

A Theorem on Subdivision Approximation and Its Application to Obtaining PTAS's for Geometric Optimization Problems

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A Dedication

Happy 60th Birthday!!

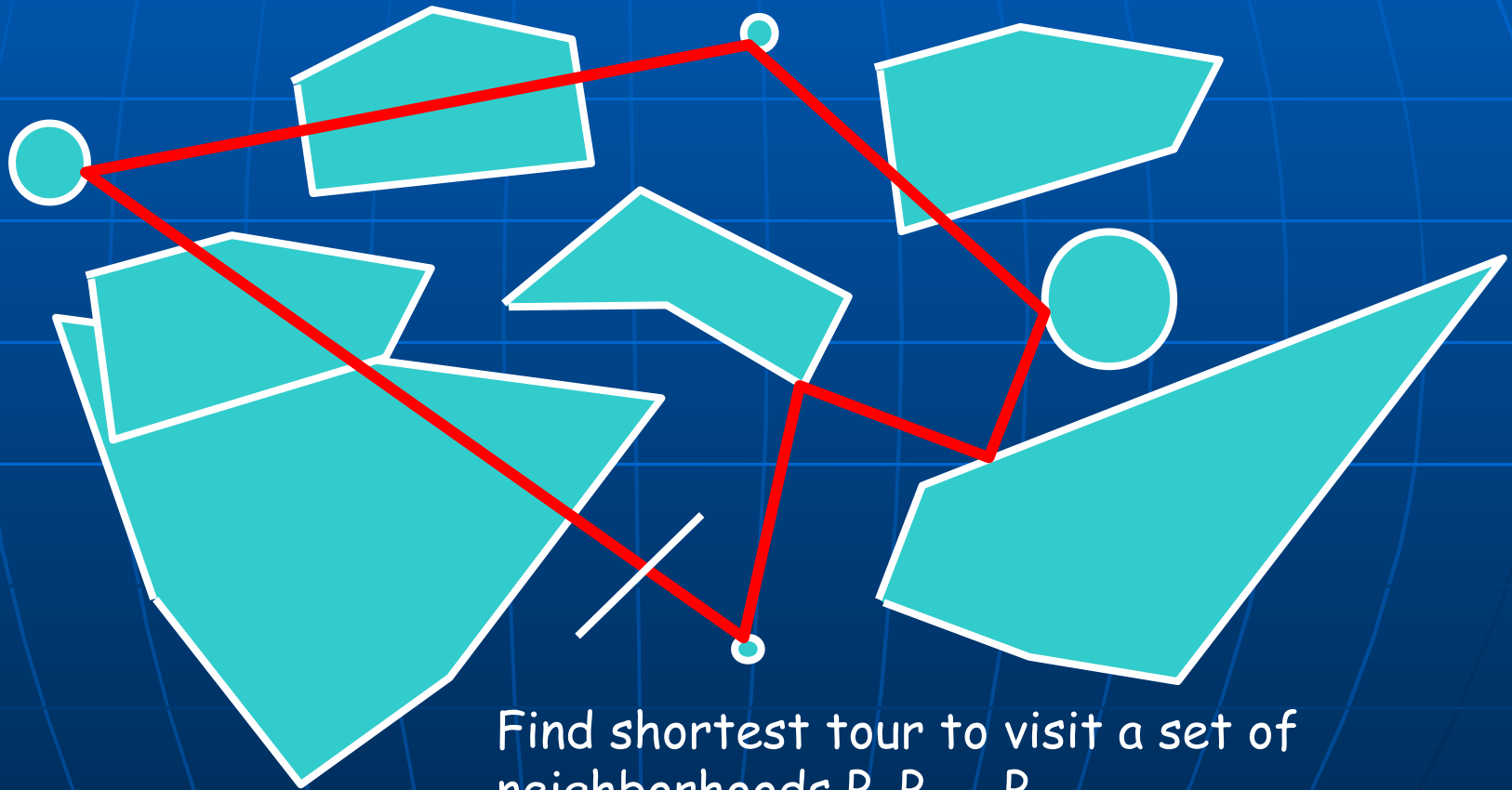


Michael Ian Shamos:

