

A survey of results about G_2 conifolds

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Results include separate joint works with
Jason Lotay (University College London)
Dominic Joyce (University of Oxford).

G₂ manifolds

Manifolds with G₂ structure

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Let M^7 be a smooth 7-manifold. A **G₂ structure** on M is a reduction of the structure group of the frame bundle from $GL(7, \mathbb{R})$ to $G_2 \subset SO(7)$.

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- A G₂ structure exists if and only if M is *orientable* and *spin*, which is equivalent to $w_1(M) = 0$ and $w_2(M) = 0$.
- A G₂ structure is encoded by a “non-degenerate” 3-form φ which nonlinearly determines a Riemannian metric g_φ and an orientation. We thus have a Hodge star operator $*_\varphi$ and dual 4-form $\psi = *_\varphi \varphi$.

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- On a manifold (M, φ) with G₂ structure, each tangent space $T_p M$ can be canonically identified with the *imaginary octonions* $\mathbb{O} \cong \mathbb{R}^7$.

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Properties of G_2 manifolds:

- The holonomy $\text{Hol}(g_\varphi)$ is contained in G_2 . If $\text{Hol}(g_\varphi) = G_2$, then (M, φ) is called an **irreducible** G_2 manifold. A *compact* G_2 manifold is irreducible if and only if $\pi_1(M)$ is finite.

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- The metric g_φ is **Ricci-flat**.
- G₂ manifolds admit a parallel spinor. They play the role in M-theory that Calabi-Yau 3-folds play in string theory.
- A G₂ structure is torsion-free if and only if $d\varphi = 0$ and $d*_\varphi\varphi = 0$. (Fernàndez–Gray, 1982.) Both φ and $*_\varphi\varphi$ are **calibrations**.

Comparison with Kähler and Calabi-Yau geometry

- G₂ manifolds are very similar to Kähler manifolds.
- Both admit **calibrated** *submanifolds* and *connections*.
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- Both admit **calibrated** *submanifolds* and *connections*.
- Both admit a Dolbeault-type decomposition of their cohomology, which implies restrictions on the topology.
- **However**, unlike G₂ manifolds, *not all* Kähler manifolds are Ricci-flat. Those are the *Calabi-Yau* manifolds.
- By the Calabi-Yau theorem, we have a topological characterization of the Ricci-flat Kähler manifolds.
- We are still *very far* from knowing sufficient topological conditions for existence of a torsion-free G₂ structure.

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- In Kähler geometry, the Kähler form ω and the complex structure J are essentially independent. Together they determine the metric g .
- Therefore, Kähler geometry can be thought of as ‘decoupling’ into complex geometry and symplectic geometry.
- **However**, if M admits a G₂ structure, the 3-form φ determines the metric g in a nonlinear way:

$$(u \lrcorner \varphi) \wedge (v \lrcorner \varphi) \wedge \varphi = C g_\varphi(u, v) \text{vol}_\varphi$$

- Thus, we cannot ‘decouple’ G₂ geometry in any way.

Examples of G₂ manifolds

Complete noncompact examples

- Bryant–Salamon (1989): these examples are total spaces of vector bundles $\Lambda_-^2(S^4)$, $\Lambda_-^2(\mathbb{C}\mathbb{P}^2)$, $\mathcal{S}(S^3)$; they are all **asymptotically conical**: far away from the base of the bundle, they “look like” *metric cones*.
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- These examples are all explicit **cohomogeneity one** G₂ manifolds — they have enough “symmetry” so that the nonlinear PDE reduces to a system of fully nonlinear ODEs, which can often be solved exactly.

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- These examples are all explicit **cohomogeneity one** G₂ manifolds — they have enough “symmetry” so that the nonlinear PDE reduces to a system of fully nonlinear ODEs, which can often be solved exactly.
- It can be shown (using the Bochner–Weitzenböck formula) that *compact* examples cannot have *any* symmetry. So the construction of compact examples is necessarily much more difficult.

