx}$
 $f' = ke^{kx}$
 $f'' = k^2 e^{kx}$

$$\rightarrow y = e^{kx}$$

E.g.
 $f = \cos x$
 $f' = -\sin x$
 $f'' = -\cos x$

$$\rightarrow y = A \cos x + B \sin x$$

E.g.
 $f = xe^x$
 $f' = e^x + xe^x$
 $f'' = e^x + e^x + xe^x = 2e^x + xe^x$

$$\rightarrow y = Axe^x + Be^x$$

$$= 2(f' - f) + f = 2f' - f$$

- Examples:
- $y'' - 4y = 2e^{3x}$? $y_p = Ae^{3x}$
 - $y'' + 3y' + 4y = 3x + 2$ $y = Ax + B$
 - $3y'' + 3y' - 2y = 2 \cos x$ $y = A \cos x + B \sin x$
 - $y'' - 4y = 2e^{2x}$ \times doesn't work.

$$y = A(3x+2) + B3$$

$$= 3A + 2A + 3B$$

$$6 = 59$$

How to deal with this situation?

$$y'' - 4y = 2e^{2x}.$$

Want to take $y_p = Ae^{2x}$ as trial solution, but it's a solution to the homogeneous equation.

Solution: Multiply trial solution by x .

$$y_c = Ae^{2x} + Be^{-2x}$$

In general:

Assume that only finitely many linearly independent functions appears in the sequence f, f', f'', f''', \dots

RULE 2 Method of Undetermined Coefficients

If the function $f(x)$ is of either form in (14), take as the trial solution

$$y_p(x) = x^s[(A_0 + A_1x + A_2x^2 + \dots + A_mx^m)e^{rx} \cos kx + (B_0 + B_1x + B_2x^2 + \dots + B_mx^m)e^{rx} \sin kx], \quad (15)$$

where s is the smallest nonnegative integer such that no term in y_p duplicates a term in the complementary function y_c . Then determine the coefficients in Eq. (15) by substituting y_p into the nonhomogeneous equation.

Translation: keep multiplying trial solution by x until it's no longer a solution to the homogeneous equation.

Consider the equation

$$y'' + y = \tan(x).$$

Homogeneous solutions:

$$y = A \cos(x) + B \sin(x)$$

Unfortunately, the sequence f, f', f'', \dots has infinitely many linearly independent terms.

$$\sec^2 x, \quad 2 \sec^2 x \tan x, \quad 4 \sec^2 x \tan^2 x + 2 \sec^4 x, \quad \dots$$

i.e. The vector space spanned by f and its derivatives is infinite dimensional.

We can't use method of undetermined coefficients.

Variation of parameters

Want to solve $y'' + Py' + Qy = f(x)$

$$\underbrace{\hspace{10em}}_{Ly}$$

Want $Ly = f$

Key ideas:

- Guess $y_p = u_1 y_1 + u_2 y_2$ where y_1, y_2 are the homogeneous solutions.

Plug this into $L[y_p] = f(x)$ and see what this tells us about u_1, u_2 .

- We are free to make one more additional constraint to make our computation easier

(1) $y_p = u_1 y_1 + u_2 y_2$ prod. rule

(2) $\Rightarrow y_p' = (u_1 y_1' + u_2 y_2') + \underbrace{(u_1' y_1 + u_2' y_2)}$

Assume $\underbrace{(u_1' y_1 + u_2' y_2)} = 0$.

(3) $y_p'' = u_1 y_1'' + u_2 y_2'' + u_1' y_1' + u_2' y_2'$

(4) Since $\text{For } i=1,2$ $y_i'' + P y_i' + Q y_i = 0$

$$\Rightarrow y_i'' = -P y_i' - Q y_i$$

Therefore.

$$y_p'' + P y_p' + Q y_p = u_1' y_1' + u_2' y_2'$$

i.e. $L[y_p] = \begin{matrix} u_1' y_1' + u_2' y_2' \\ (u_1' y_1 + u_2' y_2) = 0 \end{matrix} = f$

$$\Rightarrow \begin{pmatrix} y_1' & y_2' \\ y_1 & y_2 \end{pmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}$$



THEOREM 1 Variation of Parameters

If the nonhomogeneous equation $y'' + P(x)y' + Q(x)y = f(x)$ has complementary function $y_c(x) = c_1y_1(x) + c_2y_2(x)$, then a particular solution is given by

$$y_p(x) = -y_1(x) \int \frac{y_2(x)f(x)}{W(x)} dx + y_2(x) \int \frac{y_1(x)f(x)}{W(x)} dx, \quad (33)$$

where $W = W(y_1, y_2)$ is the Wronskian of the two independent solutions y_1 and y_2 of the associated homogeneous equation.