PhD thesis "Computational Geometry", Yale University, 1978

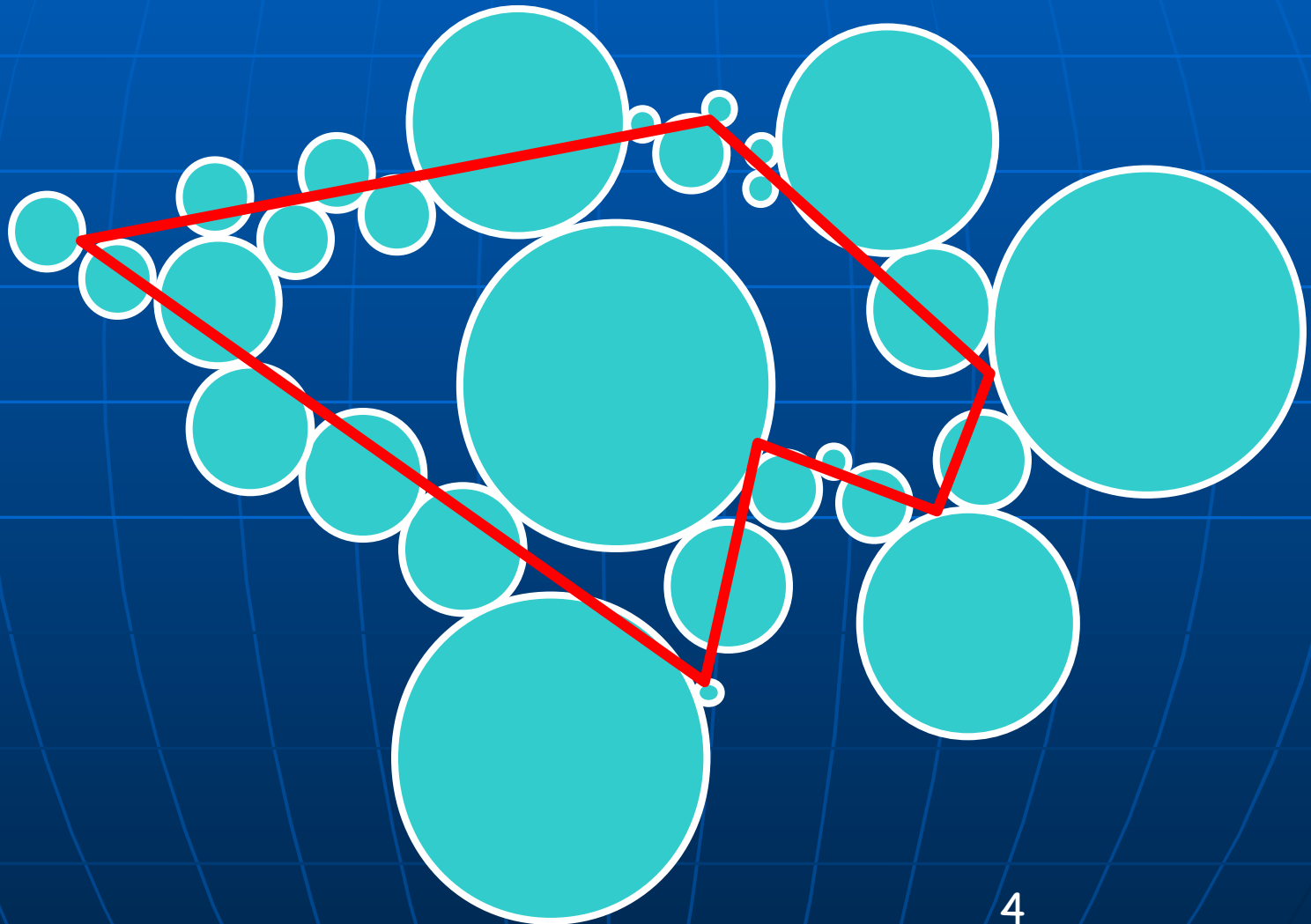


Motivating Problem: TSP with Neighborhoods

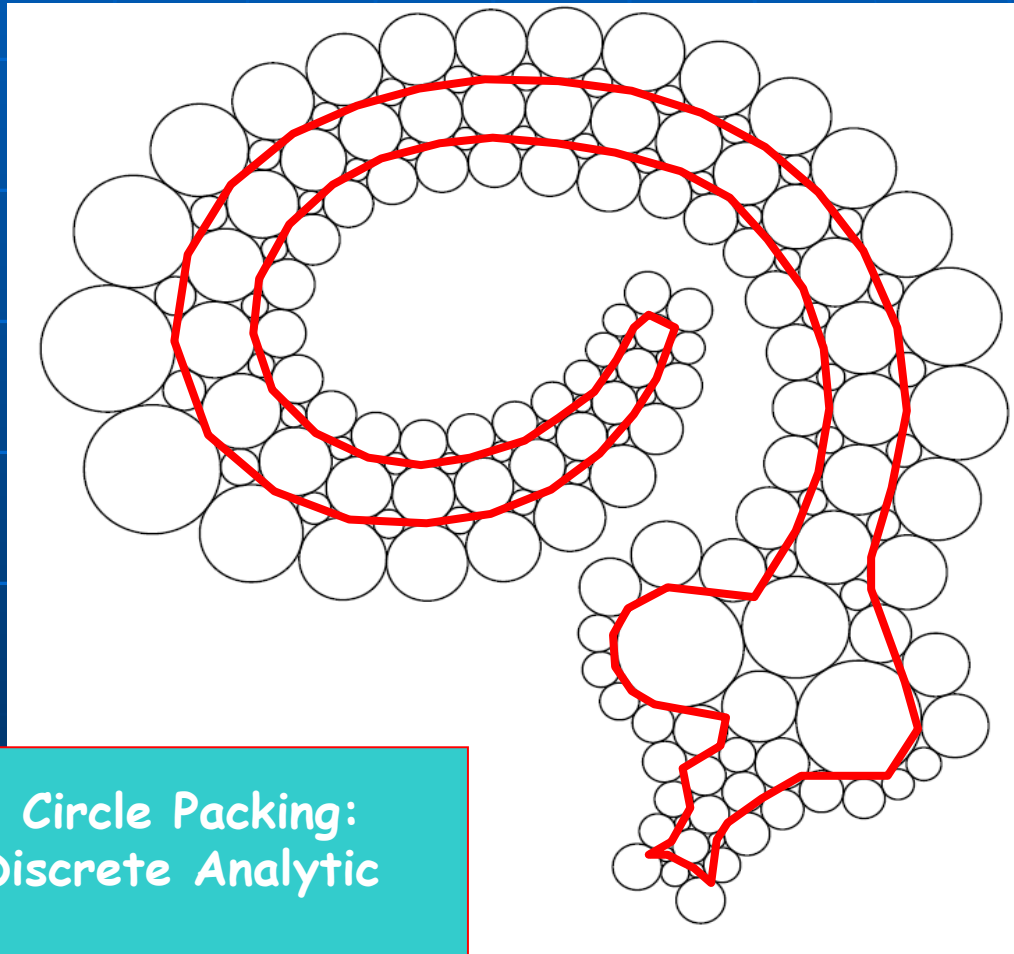


Find shortest tour to visit a set of neighborhoods P_1, P_2, \dots, P_n

TSPN for Disk Packing



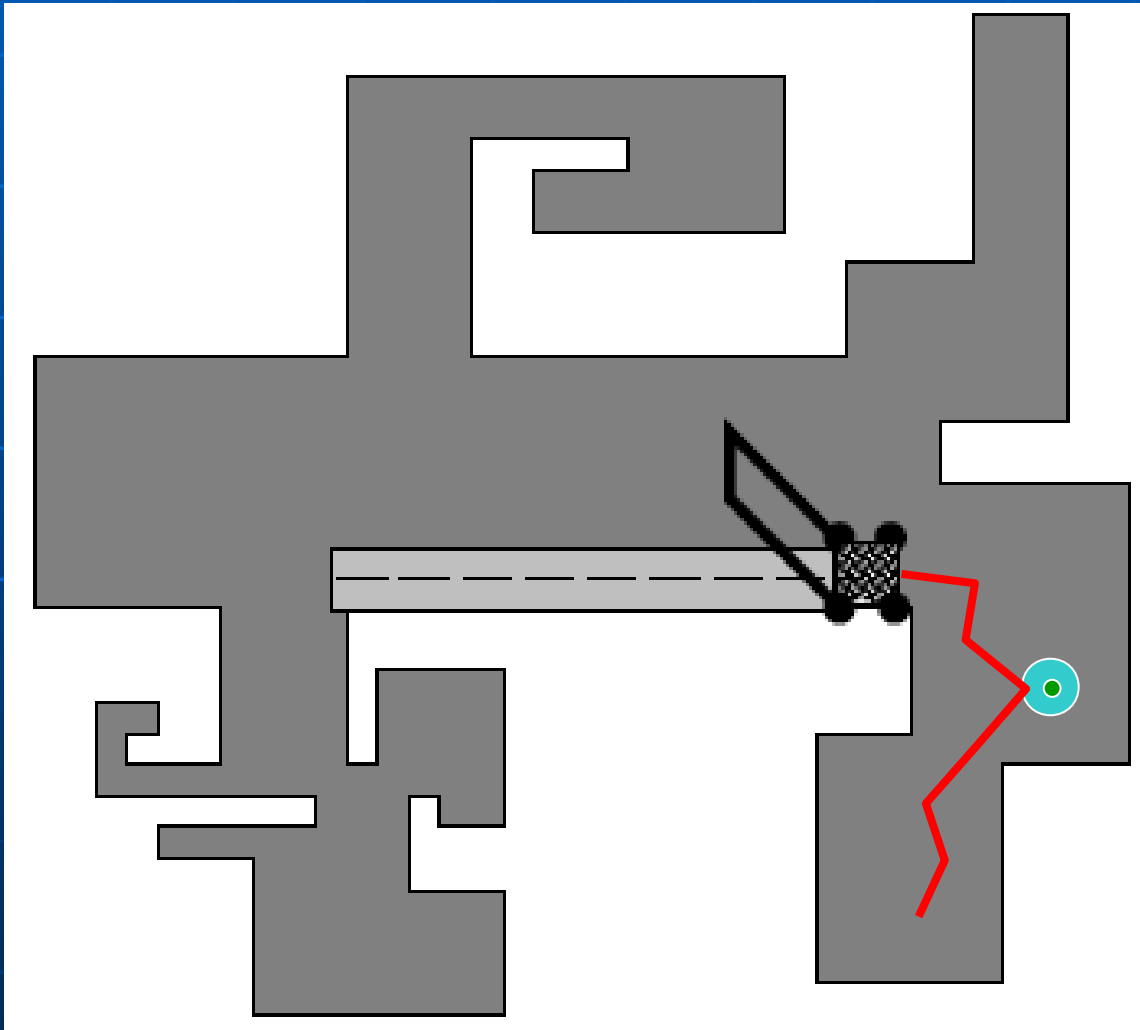
TSPN in a Circle Packing



"Introduction to Circle Packing:
the Theory of Discrete Analytic
functions"

by Ken Stephenson

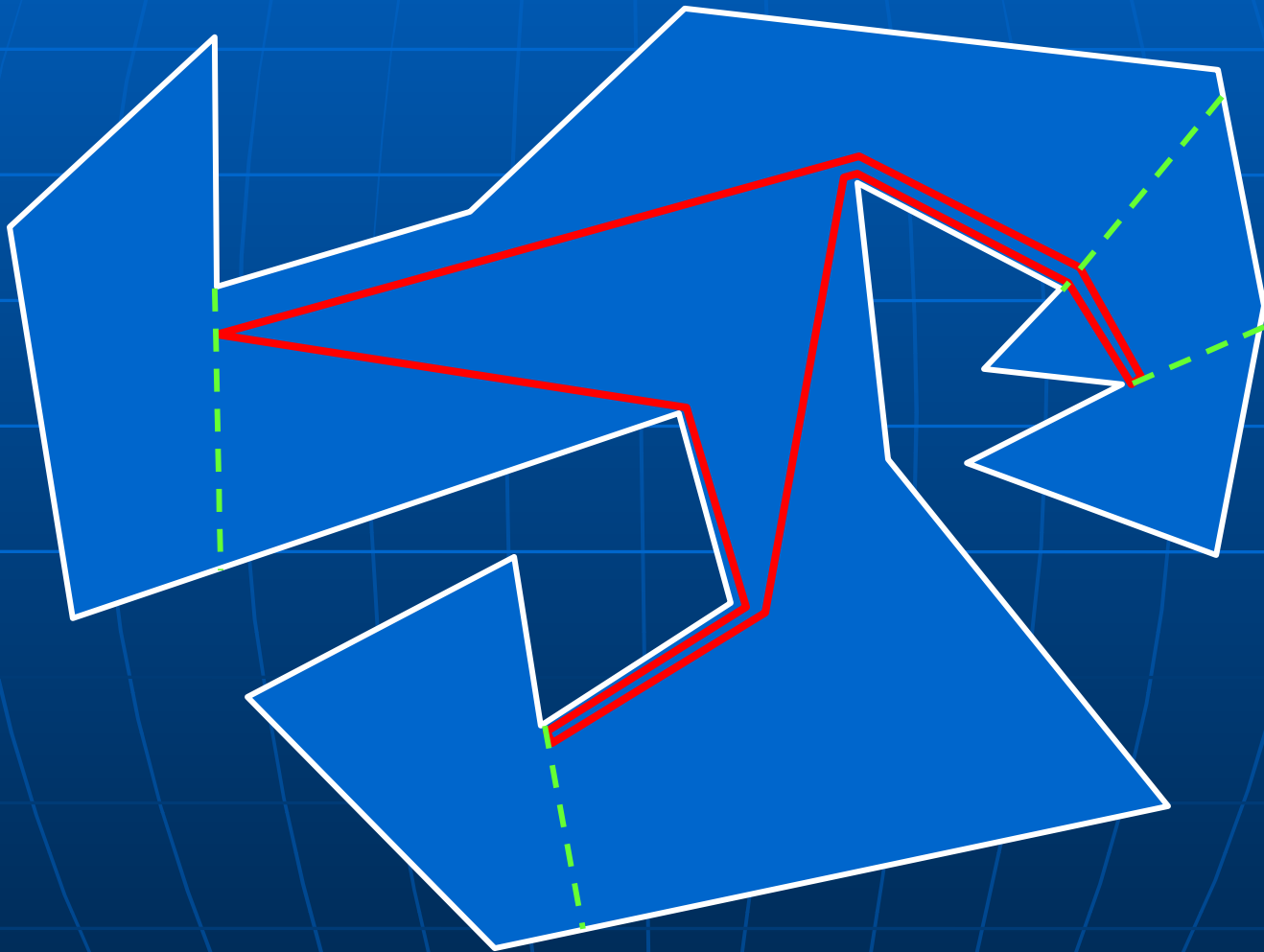
Another (Springtime) Motivation



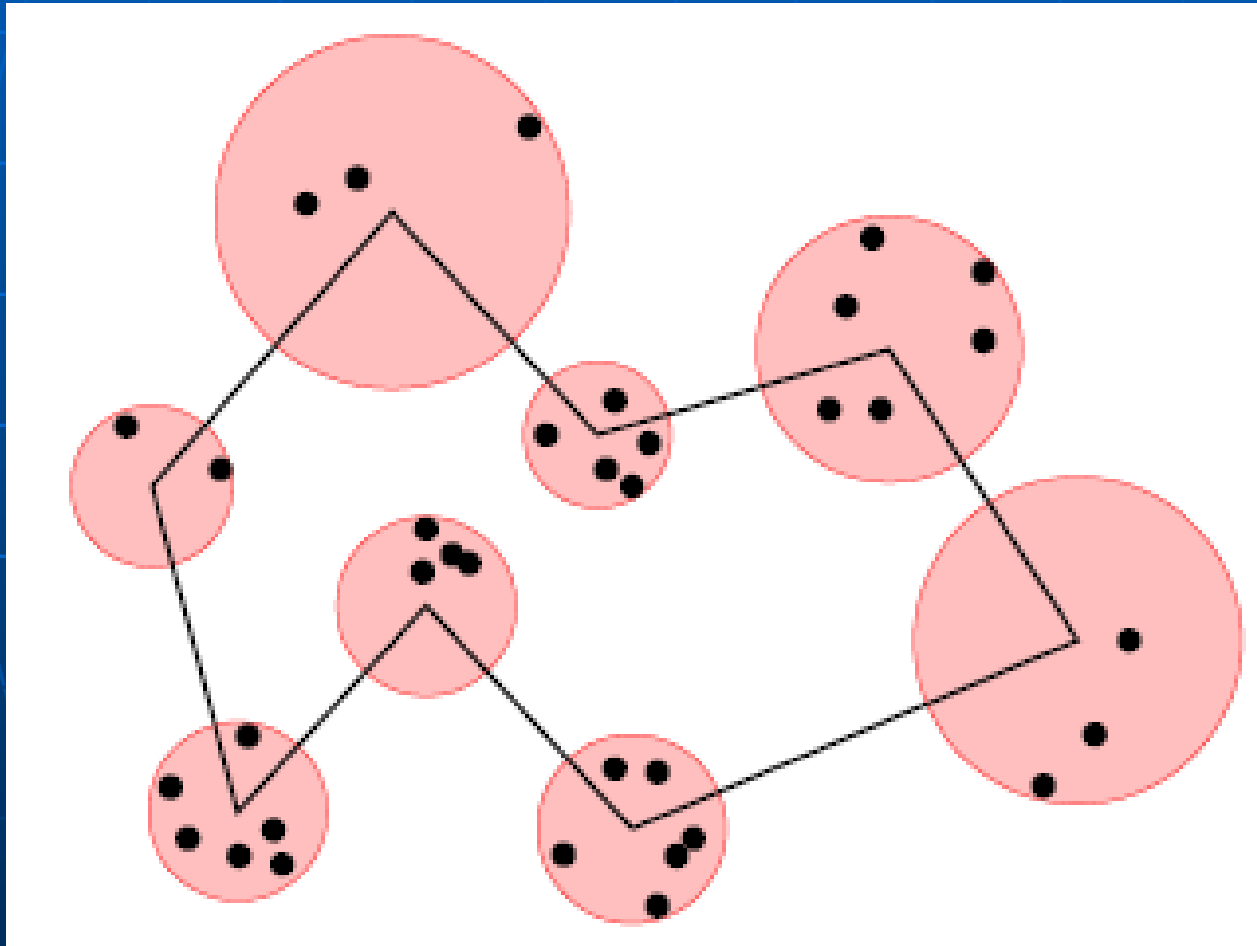
Best method of
mowing the lawn?