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- Joyce–Karigiannis (2013?) — glueing a 3-dimensional family of Eguchi–Hanson spaces

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Let M be a compact manifold with a *closed* G₂ structure φ such that the torsion is sufficiently small. (One needs good control of the L^{14} norm of the torsion and some other estimates.) Then there exists a *torsion-free* G₂ structure $\tilde{\varphi}$ close to φ in the C^0 norm, with $[\tilde{\varphi}] = [\varphi]$ in $H^3(M, \mathbb{R})$.

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These constructions provide thousands of examples, but they are likely only a *very small part of the* “landscape.”

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Ingredients [2] and [3] require compactness of M , and thus need to be modified in any noncompact setting.

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G₂ cones

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A **G₂ cone** is a 7-manifold $C = (0, \infty) \times \Sigma$, with Σ compact, and a torsion-free G₂ structure φ_C with induced metric

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- The *link* Σ of a G₂ cone C is necessarily a compact **strictly nearly Kähler** 6-manifold (also called a *Gray manifold*.)
- These are almost Hermitian manifolds (Σ, J, g, ω) with $c_1(\Sigma) = 0$, such that

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- There are **only three known compact examples**, all homogeneous, but there are expected to exist *many examples*.

Asymptotically conical (AC) G₂ manifolds

Definition

We say (N, φ_N) is an **AC G₂ manifold** of rate $\nu < 0$, asymptotic to the G₂ cone (C, φ_C) , if outside of a compact set $K \subseteq N$, we have $N \setminus K \cong (R, \infty) \times \Sigma$, and

$$\nabla^k(\varphi_N - \varphi_C) = O(r^{\nu-k}) \text{ as } r \rightarrow \infty \quad \forall k \geq 0$$

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- There are three known examples, the Bryant–Salamon manifolds, asymptotic to the three known G₂ cones.
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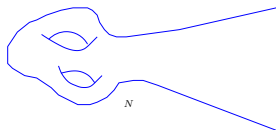
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Conically singular (CS) G₂ manifolds

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Let \overline{M} be a topological space with $M = \overline{M} \setminus \{x_1, \dots, x_n\}$ a noncompact smooth 7-manifold. We say (M, φ_M) is an **CS G₂ manifold** of rate (ν_1, \dots, ν_n) , where $\nu_i > 0$, asymptotic to the G₂ cones (C_i, φ_{C_i}) , if outside of a compact set $K \subseteq M$, we have $M \setminus K \cong \bigsqcup_{i=1}^n (0, R) \times \Sigma_i$, and

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where r_i is the distance to the vertex of C_i .

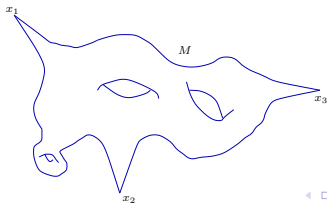
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- One way to show this, and thus to provide evidence for their likely existence, is to prove that they would *often* be **desingularizable** into families of compact smooth G₂ manifolds.
- A way to desingularize them is to cut out a neighbourhood of the singular points, and **glue** in AC G₂ *manifolds*, such as the Bryant–Salamon examples.

Desingularization of CS G₂ manifolds

Theorem (Karigiannis, Geometry & Topology, 2009)

Let M be a CS G₂ manifold with isolated conical singularities x_1, \dots, x_n , modelled on G₂ cones C_1, \dots, C_n . Suppose that N_1, \dots, N_n are AC G₂ manifolds modelled on the same G₂ cones, with all rates $\nu_i \leq -3$.

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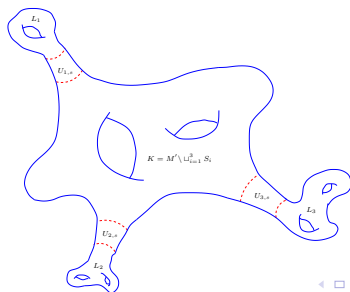
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There are natural maps $\Upsilon^k : H^k(M) \rightarrow \bigoplus_{i=1}^n H^k(\Sigma_i)$. Let $K_i(\lambda)$ be the space of *homogeneous* closed and coclosed 3-forms on C_i of rate λ .

