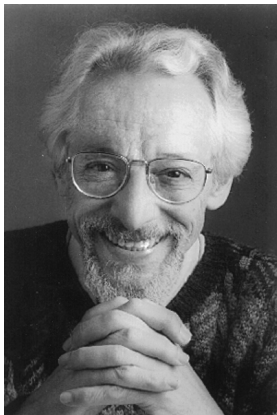


Reflections on the Early Mathematical Life of Bob Osserman



The Classical Theory of Minimal Surfaces

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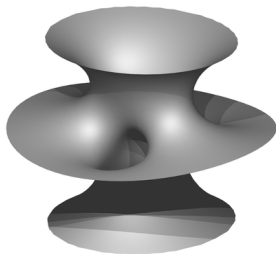
Riemann, Weierstrauss



The Classical Theory of Minimal Surfaces

Riemann, Weierstrauss

The Idea: Consider a smooth surface in Euclidean 3-space $\Sigma \subset \mathbf{E}^3$.



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Σ is called a **minimal surface**, if for every deformation Σ_t , ($\Sigma_0 = \Sigma$) in the interior, the area satisfies

$$A(\Sigma_t) \geq A(\Sigma).$$

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In particular we have:

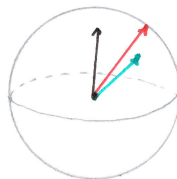
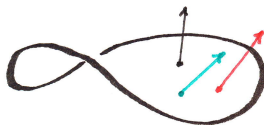
$$\left. \frac{d}{dt} A(\Sigma_t) \right|_{t=0} = 0.$$

A Geometric Characterization

THE GAUSS MAP

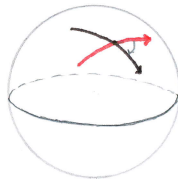
$$N : \Sigma \longrightarrow S^2$$

The Gauss map associates to each point $x \in \Sigma$, the normal vector $N(x)$ to Σ at x , i.e., the vector perpendicular to the tangent plane to Σ at x .



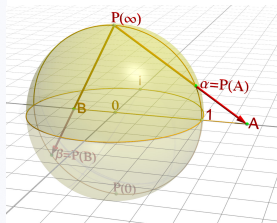
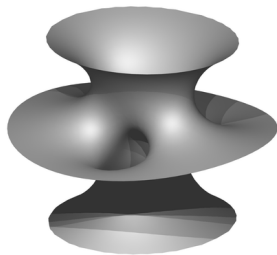
Σ is **minimal** if and only if the Gauss map is (anti)-**conformal**.

Angles are preserved (but direction is reversed).



Complex Analysis Enters the Picture

Take Stereographic Projection



Complex Analysis is

a rich and deep subject

with many beautiful results.

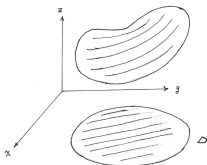
Elementary Question

Suppose our surface Σ is the graph of a function $z = f(x, y)$ over a domain D in the (x, y) -plane

When is this graph a minimal surface?

ANSWER: It must satisfy the differential equation

$$(1 + f_y^2)f_{xx} + (1 + f_x^2)f_{yy} - 2f_x f_y f_{xy} = 0.$$



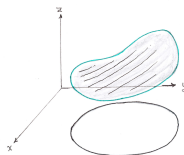
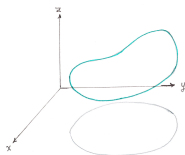
The Dirichlet Problem

Let D be the round disk of radius R .

Let φ be an arbitrary continuous function on the boundary circle.

Theorem. *There exists a unique function $f(x, y)$ continuous on D and smooth in its interior, such that $f = \varphi$ on ∂D and in the interior it satisfies the minimal surface equation:*

$$(1 + |\nabla f|^2)\Delta f - (\nabla f)^t \mathbf{H}(f) \nabla f = 0$$



The Bernstein Theorem

This gives us a wildly abundant family of minimal surfaces which are graphs over disks of radius R .

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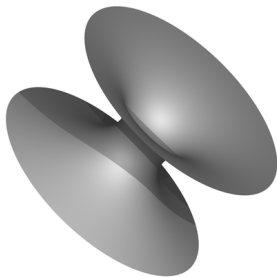
One would expect to produce many functions $f(x, y)$ defined over the entire (x, y) -plane and satisfying the M.S.Eqn.

Surprise!!

The Bernstein Theorem (1918). *Any solution of the minimal surface equation which is defined for all (x, y) in the plane must be is **linear**, i.e., its graph is an affine 2-plane.*

This is a beautiful and astonishing result.

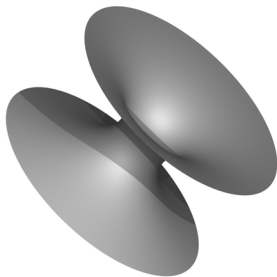
If we remove a tiny disk from the plane,
there is a function defined everywhere outside that disk
whose graph is a minimal surface.