TSPN: Visit the disk
centered at each blade
of grass

Watchman Route Problem



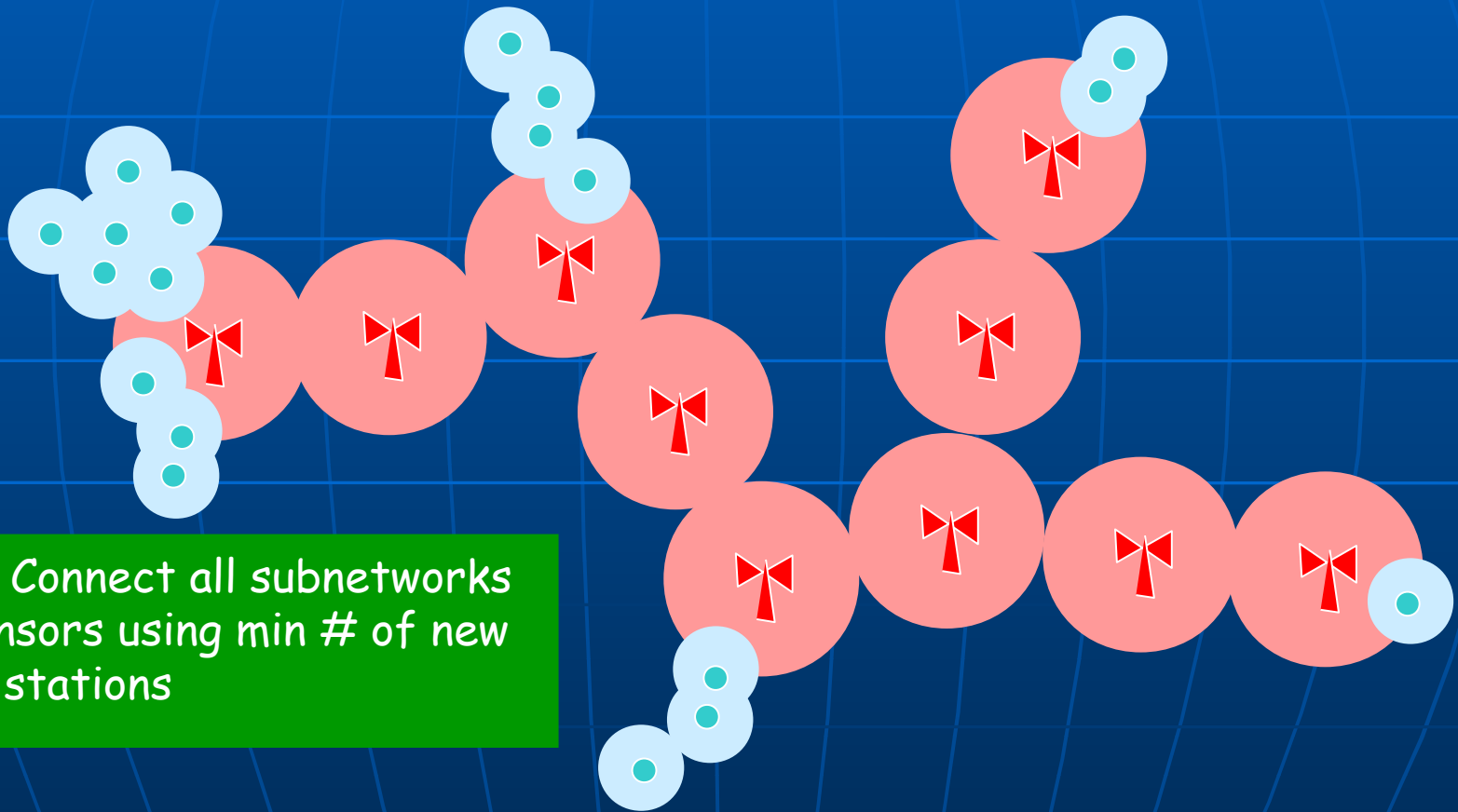
Sensor Network Application: Cover Tour Problem



Min: Tour length +
 $C * (\text{sum of radii})$

Alt, Arkin, Bronnimann, Erickson, Fekete,
Knauer, Lenchner, Mitchell, Whittlesey, SoCG'06

Sensor Network Application: Minimizing # Relay Stations

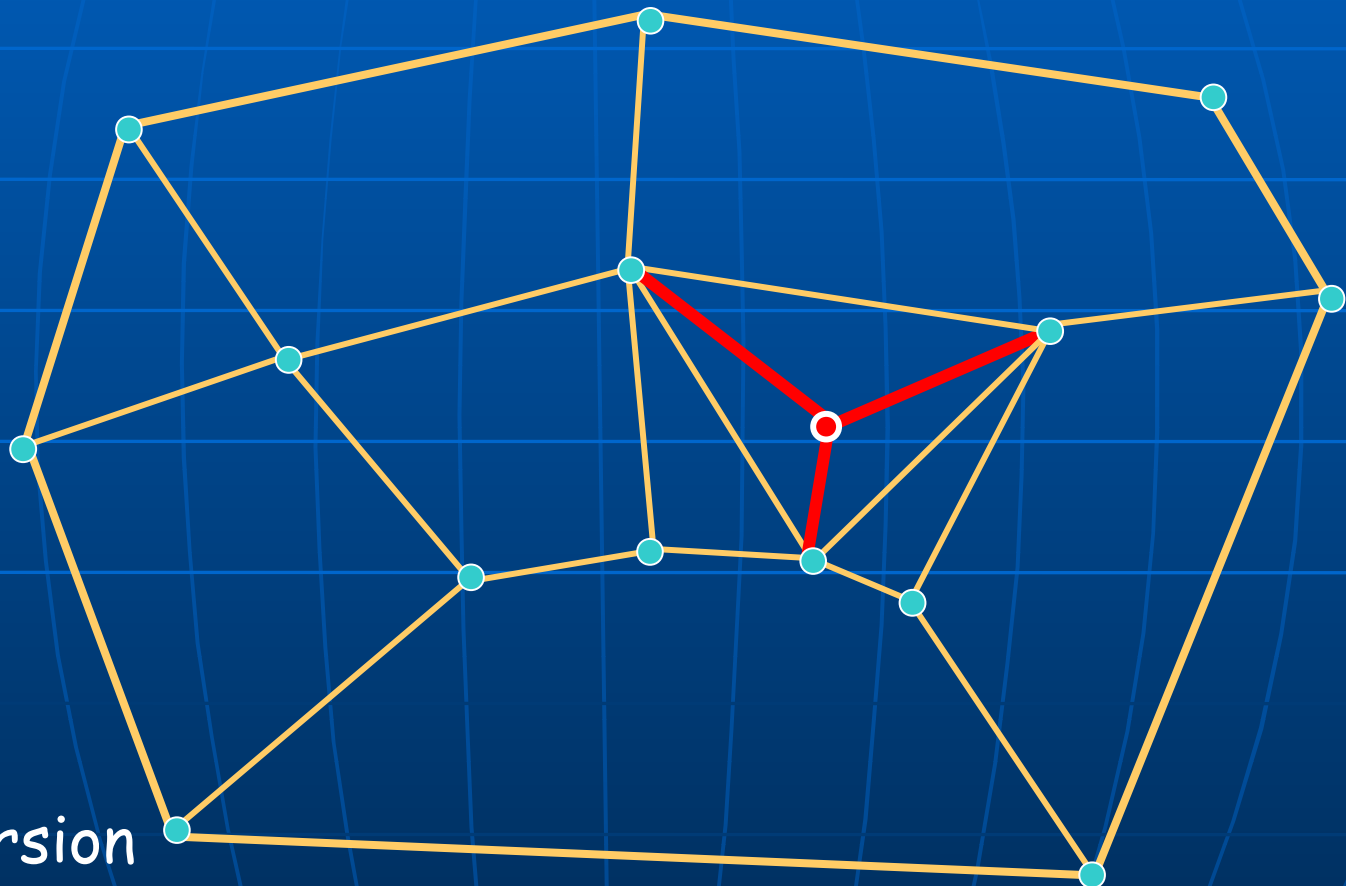


Goal: Connect all subnetworks of sensors using min # of new relay stations

New result: PTAS

Efrat, Fekete, Mitchell 2007 9

Min-Weight Convex Subdivision



Steiner version

Special Case: Min-weight (Steiner) triangulation

10

Approximation Algorithms

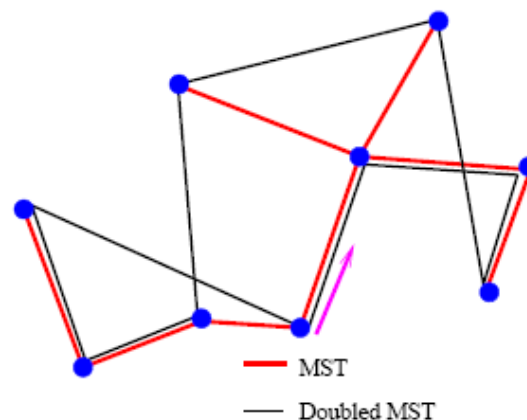
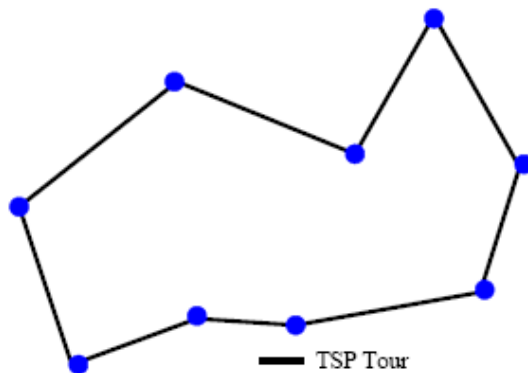
c-approximation: cost at most c times optimal, for a minimization problem ($c > 1$)

Polynomial Time Approximation Scheme (PTAS): method giving $(1 + \epsilon)$ -approx to the optimal (minimum), in time polynomial in n , for *any* fixed $\epsilon > 0$.

Dependence on ϵ may be exponential in $(1/\epsilon)$; else FPTAS

Background on TSP

- $S =$ set of n points in \mathbb{R}^d
- NP-hard
- $n^{O(n^{1-1/d})}$ exact (subexponential) [SmWo98]
- Simple 2-approx: double the MST and shortcut (holds in metric spaces)



- Christofides: 1.5-approx
(use $\text{MST} \cup \text{min-weight matching}$ on odd-degree nodes of MST)

PTAS for Geometric TSP

- $O(n^{O(1/\epsilon)})$ in \mathbb{R}^2 [Ar96,Mi96]
- $O(n^{O(1)})$ in \mathbb{R}^2 [Mi97]
- $O(n(\log n)^{O(\frac{d}{\epsilon})^{d-1}})$ expected ($O(n^{d+1}polylog)$ det.) [Ar97]
- $O(n \log n)$ deterministic [RaSm98]
Idea: t -spanners and “ t -banyons”
- NP-hard to get $(1 + \epsilon)$ -approx in $\mathbb{R}^{O(\log n)}$, for some $\epsilon > 0$ [Tr97]
- MAX-SNP-hard in metric spaces
No c -approx for $c < 129/128$ ($c < 41/40$, asym.) [PV99]

TSPN Recent Result [SODA'07]

- TSPN has a PTAS for regions/neighborhoods that are “fat”, disjoint (or sufficiently disjoint) connected regions in the plane
- Applies also to “MST with neighborhoods”, Steiner MSTN, and many related problems

PTAS = Polynomial-Time Approximation Scheme = $(1+\epsilon)$ -approx, any $\epsilon > 0$

Background on TSPN

Generalizes 2D Euclidean TSP (thus, NP-hard)

Introduced by [Arkin & Hassin, 1994]

- “obvious” heuristics do not work:
 - TSP approx on centroids (as representative points)
 - Greedy algorithms (Prim- or Kruskal-like)
- $O(1)$ -approx, time $O(n + k \log k)$, for “nice” regions:
 - Parallel unit segments
 - Unit disks
 - Translates of a polygon P
- Combination Lemma

General Connected Regions

$O(\log k)$ -approx

[Mata & M, SoCG'95]

Use guillotine rectangular subdivisions, DP
(*non* - disjoint: regions may overlap)

- $O(n^5)$ time

[Mata & M, SoCG'95]

- $O(n^2 \log n)$

[Gudmundsson & Levcopoulos, 1999]

$k = \#$ regions

$n = \#$ vertices of all regions

$O(1)$ -Approximations

- Unit disks, parallel unit segments, translates of P
[Arkin & Hassin, 1993]
- Connected regions of comparable size
[Dumitrescu & M, SODA'01]
- Disjoint fat regions of *any* size [de Berg, Gudmundsson, Katz, Levcopoulos, Overmars, van der Stappen, ESA'02]
- Discrete point sets within disjoint, fat, *non-convex* regions
[Elbassioni, Fishkin, Mustafa, Sitters, ICALP'05]
- *Non* - disjoint, convex, fat, comparable size
[Elbassioni, Fishkin, Sitters, ISAAC'06]

PTAS: $O(1+\epsilon)$ -Approximations

- Disjoint (or nearly disjoint) fat regions of comparable size
[Dumitrescu & M, SODA'01]
- Point clusters within disjoint fat regions of comparable size in \mathbb{R}^d

[Feremans, Grigoriev, EWCG'05]

New: PTAS for disjoint (or nearly disjoint) fat regions of *arbitrary* sizes.