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- In the AC case with $\nu < -4$, the moduli space may be obstructed, and its virtual dimension $\nu\text{-dim } \mathcal{M}_\nu$ is

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- The proof uses the Lockhart–McOwen machinery of weighted Sobolev spaces and its associated Fredholm theory, plus new Hodge-theoretic results in this context, and other G₂ specific ingredients (surjectivity of Dirac operator, L^2 harmonic 1-forms are parallel, more ...)

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- [4] Statements [2] and [3] will be true *in general* if certain conjectures about the spectrum of the Laplacian on forms are true for *all* compact strictly nearly Kähler 6-manifolds.

A new construction of compact G_2 manifolds

(which may possibly generalize to construct compact CS G_2 manifolds)

[Step 1] Construct an orbifold \widehat{M}

- Let $(N^6, g, \omega, \Omega, J)$ be a compact Calabi-Yau manifold admitting an *antiholomorphic isometric involution* τ :

$$\tau^*(g) = g, \quad \tau^*(\omega) = -\omega, \quad \tau^*(\Omega) = \overline{\Omega}, \quad \tau^*(J) = -J.$$

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- Define $M^7 = N^6 \times S^1$. Then

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- Define $\sigma : M \rightarrow M$ by $\sigma(p, \theta) = (\tau(p), -\theta)$. Then σ is an involution of M such that $\sigma^*(\varphi) = \varphi$. The quotient space $\widehat{M} = M/\langle\sigma\rangle$ is a **G_2 orbifold**, with singularities locally of the form $\mathbb{R}^3 \times (\mathbb{C}^2/\{\pm 1\})$.

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- The singular set $L^3 = A^3 \times \{\pm 1\}$, where $A^3 = \operatorname{Fix}(\tau)$ is a compact **special Lagrangian submanifold** of N^6 , and L is totally geodesic in M .

[Step 2] Glue in a family of Eguchi-Hanson spaces

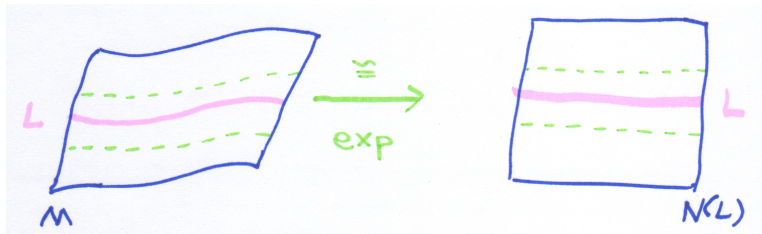
- We want to cut out a neighbourhood of the singular locus L in \widehat{M} and glue in a noncompact smooth manifold to get a smooth compact 7-manifold \widetilde{M} , which hopefully will admit a *closed G_2 structure with small enough torsion*, to to apply Joyce's existence theorem.

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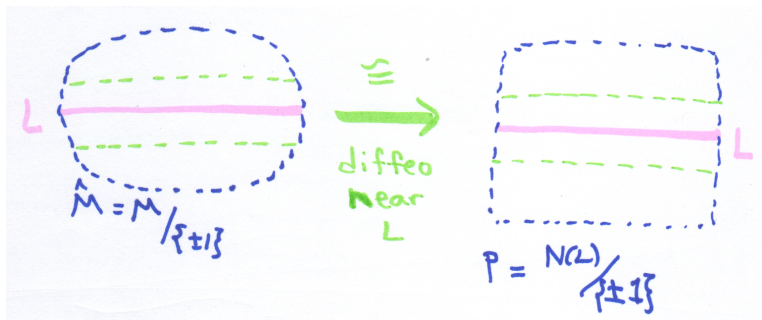
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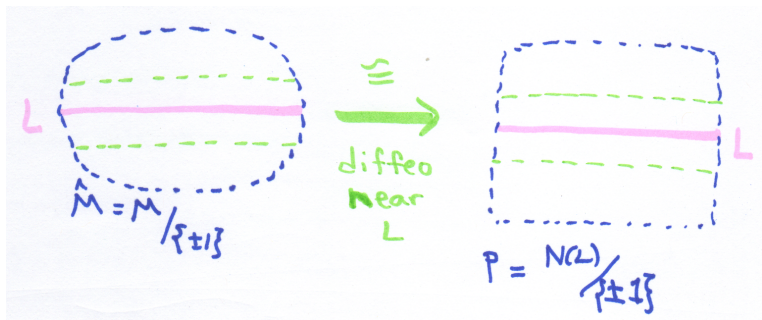