This is also true if we remove a half-line from the plane,

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Is this a special case – a quirk of nature?

Or – is there something deeper hidden behind this result?

In 1959 Bob gave a wonderful geometric generalization
of Bernstein's Theorem.

In fact a significant body of his subsequent research
revolved around the mathematical questions
engendered by this initial result.

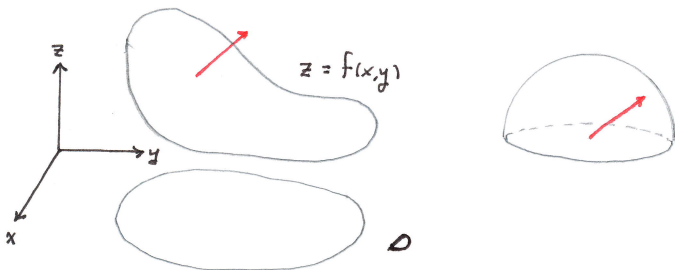
To understand his theorem
we must return to the **Gauss Map**.

Notice: If

$$\Sigma = \{(x, y, f(x, y)) : (x, y) \in D\}$$

is a the graph of a function, then

the image of the Gauss map lies in the **upper hemisphere**



Theorem (Osserman – 1959).

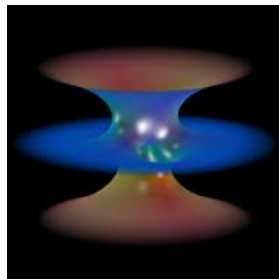
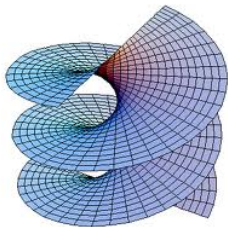
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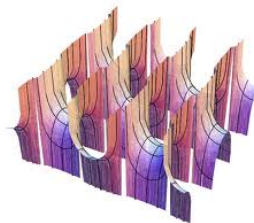
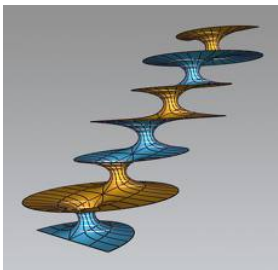
Complete means there is no curve of finite length in Σ which gets to the “end” or “boundary” of the surface (i.e., which exits every compact subset).

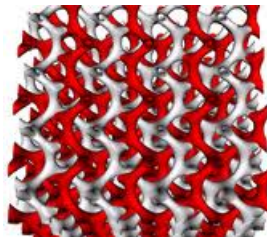
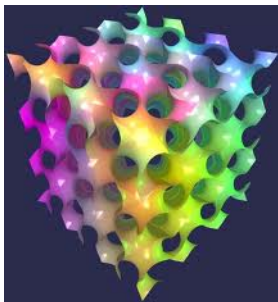
Theorem (Osserman – 1959).

Let $\Sigma \subset E^3$ be a complete minimal surface whose Gauss image misses a neighborhood of some point in S^2 . Then Σ is a plane.

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Idea of Proof.

By passing to the universal covering we can assume that Σ is parameterized (perhaps redundantly) by a conformal mapping

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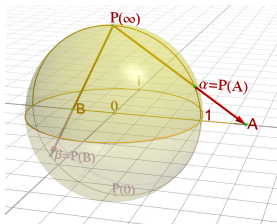
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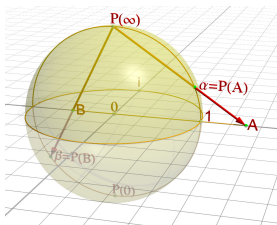
We may assume that N misses a neighborhood of the north pole.

Thus after stereographic projection,



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We are reduced to the case where R is conformally the unit disk.

Applying the Weierstrass Representation Theorem and a clever complex analysis argument, Bob Osserman showed that the induced metric could not be complete.

The argument boils down to the following assertion. Let $f : \Delta \rightarrow \mathbb{C}$ be a holomorphic function which is nowhere zero. Then the riemannian metric

$$ds^2 = |f(z)|^2 |dz|^2$$

is not complete. To see this set

$$F(z) \equiv \int_0^z f(\zeta) d\zeta.$$

By Liouville's Theorem there is a maximal disk $\{|w| < r\}$ of finite radius on which the inverse function $G(w) = F^{-1}(w)$ is defined (with $G(0) = 0$), and there is a point w_0 with $|w_0| = r$ such that G cannot be analytically continued into any neighborhood of w_0 .

Now the path $\Gamma = G(\{tw_0 : 0 \leq t < 1\})$ has finite length ($\leq r$) and must go to the boundary in Δ .

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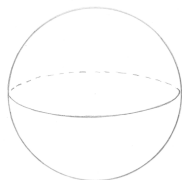
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Theorem (Osseman – 1961).

Let $\Sigma \subset E^3$ be a complete minimal surface whose Gauss image misses a set of positive logarithmic capacity in S^2 . Then Σ is a plane.