Def: P is **fat** if $\text{area}(P) = \Omega(\text{diam}^2(P))$

Weaker notion than usual "fatness" 18

Related Work: APX-hardness

- General connected regions (overlapping):

- No c -approx with $c < 391/390$, unless $P=NP$

[de Berg, Gudmundsson, Katz, Levcopoulos,
Overmars, van der Stappen, ESA'02]

(from *MinVertexCover*)

- No c -approx with $c < 2$, unless $P = NP$

TIME ($n^{O(\log \log n)}$)

[Safra, Schwartz, ESA'03]

(from *Hypergraph VertexCover*)

- Line segments, comparable length

[Elbassioni, Fishkin, Sitters, ISAAC'06]

- Pairs of points (disconnected)
2004]

[Dror, Orlin,

Exact Poly-Time Solutions

TSPN for a set of **infinite** lines in 2D:



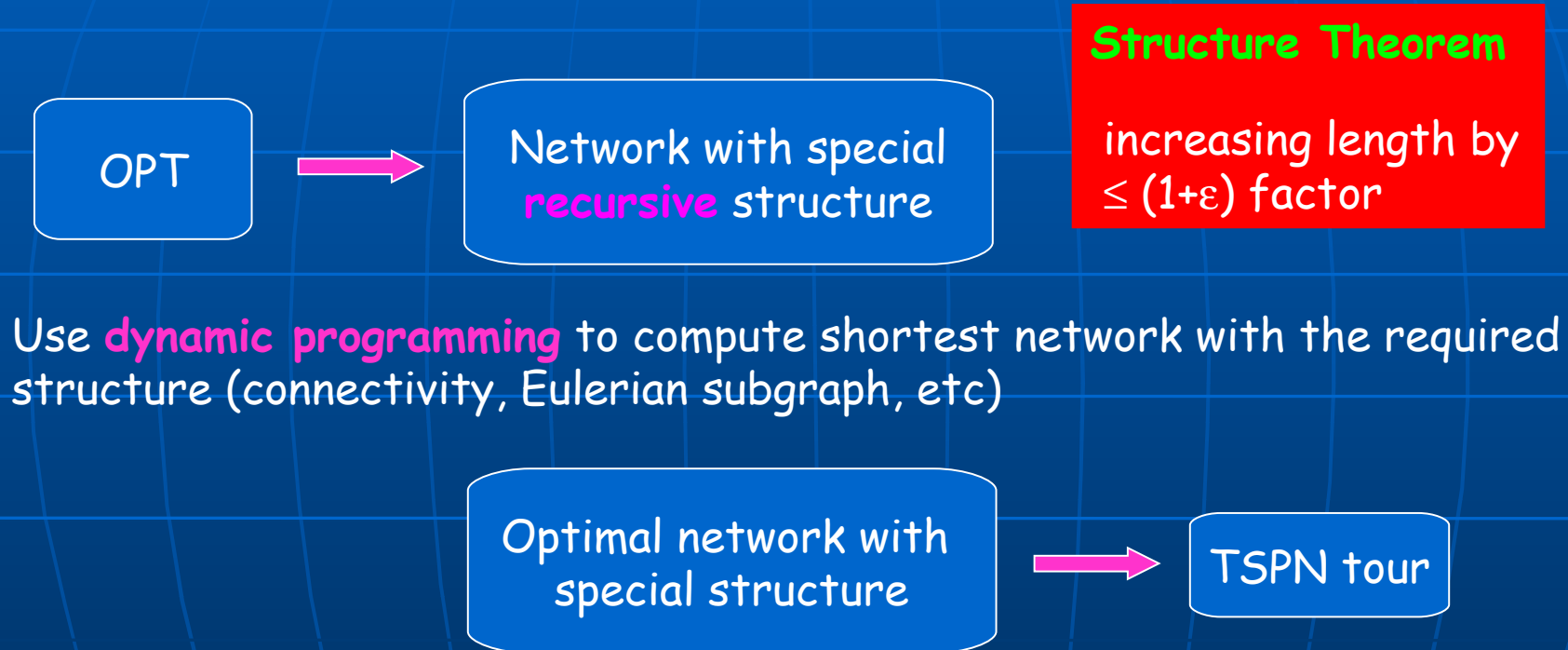
Is this the only nontrivial case exactly solvable in poly-time?

What about visiting **planes** in 3D?

Solved in $O(n^4 \log n)$ time using Watchman Route solution

[Dror, Efrat, Lubiw, 20, STOC'03]

Recipe for PTAS



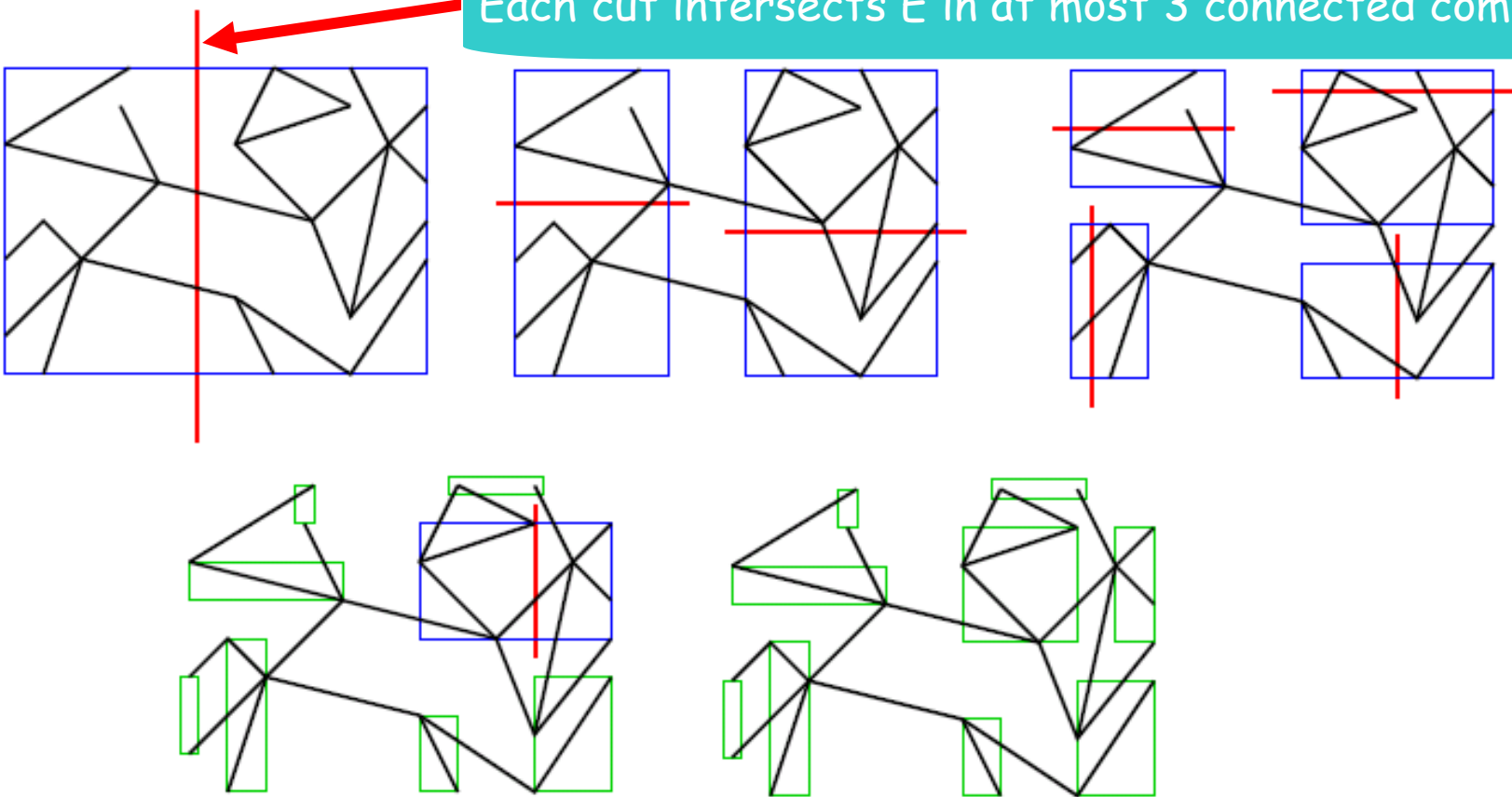
What should the special recursive structure be?

m-Guillotine Structure

Network edge set E is m -guillotine if it can be recursively partitioned by horiz/vertical cuts, each having small ($O(m)$) complexity wrt E

Example: 3-guillotine

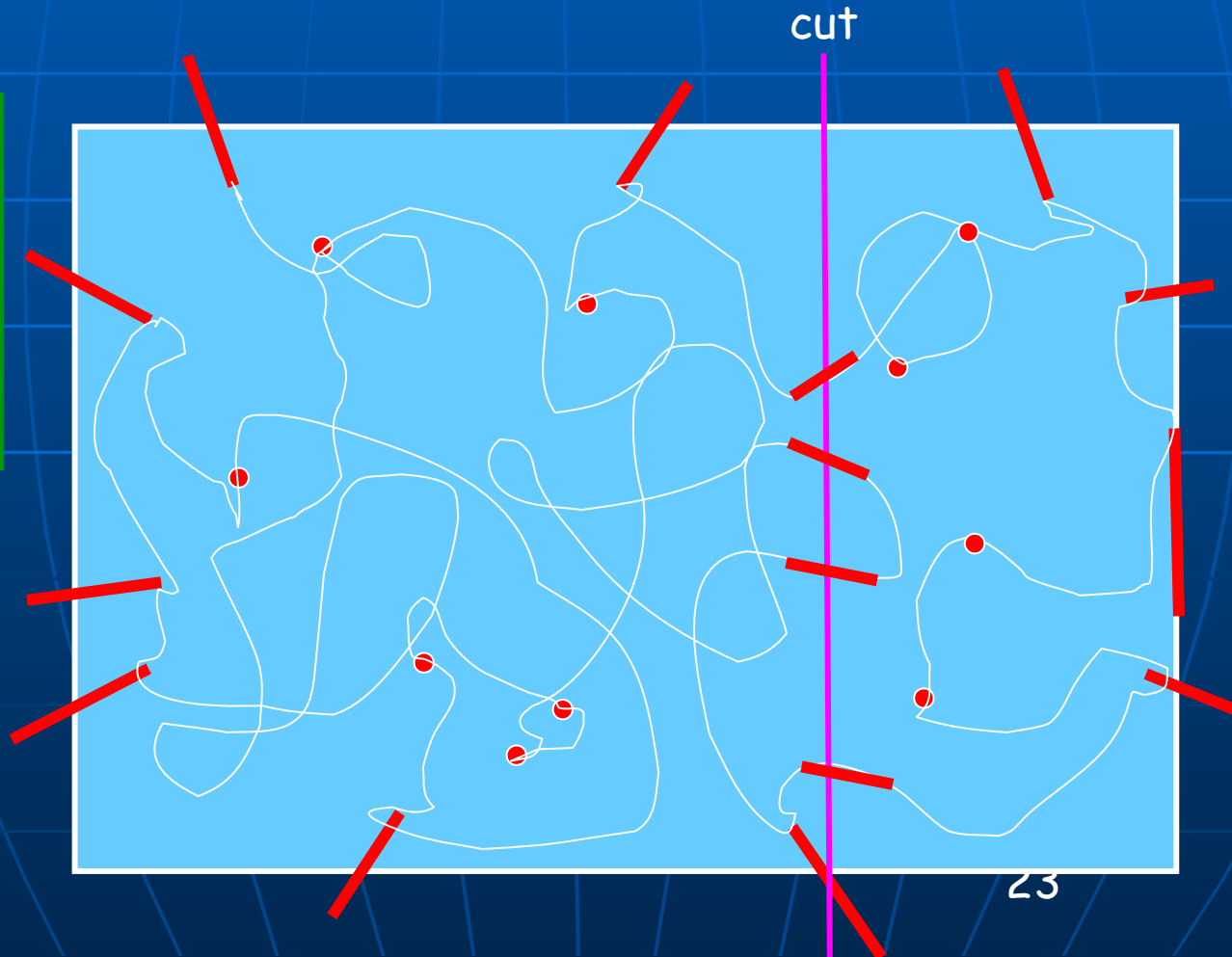
Each cut intersects E in at most 3 connected components