- The submanifold L is an **associative submanifold**. This implies that, given a nonvanishing 1-form α on L , the normal bundle $N(L)$ is actually a \mathbb{C}^2 **bundle** over L , and the above diffeomorphism descends to identify \widehat{M} with $P = N(L)/\{\pm 1\}$ near L .

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- The fibres of $P = N(L)/\{\pm 1\}$ are $\mathbb{C}^2/\{\pm 1\}$. We resolve P to \widetilde{P} with a 'fibre-wise blow-up', replacing each fibre with $\widetilde{\mathbb{C}^2/\{\pm 1\}} \cong T^*S^2$.

- Each fibre T^*S^2 admits an $S^2 \times (0, \infty)$ family of *Eguchi-Hanson metrics* (holonomy $SU(2)$ metrics) that are parametrized by a choice of complex structure on $\mathbb{R}^4 = \mathbb{H}$ (a unit vector in \mathbb{R}^3) and a scaling.

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- If $N(L)$ is trivial, then $P = N(L)/\{\pm 1\} \cong L \times (\mathbb{C}^2/\{\pm 1\})$. If in addition $L \cong T^3$, then we could take *any* E-H metric on T^*S^2 and the resolution $\tilde{P} \cong L \times T^*S^2$ would admit a torsion-free G_2 structure.

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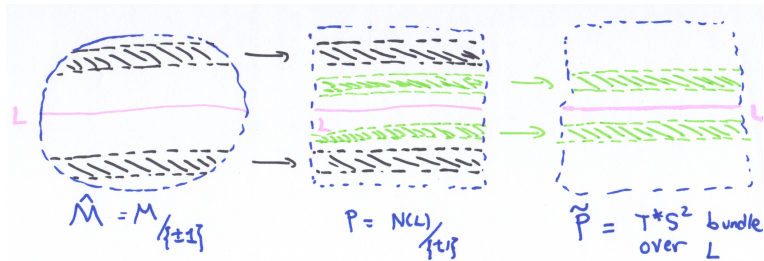
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- We can use α to construct a closed G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} with small torsion, but for the torsion to have any chance of being small enough, **it is necessary that $d\alpha = 0$ and $d^*\alpha = 0$** . For now, let us assume that we have such a nowhere vanishing harmonic 1-form α .

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- We construct a compact smooth manifold \tilde{M} as follows. Far from the zero section, identify P with \hat{M} using the *exponential map*. Close to the zero section, identify P with \tilde{P} using the *resolution map*.

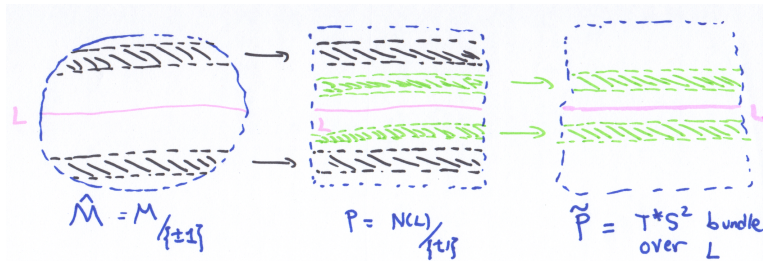
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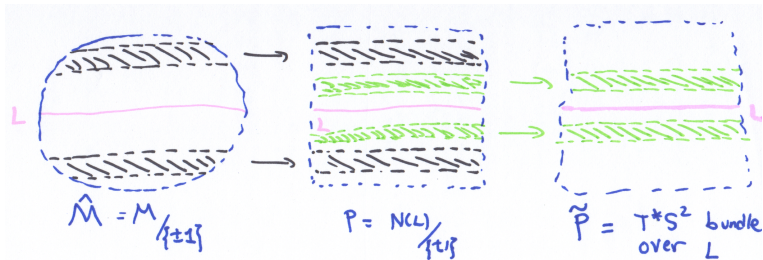
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- We want to construct a closed G_2 structure $\tilde{\varphi}$ on \tilde{M} by interpolating between $\varphi_{\hat{M}}$ and $\varphi_{\tilde{P}}$ using $\bar{\varphi}$. We use the metric \bar{g} of $\bar{\varphi}$ to measure the torsion of $\tilde{\varphi}$, since we cannot compare \hat{M} and \tilde{P} directly.

