

MAT 341 (HW 4 SOINS)

2.4

2) Here

$$f(x) = u(x, 0) = T_0 + T_1 \left(\frac{x}{a}\right)^2$$

$(0 < x < a)$

$$\begin{aligned} a_0 &= \frac{1}{a} \int_0^a f(x) dx \\ &= \frac{1}{a} \int_0^a \left(T_0 + \frac{T_1 x^2}{a^2} \right) dx \\ &= T_0 + \frac{1}{3} T_1 \end{aligned}$$

$$\begin{aligned} a_n &= \frac{2}{a} \int_0^a f(x) \cos\left(\frac{n\pi x}{a}\right) dx \\ &= \frac{2}{a} \int_0^a \left(T_0 \underbrace{\cos\left(\frac{n\pi x}{a}\right)}_{\substack{\swarrow \\ \text{Vanishes}}} \right) + \frac{T_1}{a^2} \underbrace{\left(\cos\left(\frac{n\pi x}{a}\right) x^2 \right)}_{\substack{\searrow \\ \text{Computed using} \\ \text{integration} \\ \text{by parts}}} dx \end{aligned}$$

$$= \frac{4T_1 \cos n\pi}{n^2 \pi^2}$$

So, $u(x, t) = \frac{3T_0 + T_1}{3} + \sum_{n=1}^{\infty} \frac{4T_1 \cos(n\pi)}{n^2 \pi^2} \cos\left(\frac{n\pi x}{a}\right) e^{-\frac{2}{a^2} n^2 \pi^2 t}$

$$\hookrightarrow f(x) = \begin{cases} T_1 & 0 < x < a/2 \\ T_2 & \frac{a}{2} < x < a \end{cases}$$

$$a_0 = \frac{1}{a} \int_0^a f(x) dx = \frac{1}{a} \int_0^{a/2} T_1 + \frac{1}{a} \int_{a/2}^a T_2$$

$$= \frac{T_1 + T_2}{2}$$

$$a_n = \frac{2}{a} \int_0^a f(x) \cos\left(\frac{n\pi x}{a}\right)$$

$$= \frac{2}{a} \int_0^{a/2} T_1 \cos\left(\frac{n\pi x}{a}\right) + \frac{2}{a} \int_{a/2}^a T_2 \cos\left(\frac{n\pi x}{a}\right)$$

$$= \frac{2}{n\pi} \left[T_1 \sin\left(\frac{n\pi}{2}\right) - T_2 \sin\left(\frac{n\pi}{2}\right) \right]$$

So,

$$u(x,t) = \frac{T_1 + T_2}{2} + \sum_{n=1}^{\infty} \frac{2(T_1 - T_2)}{n\pi} \sin\left(\frac{n\pi}{2}\right) \cos\left(\frac{n\pi x}{a}\right) \exp(-\gamma_n^2 kt)$$

5)

$V(x)$ is linear since $\frac{d^2V}{dx^2} = 0$

a) Assume $V(x) = ax + b$

We have $\frac{dV}{dx} = a$

but $\frac{\partial u}{\partial x}(0, t) = S_1 \Rightarrow \lim_{t \rightarrow \infty} \frac{\partial u}{\partial x}(0, t) = S_1$
 $\Rightarrow a = \frac{dV}{dx} = S_1$

Similarly $a = S_2$

$\therefore S_1 = S_2$

Conversely if $S_1 = S_2$ the

Steady state $V(x) = S_1 x + c$ (c is a constant)

Observe that the condition

$S_1 = S_2$ is physically necessary

since heat flux a is

proportional to $\frac{\partial u}{\partial x}$

$$q = -S_2 k_2 \frac{\partial u}{\partial x} = S_1 k_1$$

So if the system ends up in

a steady state then $S_1 = S_2$

If steady state soln exist then

$$b) \quad W(x,t) = u(x,t) - V(x)$$

$$\frac{\partial W(x,t)}{\partial x} \Big|_{(0,t)} = \frac{\partial u}{\partial x} (0,t) - \frac{\partial V}{\partial x} = 0$$

Similarly

$$\frac{\partial W(x,t)}{\partial x} \Big|_{(a,t)} = 0$$

$$c) \quad u(x,t) = A(kx + x^2/L) + Bx$$
$$\frac{\partial^2 u}{\partial x^2} = A = \frac{1}{k} \frac{\partial u}{\partial t}, \quad u(x,0) = Ax^2/L + Bx$$

So u satisfies heat eqn.