Desired Recursive Structure

Rectangular subproblem in dynamic program (recursion)

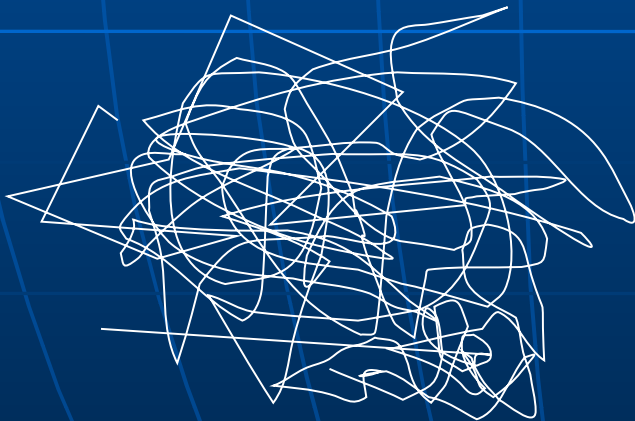
Constant
($O(m)$)
information
flow across
boundary



m-Guillotine Structure Theorem

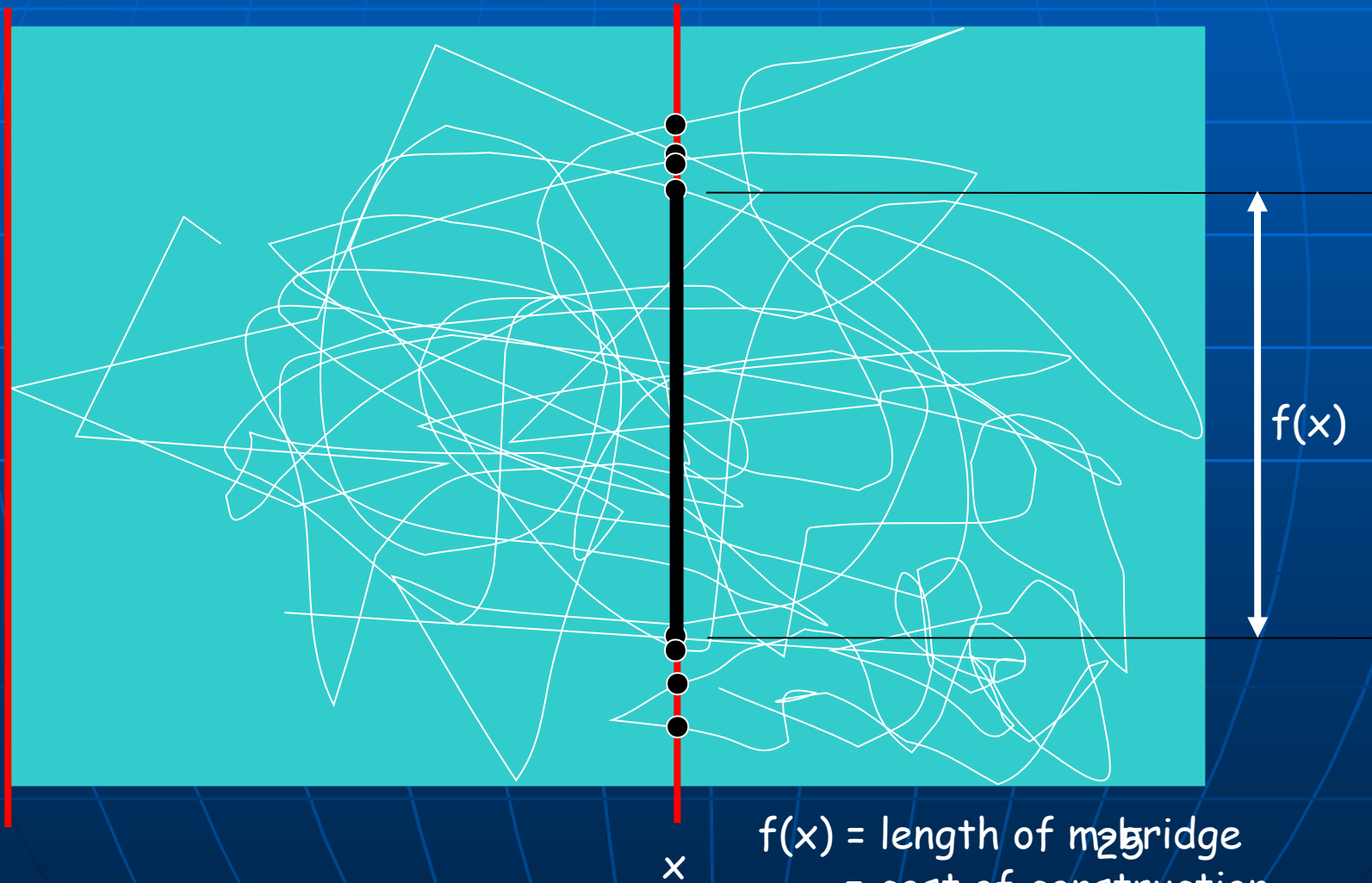
Any set E of edges of length L can be made to be m -guillotine by adding length $O(L/m)$ to E , for any positive integer m .

Proof is based on a simple charging scheme.

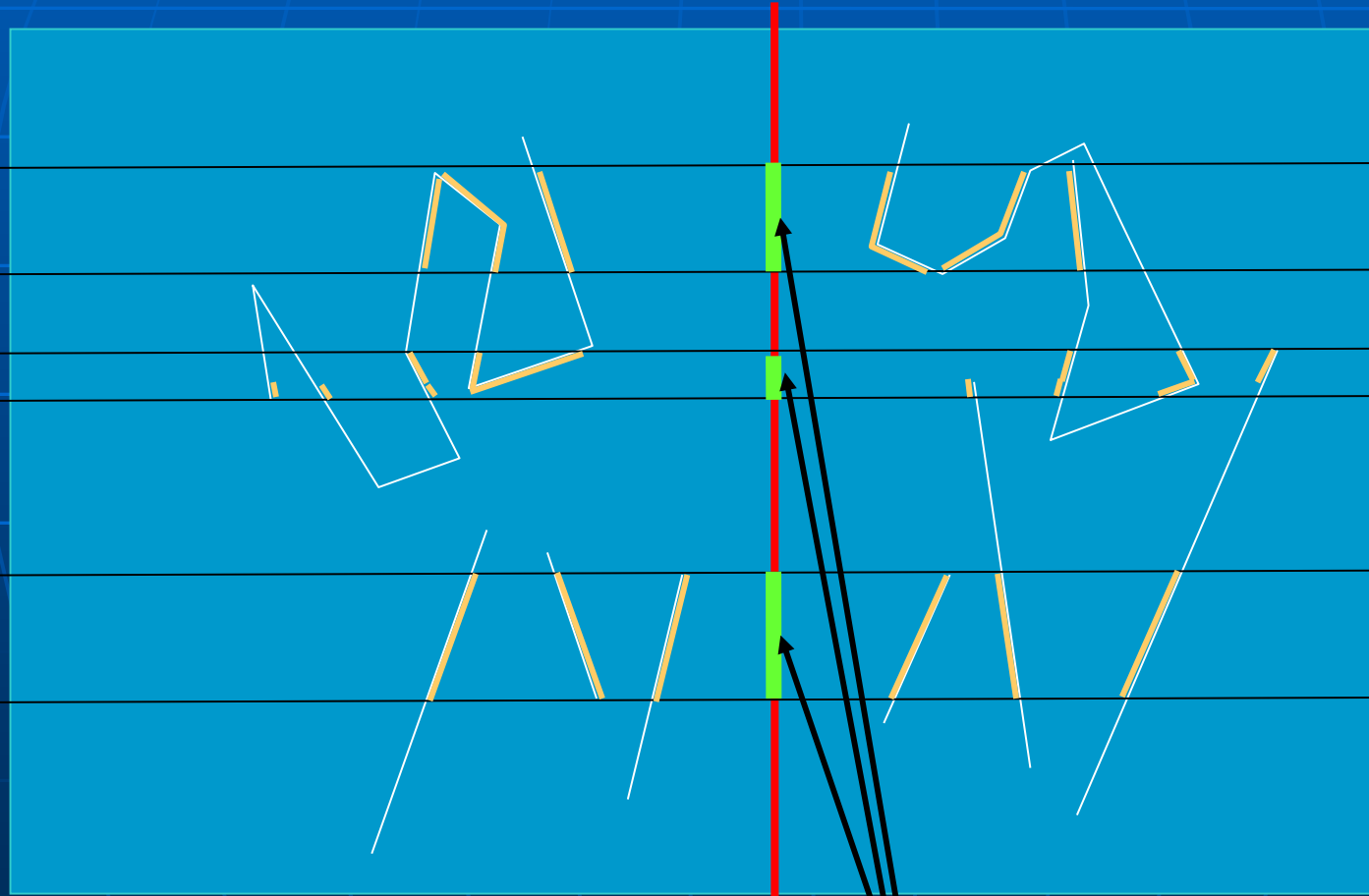


While this “scribble” may not be m -guillotine, it is “close” in that it can be made m -guillotine by adding only $(1/m)$ th of its length

Possible Vertical Cuts



Paying for the Bridge Construction: The Chargeable Length



Green portion: "m-dark"

x

$h(x)$ = chargeable length

Charging Scheme

- Let $f(x)$ = length of m -span of vertical line through x
Let $g(y)$ = length of m -span of horizontal line through y

- Then,

$$A_x = \int f(x) dx$$

is simply the area of the “ m -dark” (RED) region wrt horiz cuts

Similarly,

$$A_y = \int g(y) dy$$

is the area of the “ m -dark” (BLUE) region wrt vertical cuts

- Assume, WLOG, that $A_x \geq A_y$

- Thus, for $h(y)$ = length of m -dark, for horiz line through y ,

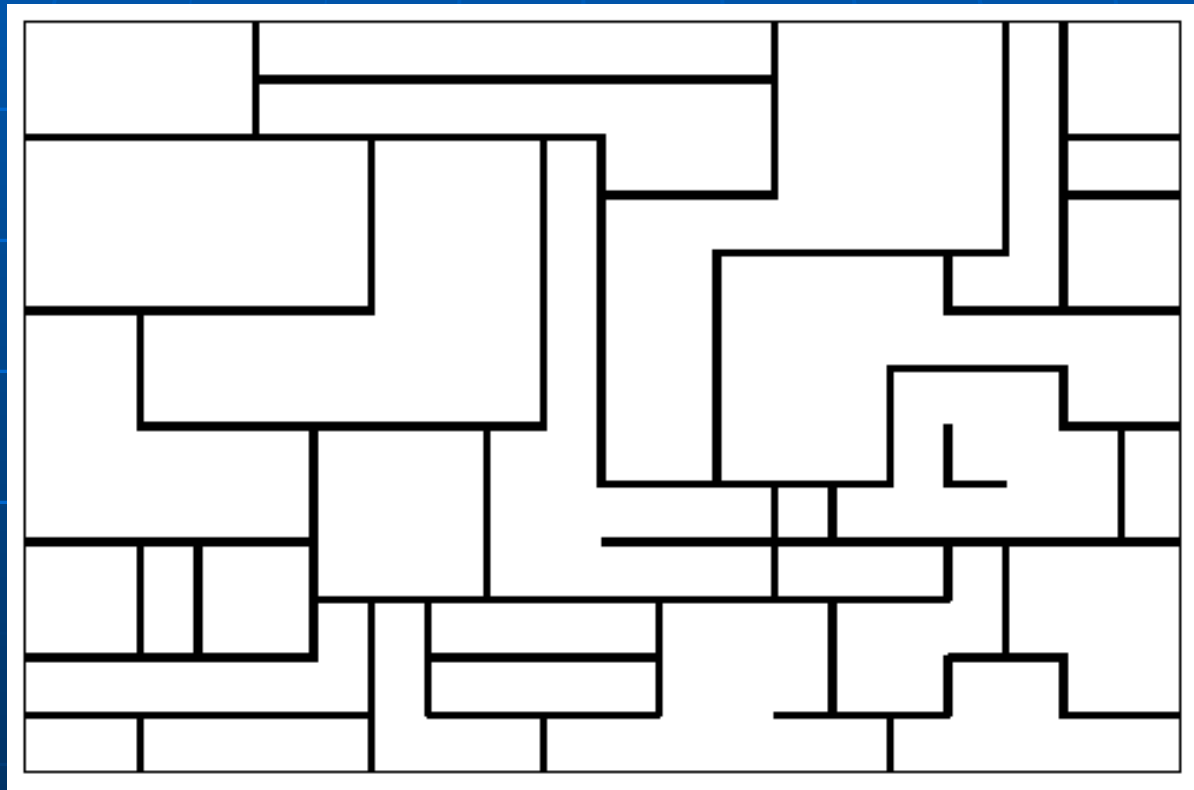
$$A_x = \int h(y) dy \geq \int g(y) dy = A_y > 0$$

So, $\exists y^*$ for which $h(y^*) \geq g(y^*)$;

i.e., \exists a horiz line through y^* whose m -dark portion $\geq m$ -span.