- In fact, the G_2 structures $\bar{\varphi}$ on P and $\varphi_{\tilde{P}}$ on \tilde{P} are *not closed*, so these have to be slightly modified, using smooth cut-off functions, to “closed versions” before we can construct $\tilde{\varphi}$ on \tilde{M} by interpolation.

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 - We need to perform two *corrections* to solve these problems.

[Step 4] 1st correction: bend horizontal and vertical

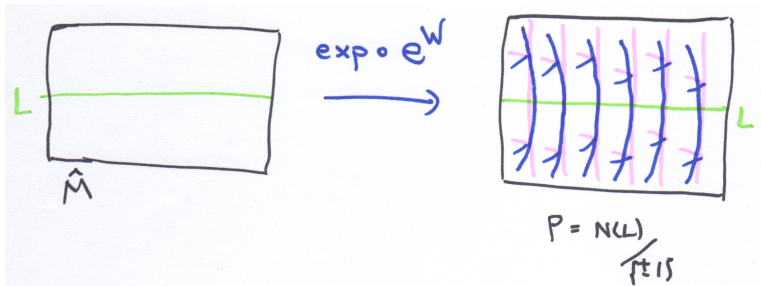
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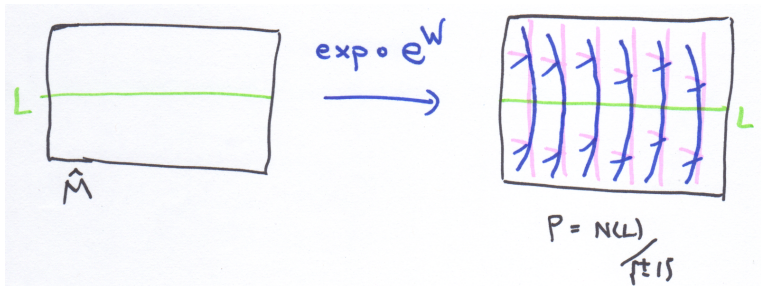
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- These can in fact be chosen to make $\bar{\varphi}$ close enough to φ_M .

[Step 5] 2nd correction: solving a PDE on E-H space

- We also need to modify the G_2 structure $\varphi_{\tilde{P}}$ on \tilde{P} in order to make the torsion of $\tilde{\varphi}$ on \tilde{M} small enough to apply Joyce's theorem.

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- This is done using Lockhart–McOwen theory of Fredholm operators on noncompact manifolds with “well-behaved” geometry at infinity.
- The theory says that such an equation can be solved if and only if σ has appropriate asymptotic behaviour at infinity, which it does.

Remarks on the construction

- Our construction is more general. We can take any G_2 manifold M admitting an involution σ such that $\sigma^*(\varphi) = \varphi$. Then $L = \text{Fix}(\sigma)$ is an associative submanifold and everything proceeds as before.

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However, if N is near the “large complex structure limit” of the moduli space, from mirror symmetry arguments we expect it to contain a special Lagrangian torus that is *close to being flat*, so it will admit such 1-forms.

- Generically, a harmonic 1-form α on L has isolated zeroes. Then we can resolve M to \tilde{M} except for a finite number of singular points. In fact, near the singular points, \tilde{M} is *topologically* a cone over $\mathbb{C}\mathbb{P}^3$.

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This is work in progress.

Happy birthday, Blaine!