For our example:

$$y_1 = \cos x$$

$$y_2 = \sin x$$

$$f(x) = \tan x.$$

$$y_p =$$

See textbook, last ex.

Consider a system of two linear equations in two variables.

$$\begin{aligned} a_1x + b_1y &= c_1 \\ a_2x + b_2y &= c_2 \end{aligned}$$

The solution using Cramer's Rule is given as

$$x = \frac{D_x}{D} = \frac{\begin{vmatrix} c_1 & b_1 \\ c_2 & b_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}, D \neq 0; \quad y = \frac{D_y}{D} = \frac{\begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix}}{\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}}, D \neq 0.$$

$$\begin{pmatrix} y_1 & y_2 \\ y_1' & y_2' \end{pmatrix} \begin{pmatrix} u_1' \\ u_2' \end{pmatrix} = \begin{pmatrix} f \\ 0 \end{pmatrix}$$

Solve is

$$u_1' = \frac{fy_2}{y_1'y_2 - y_1y_2'}, \quad u_2' = \frac{-fy_1}{y_1'y_2 - y_1y_2'}$$

$$u_1' = \frac{-fy_2}{W(y_1, y_2)}, \quad u_2' = \frac{fy_1}{W(y_1, y_2)}$$

$$u_1 = \int \frac{-fy_2}{W(y_1, y_2)} dx, \quad u_2 = \int \frac{fy_1}{W(y_1, y_2)} dx$$

$$y_p = u_1y_1 + u_2y_2.$$

Back to our example:

$$y'' + y = \tan(x).$$

Homogeneous solutions:

$$y_1 = \cos(x), y_2 = \sin(x)$$

$$ay'' + by' + cy = f.$$

$\underbrace{\hspace{10em}}_{Ly}$

Why does method of undetermined coefficients work?

Assume that only finitely many linearly independent functions appears in the sequence f, f', f'', f''', \dots

RULE 1 Method of Undetermined Coefficients

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Need to explain why $y_p = C_0f + C_1f' + C_2f'' + \dots + C_nf^{(n)}$

Proof sketch:

- Let V be the vector space spanned by f, f', f'', f''', \dots

We are assuming that V is finite dimensional.

- Then L is a linear operator $V \rightarrow V$.
- By the rank nullity theorem from linear algebra, one of the two possibilities always holds:
 - $Lg = 0$ for some $g \in V$, i.e. $\dim(\ker L) > 0$.
 - $Lg = h$ always has a solution $g \in V$.

- Therefore, if we assume that the first doesn't hold, then the second must hold.

What about rule 2?

RULE 2 Method of Undetermined Coefficients

If the function $f(x)$ is of either form in (14), take as the trial solution

$$y_p(x) = x^s [(A_0 + A_1x + A_2x^2 + \dots + A_mx^m)e^{rx} \cos kx + (B_0 + B_1x + B_2x^2 + \dots + B_mx^m)e^{rx} \sin kx], \quad (15)$$

where s is the smallest nonnegative integer such that no term in y_p duplicates a term in the complementary function y_c . Then determine the coefficients in Eq. (15) by substituting y_p into the nonhomogeneous equation.

Need to explain why $y_p = x^s(C_0f + C_1f' + C_2f'' + \dots + C_nf^{(n)})$

Proof sketch:

- Let V be the vector space spanned by f, f', f'', f''', \dots

We are assuming that V is finite dimensional.

- Then L is a linear operator $V \rightarrow V$, and $\dim(\ker L) > 0$.
- Consider the vector space $W = \{x^s g : g \in V\}$.
 - Check: If s is small enough, $L : W \rightarrow V$.
 - Check: As s increases, $\dim(\ker L)$ decreases

- Therefore, if s is just right, $\dim(\ker L) = 0$ and so $Lg = h$ always a solution $g \in W$.