(If $A_x \leq A_y$, then \exists a vertical favorable cut.)

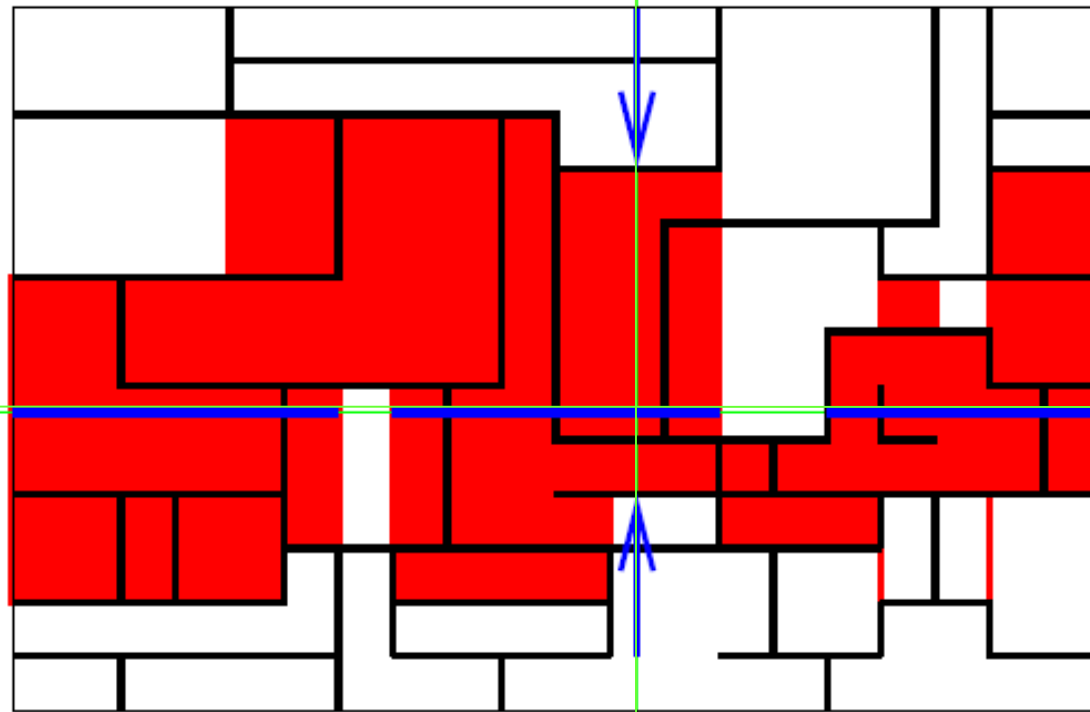
Charging Scheme



Charging Scheme

Region of 2-dark points wrt horizontal cuts (RED)

$f(x)$



$h(y)$ =
chargeable
length of horiz
cut at y

y

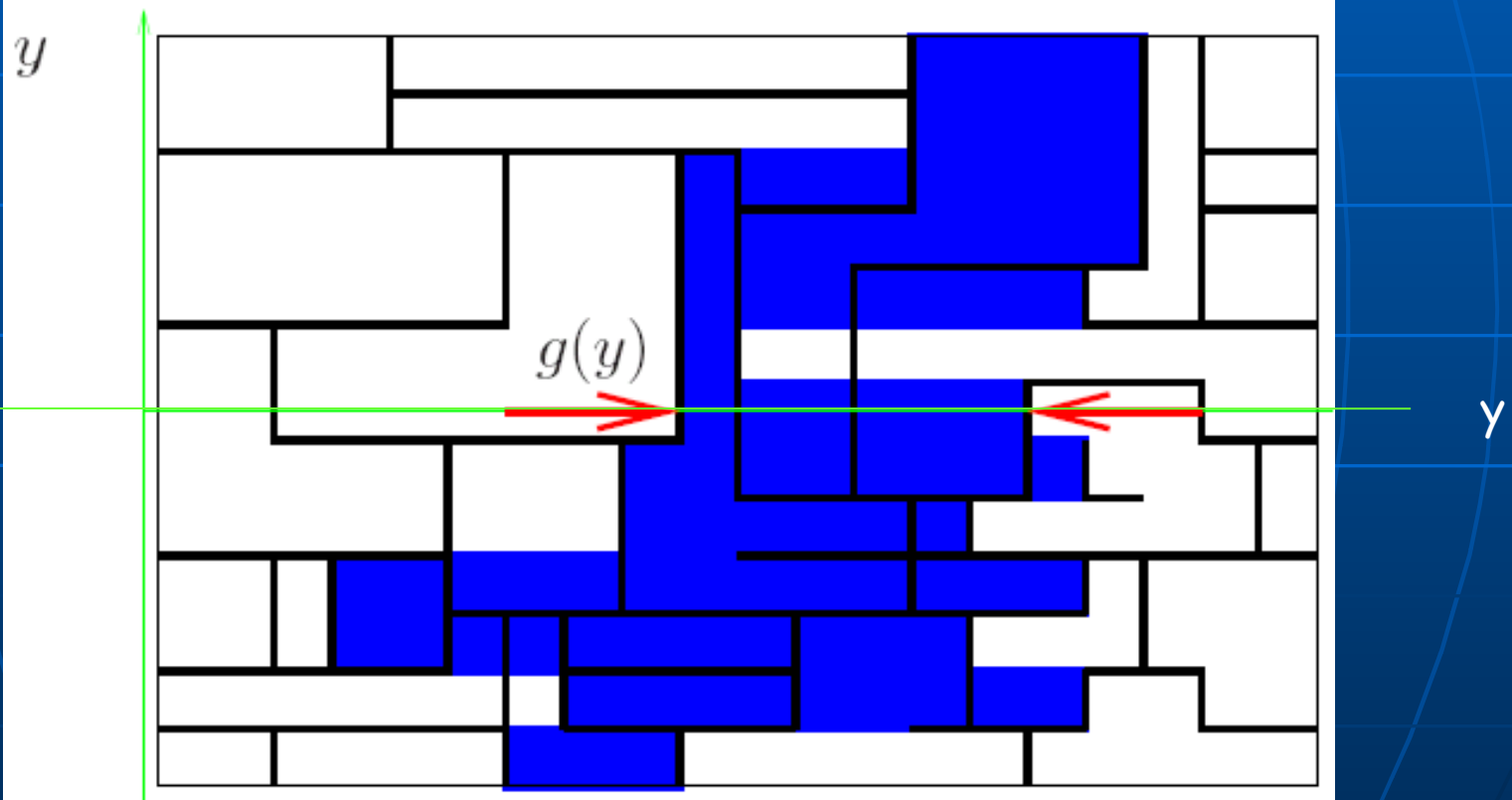
x

Red area = $A_x = \int f(x) dx = \int h(y) dy$

\times $f(x)$ = cost of construction of
vert cut at x

Charging Scheme

Region of 2-dark points wrt vertical cuts (BLUE)



Blue area = $A_y = \int g(y) dy$

Charging Scheme

- Let $f(x)$ = length of m -span of vertical line through x
Let $g(y)$ = length of m -span of horizontal line through y

- Then,

$$A_x = \int f(x)dx$$

is simply the area of the “ m -dark” (RED) region wrt horiz cuts

Similarly,

$$A_y = \int g(y)dy$$

is the area of the “ m -dark” (BLUE) region wrt vertical cuts

- Assume, WLOG, that $A_x \geq A_y$

- Thus, for $h(y)$ = length of m -dark, for horiz line through y ,

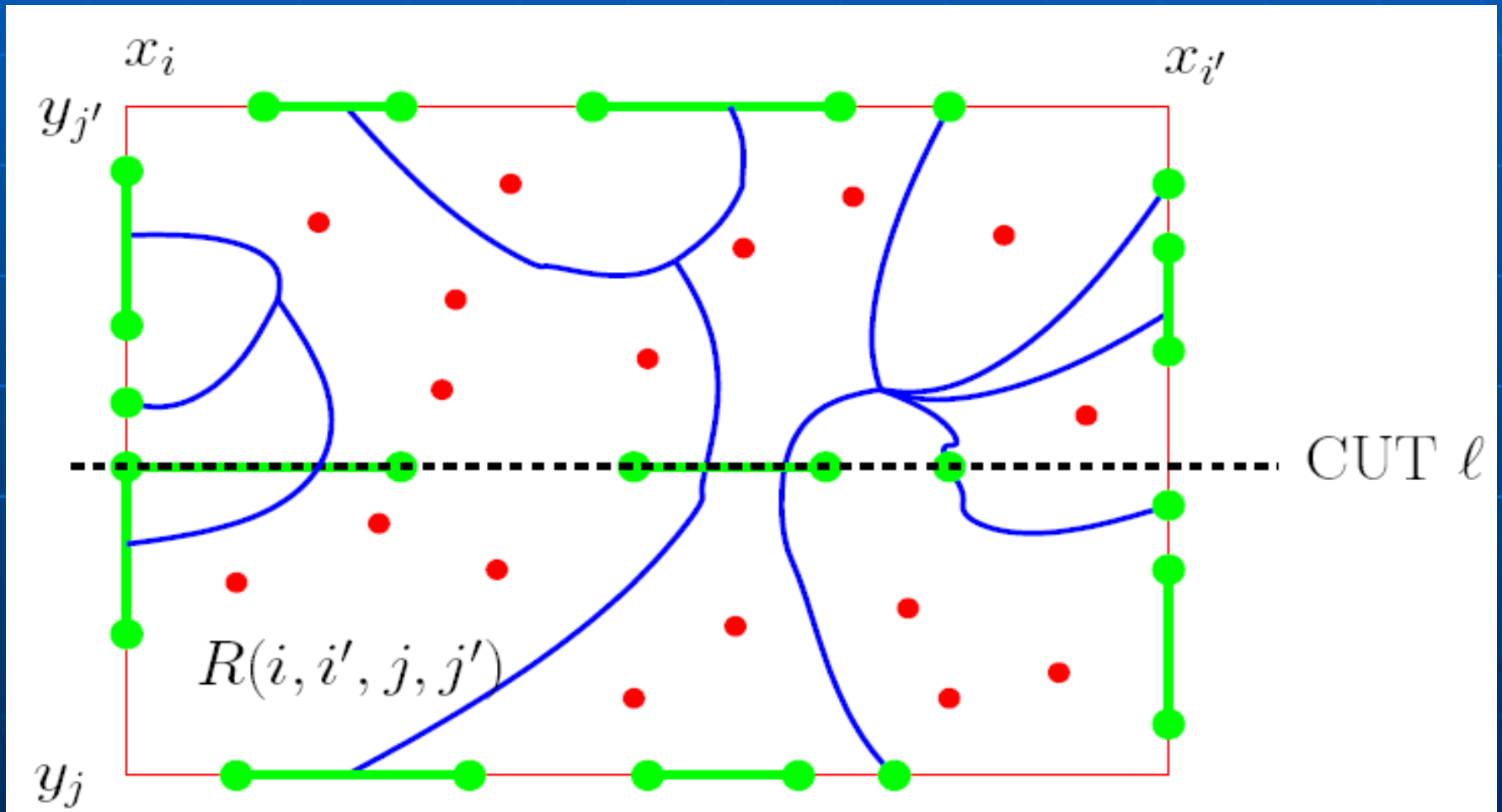
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So, $\exists y^*$ for which $h(y^*) \geq g(y^*)$;

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(If $A_x \leq A_y$, then \exists a vertical favorable cut.)