$$\frac{\partial u}{\partial x} (0,t) = B = S_0$$

$$\frac{\partial u}{\partial x} (a,t) = Aa + B = S_1$$

\Leftrightarrow

$$\therefore A = \frac{S_1 - S_0}{a}, \quad B = S_0$$

\therefore So A, B can be chosen.

$$\text{If } S_1 \neq S_0 \quad A \neq 0$$

$$\therefore \lim_{t \rightarrow \infty} u(x,t) = \pm \infty$$

8) If $\phi''(x) = p^2 \phi(x)$, $\phi'(0) = \phi'(a) = 0$

The general solution is given by

$$\phi(x) = c_1 e^{px} + c_2 e^{-px}$$

$$\phi'(0) = c_1 p - c_2 p = 0 \Rightarrow c_1 = c_2$$

$$\phi'(a) = c_1 (pe^{pa} - pe^{-pa}) = 0 \quad a \neq 0$$

$$\Rightarrow c_1 = 0$$

$$\therefore c_1 = c_2 = 0 \Rightarrow \phi(x) = 0$$

9)

Use Theorem 7 (Section 1.5)

$$\sum_{n=1}^{\infty} |A_n(t_1)| \quad \text{converges}$$

$$\text{and } |A_n(t_1)| = |a_n| \exp(-\lambda_n^2 \kappa t)$$

$$a_n = \frac{1}{a} \int_0^a f(x) \cos \lambda_n x \, dx \quad \text{so } |a_n| \leq \frac{1}{a} \int_0^a |f(x)| \, dx = c_1$$

$$a_n's \text{ are bounded and } \exp(-\lambda_n^2 \kappa t) \leq c_2^{-n^2}$$

$$\text{So } |A_n(t_i)| \leq c_1 c_2^{-n}$$

as a geometric series

converges, the series

$$\sum |A_n(t_i)| \text{ converges}$$

\therefore So the given ~~series~~ series converges uniformly in $0 \leq x \leq h$ by theorem 7. to $u(x, t_i)$

Similar argument shows $\left(\frac{\partial^2 u}{\partial x^2} \right)$

2.7

(3d)

$$\varphi(x) = c_1 \sin \lambda x + c_2 \cos \lambda x$$

$$\varphi'(x) = \lambda c_1 \cos \lambda x - \lambda c_2 \sin \lambda x$$

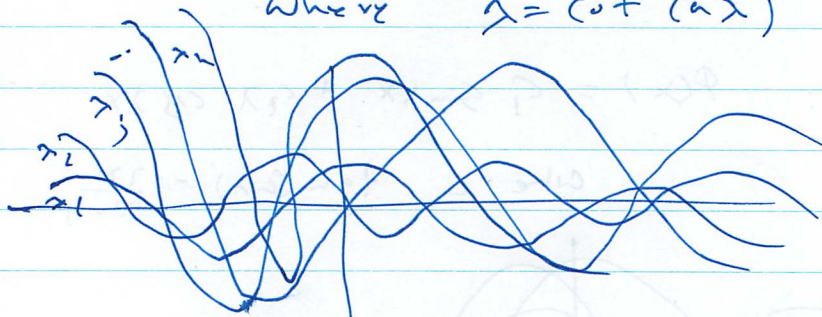
$$\text{So } \varphi(0) = c_2 = \varphi'(0) = \lambda c_1$$

$$\varphi'(a) = \lambda c_1 \cos(a\lambda) - \lambda c_2 \sin a\lambda$$

$$\Rightarrow \lambda = \cot(a\lambda)$$

$$\varphi(x) = c_1 \sin \lambda x + c_1 a \cos \lambda x$$

$$\text{where } \lambda = \cot(a\lambda)$$



For large n the graph
looks like
a sine graph

(3e)

Here we get

$$\phi(x) = \phi'(x) \quad \text{So} \quad c_2 = \lambda c_1$$

and $\phi(x) = -\phi'(x)$

$$\begin{aligned} \text{So } \phi_1 \sin(\lambda x) + \lambda \phi_1 \cos(\lambda x) &= \\ &= (\lambda^2 \phi_1 \sin(\lambda x) \\ &\quad + \lambda \phi_1 \cos(\lambda x)) \\ &\quad \times (-1) \end{aligned}$$

$$\therefore \tan(\lambda x) = \frac{2\lambda}{\lambda^2 - 1}$$

$$\therefore \phi(x) = c_1 \sin \lambda x + c_2 \lambda \cos \lambda x$$

where $\tan(\lambda x) = \frac{2\lambda}{\lambda^2 - 1}$