Gauss Curvature

Gauss curvature is a function $K : \Sigma \rightarrow \mathbb{R}$ which is characterized in several ways.



$$K > 0$$



$$K = 0$$



$$K < 0$$

On a minimal surface $K \leq 0$.

Theorem (Osserman – 1961).

Let $\Sigma \subset E^3$ be a complete minimal surface whose Gauss image misses a set of logarithmic capacity zero in S^2 . Then Σ is a plane.

Theorem (Osserman – 1964).

Let $\Sigma \subset E^3$ be a complete minimal surface.

1. Suppose $\int_{\Sigma} K dA = -\infty$, then the normals assume every direction infinitely often except for a set of logarithmic capacity zero.
2. Suppose $\int_{\Sigma} K dA$ is finite but not zero. Then the normals assume all but at most three directions.
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Conjectures of Nirenberg

Prior to Bob's first work on minimal surfaces, Louis Nirenberg made the following conjectures. They were based (I imagine) on taking seriously the analogy between the Gauss map of a complete minimal surface in $\mathbb{E}^3$ and a holomorphic function on $\mathbb{C}$.

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Conjecture 1 (Liouville-type theorem). If the Gauss map of a complete minimal surface in $\mathbb{E}^3$ misses a neighborhood of some point, the surface is a plane.

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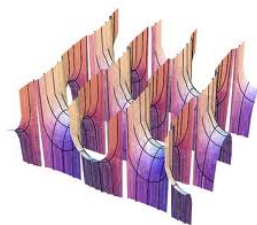
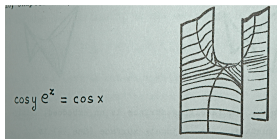
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Conjecture 1 (Liouville-type theorem). If the Gauss map of a complete minimal surface in $\mathbb{E}^3$ misses a neighborhood of some point, the surface is a plane.

(Proved by Bob)

Conjecture 2 (Picard-type theorem). If the Gauss map of a complete minimal surface in $\mathbb{E}^3$ misses three points, the surface is a plane.

(Proved to be **wrong** by Bob!)



Subsequent Spectacular Work

Theorem.(F. Xavier – 1982).

If the Gauss map of a complete minimal surface omits 7 points of the sphere, the surface is a plane

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Theorem.(Osserman and Mo – 1990).

If the Gauss map of a complete minimal surface assumes five distinct values only a finite number of times, then the surface has finite total curvature.

Minimal Surfaces in $\mathbb{E}^n$

Consider now a minimal surface

$$\Sigma \subset \mathbb{E}^n$$

for a general dimension $n \geq 3$.

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Suppose all the normals to Σ (at all points) make an angle $\geq \alpha > 0$ with respect to some fixed direction. Fix $x \in \Sigma$ and let d be the distance from x to the boundary of Σ . Then the Gauss curvature of Σ at x satisfies

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Corollary If Σ is complete and all the normals to Σ make an angle $\geq \alpha > 0$ with respect to some fixed direction, then Σ is a plane.

Minimal Surfaces in $\mathbb{E}^n$ – Another View

Let $\Sigma \subset \mathbb{E}^n$ be a minimal surface. Choosing isothermal coordinates $z = x + iy$ gives a local **conformal** parameterization

$$\psi : \Delta \longrightarrow \Sigma \subset \mathbb{E}^n.$$

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$$\varphi^2 = \sum_{k=1}^n \varphi_k^2 \equiv 0.$$

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Let $\Sigma \subset \mathbb{E}^n$ be a minimal surface. Choosing isothermal coordinates $z = x + iy$ gives a local **conformal** parameterization

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where $\psi = (\psi_1, \dots, \psi_n)$. Conformality is equivalent to

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Φ is the [Generalized Gauss Mapping](#).

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This was followed by a long collaboration of Hoffman and Osserman who obtained beautiful generalizations of many of the results I have discussed to more general surfaces in $\mathbb{E}^n$.

Graphs in $\mathbb{E}^n$

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What can one say about the Dirichlet problem for the minimal surface equation in $\mathbb{E}^n$?

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Consider the graph

$$\Gamma(f) = \{(x, f(x)) : x \in \Omega\} \subset \mathbb{E}^{p+q}$$

of a smooth function

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For functions f which are only Lipschitz these equations can be replaced by the requirement that the the area of the graph be stationary.

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Given a continuous function

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Theorem. (Allard – 1975)

Boundary regularity holds for solutions to the Dirichlet Problem.

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Theorem. (L and O – 1977)

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Regularity fails for solutions to the Dirichlet problem. There are Lipschitz solutions which are not C^1 .

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What happens in between?

The Simplest Case

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Theorem. (L and O)

The cone on the Hopf map

$$f(x) = \|x\| \varphi \left(\frac{x}{\|x\|} \right) \quad \text{for } \|x\| \leq 1$$

is the solution to the Dirichlet problem on the unit 4-disk D for boundary values φ on $\partial D = S^3$.

Reflections on the Early Mathematical Life of Bob Osserman