Subproblem



Dynamic Program: Min Steiner Tree

Sorted x -coord: $x_1 < x_2 < \dots$ (for P , and grid lines)

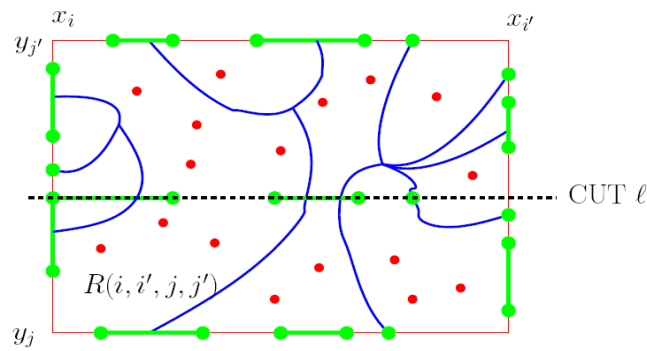
Sorted y -coord: $y_1 < y_2 < \dots$

Subproblem: $O(n^4 \cdot (n^{2m})^4) = O(n^{8m+4})$ choices

Input:

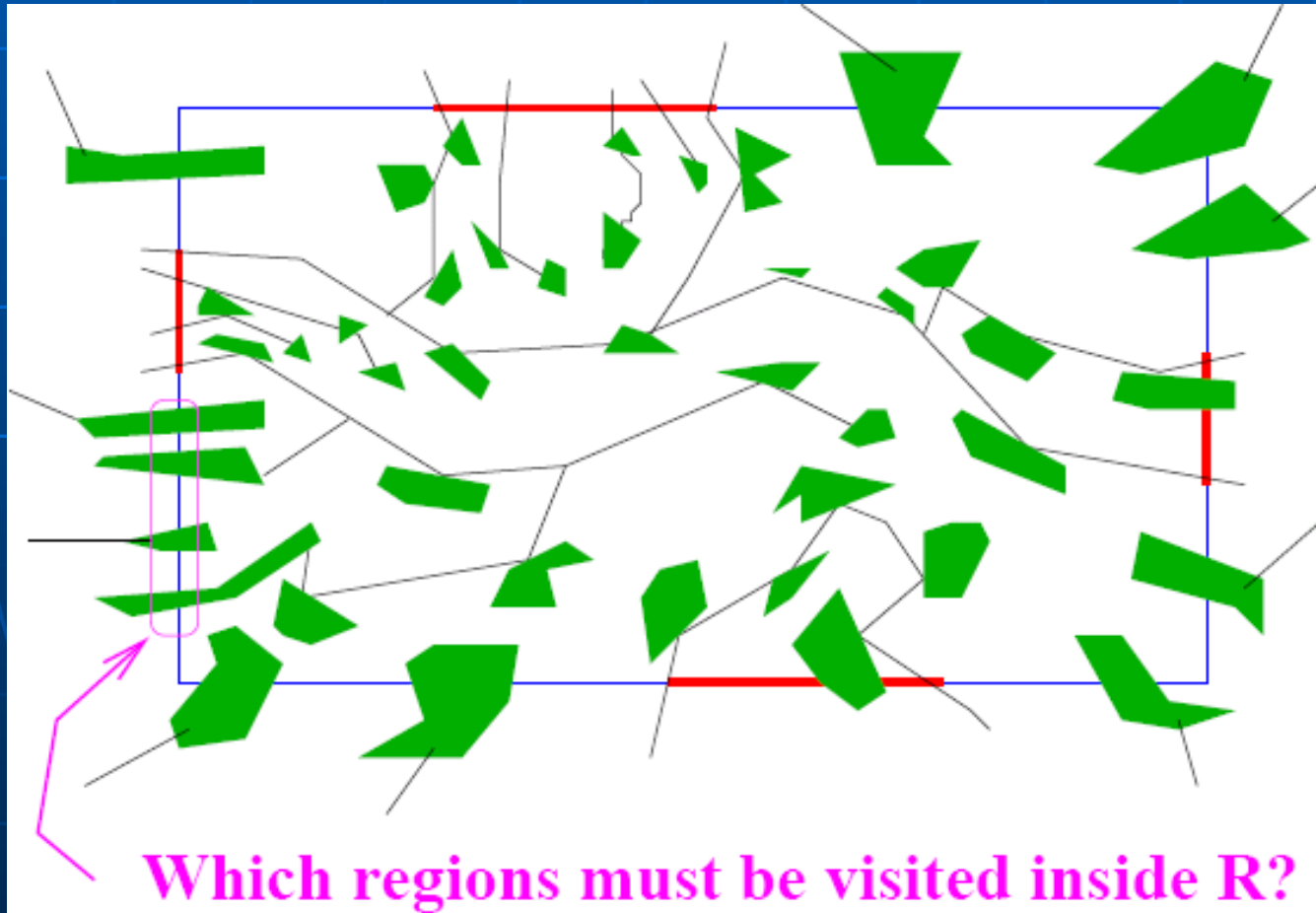
1. a rectangle $R(i, i', j, j')$, defined by $x_i, x_{i'}, y_j, y_{j'}$ $O(n^4)$
2. four sets of “boundary information”, $\Sigma_l, \Sigma_r, \Sigma_b$, and Σ_t ,
determined by $\leq 2m$ endpoints on each side $O((n^{2m})^4)$
3. a partition, \mathcal{P} , of $\cup_{\alpha} \Sigma_{\alpha}$, giving required connectivity among
boundary pieces $O(1)$

Objective: Find min-length m -guillotine subdivision, S_G^* (edges E_G^* interior to $R(i, i', j, j')$), such that E_G^* covers P and E_G^* connects the boundary pieces, according to partition \mathcal{P} .



Difficulty in Applying TSP Methods to TSPN / MSTN

Consider a subproblem (rectangle):



New Structure

- Build **region-bridges** in order to encode succinctly which regions are the “responsibility” of a subproblem
- Cannot afford to build **m**-region-bridges for **$m = O(1/\epsilon)$** , constant wrt **n** .
- But *can* afford to build **M**-region-bridges, with **$M = O((1/\epsilon)\log n)$** and this is “just right”, since the remaining **M** bridges that are not part of the bridge can be specified in the subproblem: **$2^M = 2^{O(\log n)}$** is **poly(n)**

Bridges

$m = 4$

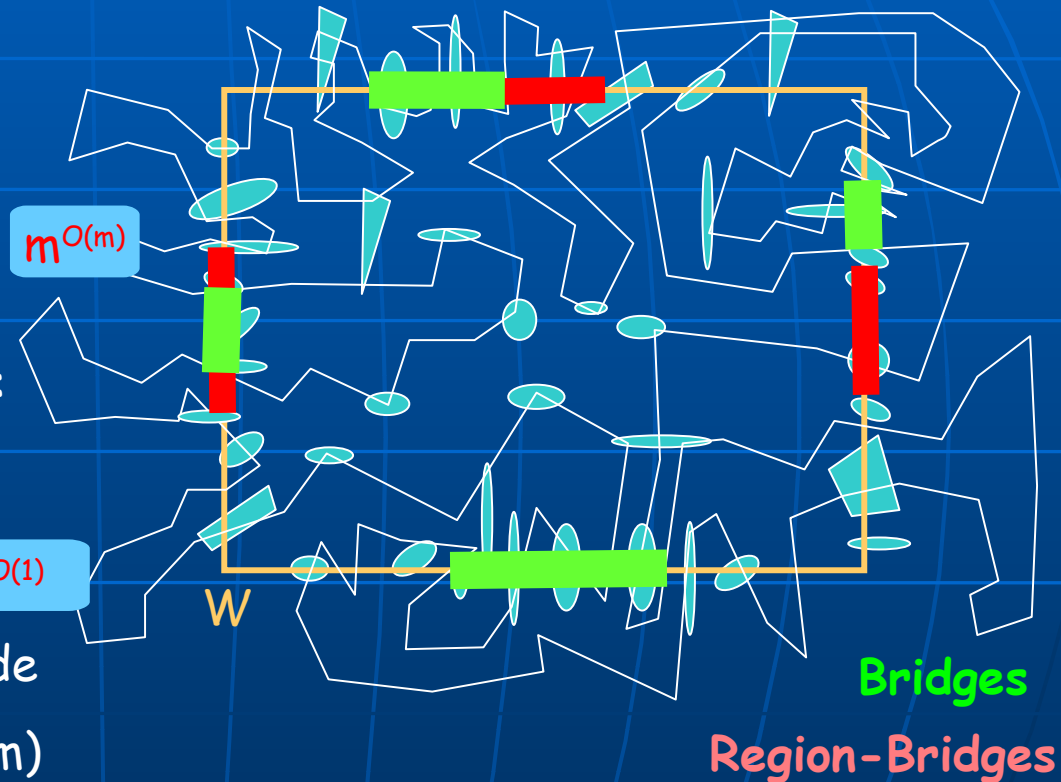
$$m = 4$$

$M=3$

Subproblem Optimization

Specification of a subproblem:

1. Window W n^4
2. ≤ 4 Bridges, $\leq 2m$ segs/side of W $m^{O(m)}$
3. ≤ 4 Region-Bridges, one bit per $\leq 8M$ non-bridged crossing region:
Is the subproblem responsible to visit?
 $n^{O(1)} + 2^{O((1/\epsilon)\log n)} = n^{O(m)}$
4. Protruding regions not in R_{w_0} specified by ≤ 2 sequences per side $n^{O(1)}$
5. Connection pattern among the $O(m)$ segs crossing into W $m^{O(m)}$



Total # subproblems = $n^{O(m)}$

$$m = 1/\epsilon$$

$$M = (1/\epsilon) \log n$$

and $n^{O(m)}$ choices for the best horiz/vertical cut, in DP optimization

(m,M) -Guillotine Structure

Definition: Network edge set E is (m,M) -guillotine if it can be recursively partitioned by horiz/vertical cuts, each containing the " m -span" (**bridge**) of E and the " M -region-span" (**region-bridge**) of the set of regions.

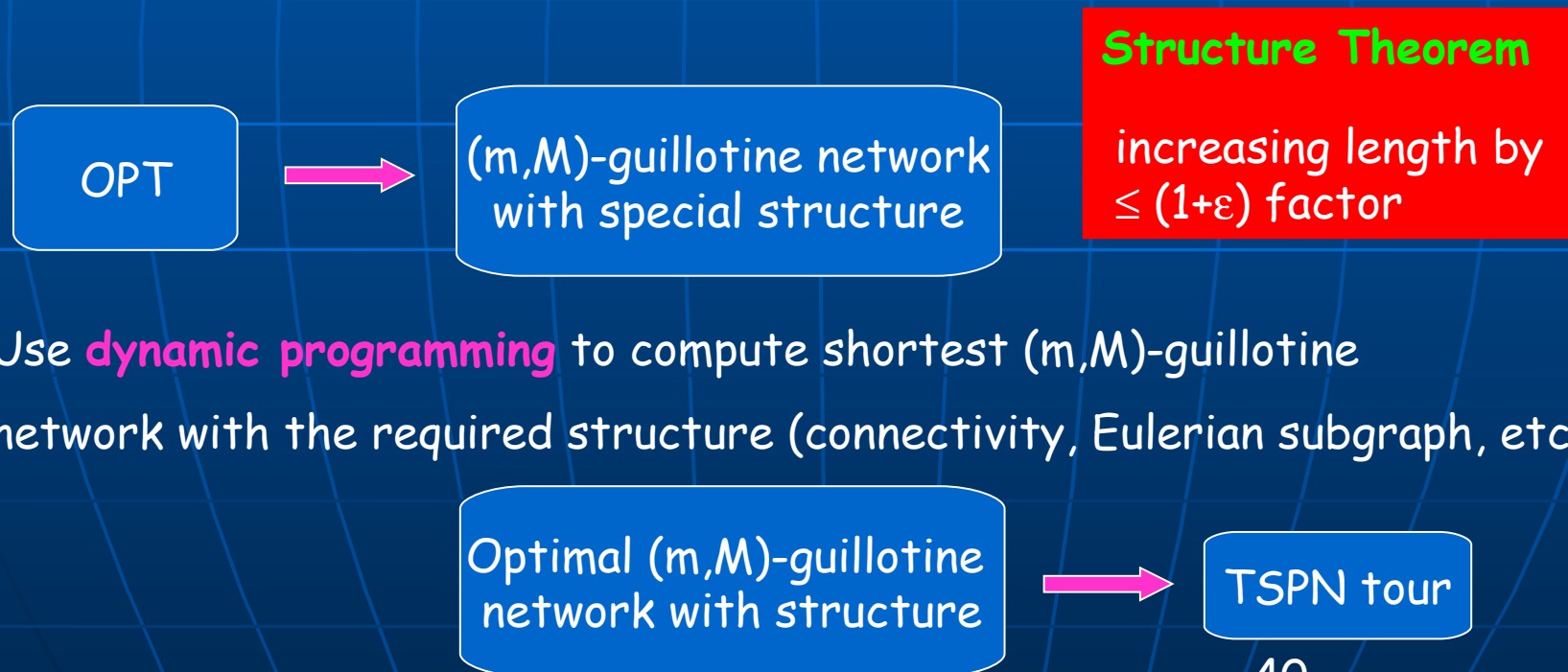
What the DP Computes

Minimum-length network that is

1. (m,M) -guillotine wrt window W_0 and regions R_{W_0}
2. Connected
3. Containing an Eulerian spanning subnetwork
4. Spanning (visits all regions)

Main Idea of PTAS

Use m -guillotine PTAS method, with new structure to address difficulty with TSPN



New Structure Theorem

Theorem: Let E be a connected set of edges of length L , spanning all regions. Then, for any positive integers m and M , there is a superset, E' , of E , of length at most $L + (\sqrt{2}/m) L + (\sqrt{2}/M) \lambda(R_{w_0})$.

We pick $M = (1/\varepsilon) \log n$, and $m = 1/\varepsilon$

Sum of region diameters

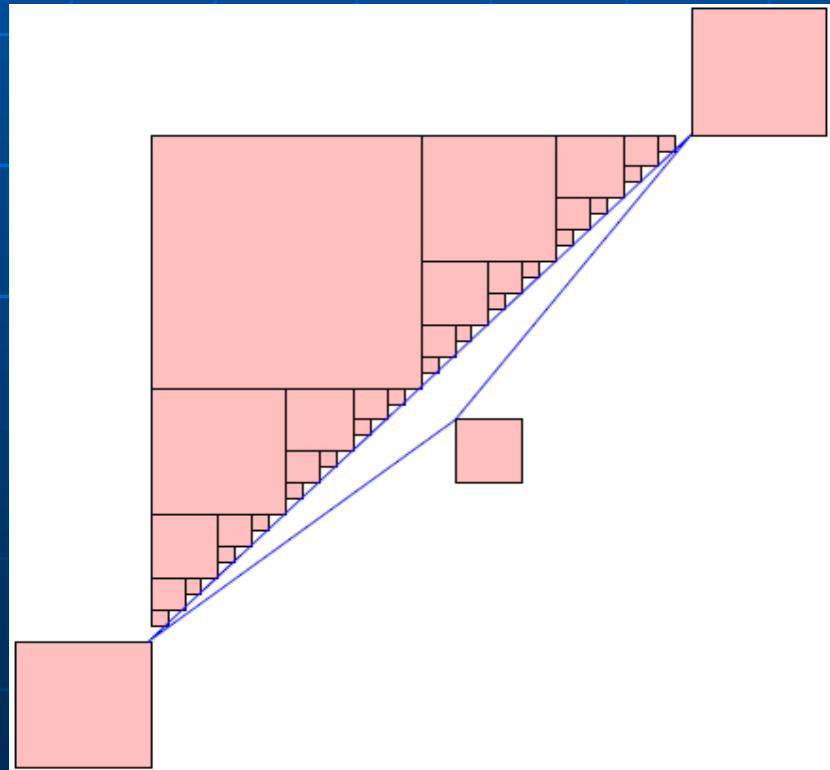
Then, by the Key Lemma, we see that T^* can be converted to be (m, M) -guillotine, adding length $O(T^*/\varepsilon)$

Key Lemma: $L^* \geq C \lambda(R_{w_0}) / \log n$

Key Geometric Observation

The sum of the perimeters of a set of n disjoint fat regions that are visited by a path of length L is at most $O(L \log n)$

Uses **PACKING** argument



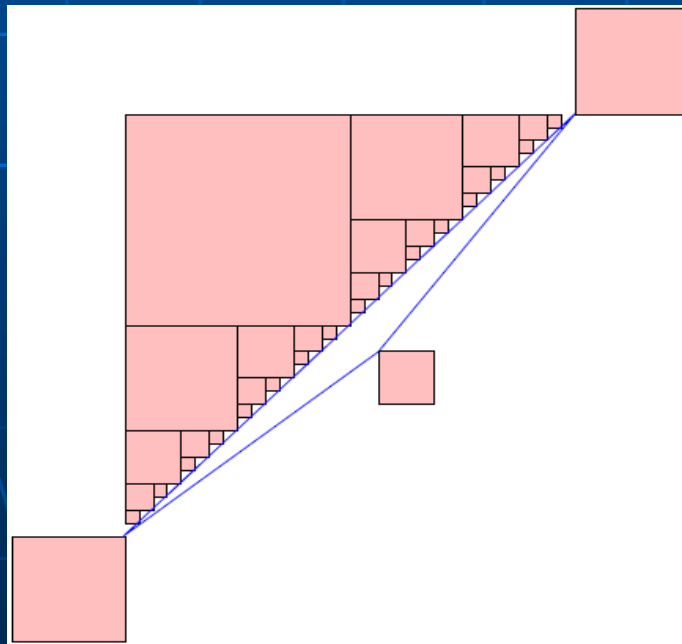
Ex: Bound is tight

Key Lemma: Lower Bound on OPT

Key Lemma: $L^* \geq C \lambda(R_{w_0}) / \log n$

Relates tour length of OPT, L^* , to sum of diameters, $\lambda(R_{w_0})$

Ex: Tight



$$L^* = \Omega(\lambda(R_{w_0}) / \log n)$$

Proof of Key Lemma

Cluster regions by size (diameter), into $\log(n/\varepsilon)$ classes

There are n_i regions with diameter in range $(d_i/2, d_i)$

Area (packing) argument:

Let $A_i = \text{area}(\mathcal{T}^* \oplus B(d_i)) \cap W_0$

Minkowski sum with ball of radius d_i

This is where fatness and disjointness are used!

By **fatness**, $A_i \geq C_0 d_i^2 n_i$, for some constant C_0

Thus, by **Claim** below, $C_0 d_i^2 n_i \leq 2d_i L^*$, or $L^* \geq (C_0/2) d_i n_i$

Summing on i , we get $L^* \geq C \lambda(R_{W_0}) / \log n$

Claim: $A_i \leq 2d_i L^*$

Bucketing Regions by Size

- Consider each minimal covering AAB, W_0 , snapped to grid (only $O(n^4)$ of them)
- R_{W_0} = regions fully within W_0 (each has diameter $O(D)$)
- Partition R_{W_0} into $K = O(\log(D/\delta)) = O(\log(n/\epsilon))$ classes according to the diameters falling in ranges:

$(0, \delta)$ $(\delta, 2\delta)$ $(2\delta, 4\delta)$ $(4\delta, 8\delta)$... $(2^{i-1}\delta, 2^i\delta)$... $(2^{K-2}\delta, 2^{K-1}\delta)$

Class i

$$d_i = 2^i \delta$$

$$\delta = \epsilon D / n$$

Can shrink to single grid points, by Grid Lemma

Proof of Claim

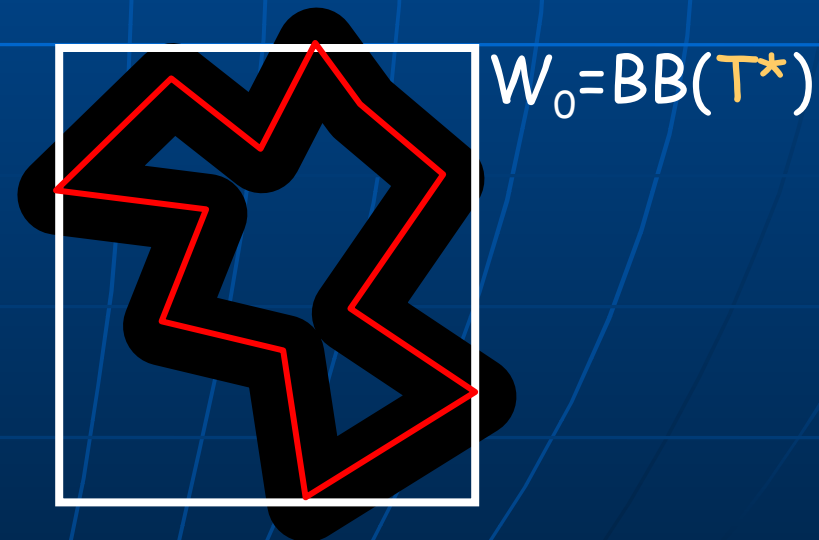
Claim: $A_i = \text{area}((\mathcal{T}^* \oplus B(d_i)) \cap W_0) \leq 2d_i L^*$

Minkowski sum with ball of radius d_i

Proof:

$$\text{area}(\mathcal{T}^* \oplus B(d_i)) \leq 2d_i L^* + \pi d_i^2$$

That portion within W_0
does not include (at least)
the area, πd_i^2



Main Result

Theorem: TSPN for disjoint fat regions has a PTAS.

PTAS also for the case of nondisjoint regions, if there are disjoint disks β_1, \dots, β_n , with $\beta_i \cap P_i$ and $\text{diam}(P_i)/\text{diam}(\beta_i) < C$.

Improve running time to $O(n^C)$, with C independent of $1/\varepsilon$: use grid-rounded guillotine subdivisions.

Generalizations/Extensions

- Disconnected regions: sets of points/regions that are within a “nice” set of regions
- k -TSPN
- Steiner MST with Neighborhoods
- MST with Neighborhoods (MSTN)
- k -MSTN

Approximation of 2D TSPN: Connected Regions

Fat Regions

non-Fat Regions

Comparable
sizes

Arbitrary
size

<p>Disjoint PTAS</p> <p>Newest PTAS $O(1)$</p> <p>Non-Disjoint</p>	<p>Disjoint $O(1)$</p> <p>$O(1)$ APX-hard</p> <p>Non-Disjoint</p>
<p>Disjoint $O(1)$ New PTAS</p> <p>Newest $O(1)$, PTAS? $O(\log n)$</p> <p>Non-Disjoint</p>	<p>Disjoint $O(\log n)$</p> <p>$O(\log n)$ APX-hard</p> <p>Non-Disjoint</p>

Conjecture:
PTAS for all

Conjecture:
 $O(1)$ for all

Laundry List of Problems

■ Know PTAS

- TSP, k-TSP, Steiner MST, k-MST
- Red-blue separation
- Min-weight convex subdivision
- TSPN, fat regions
- Orienteering problem
- Lawnmowing problem

■ OPEN: PTAS?

- TSPN, disjoint regions in 2D
- Vehicle routing; min-weight cover with k-tours
- Deg-3, deg-4 spanning trees
- Min-weight triangulation
- Watchman route problem
- Min-area triangulated surface; special case: terrain