

>

```
> phug:= R->[diff(theta(t),t) = (v(t)^2-cos(theta(t)))/v(t),  
diff(v(t),t) = -sin(theta(t)) - R*v(t)^2 ];
```

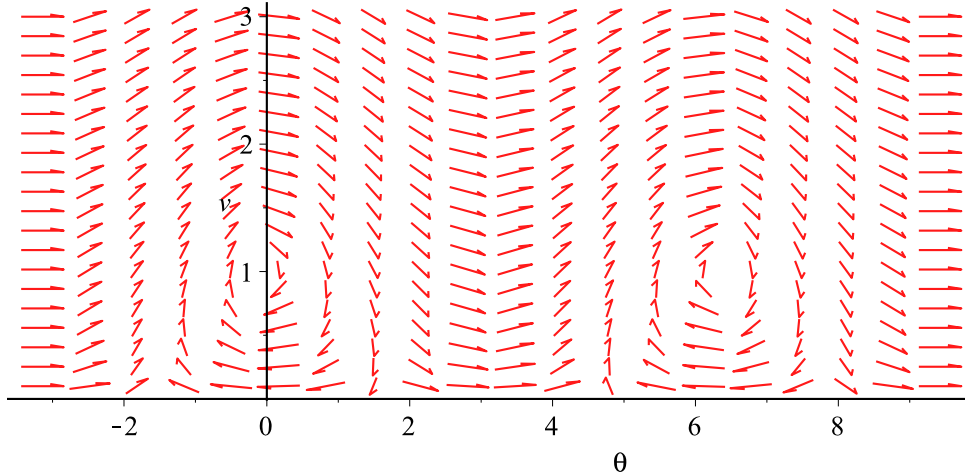
$$phug := R \rightarrow \left[\frac{d}{dt} \theta(t) = \frac{v(t)^2 - \cos(\theta(t))}{v(t)}, \frac{d}{dt} v(t) = -\sin(\theta(t)) - R v(t)^2 \right]$$

(1)

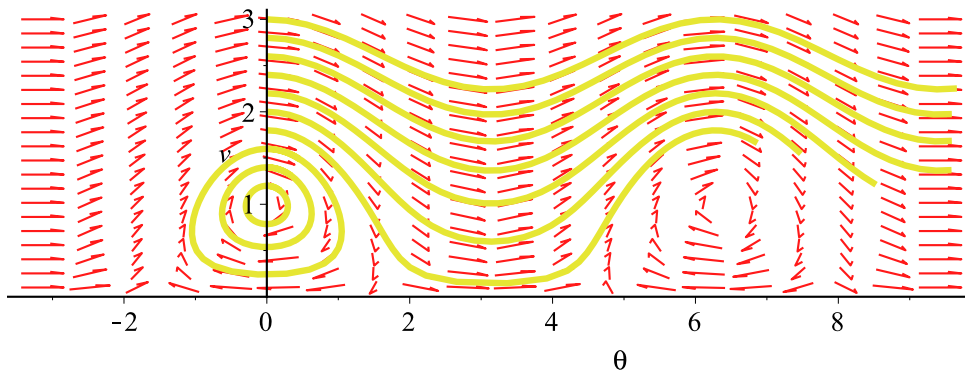
```
> with(DEtools):
```

Look at system in theta-v space with R=0

```
> DEplot(phug(0), [theta(t),v(t)], t=0..5,  
theta=-Pi..3*Pi, v=0.1..3);
```

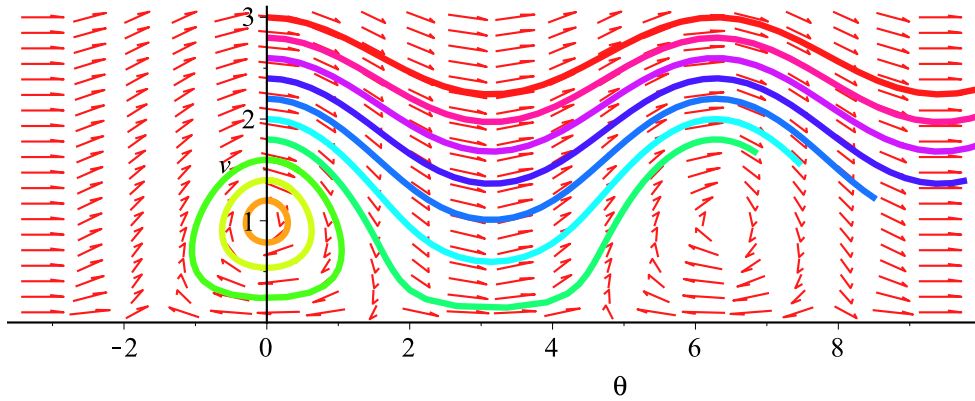


```
> DEplot(phug(0), [theta(t),v(t)], t=0..5,  
[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],  
theta=-Pi..3*Pi, v=0.1..3);
```

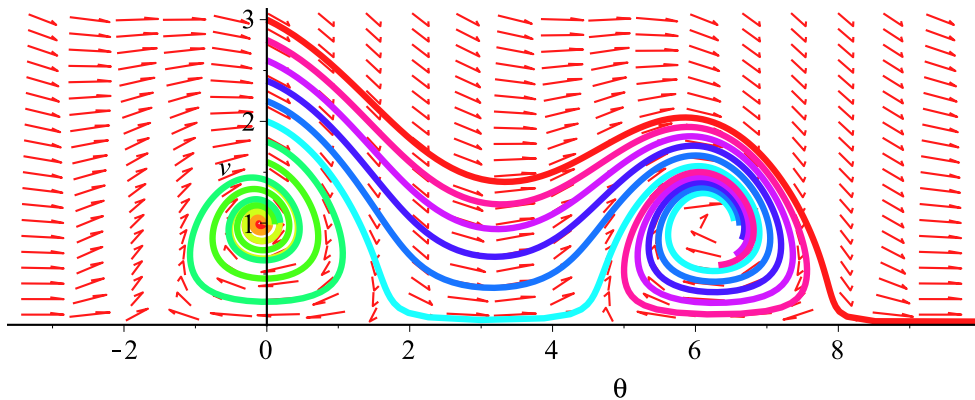


Yellow is ugly. Conditions go outside are dropped, must fix with obsrange.

```
> DEplot(phug(0), [theta(t),v(t)], t=0..5,  
[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],  
theta=-Pi..3*Pi, v=0.1..3,  
obsrange=false,  
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)]);
```



```
> DEplot(phug(0.1), [theta(t),v(t)], t=0..10,
[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],
theta=-Pi..3*Pi, v=0.1..3,
obsrange=false,
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],
numpoints=200);
```

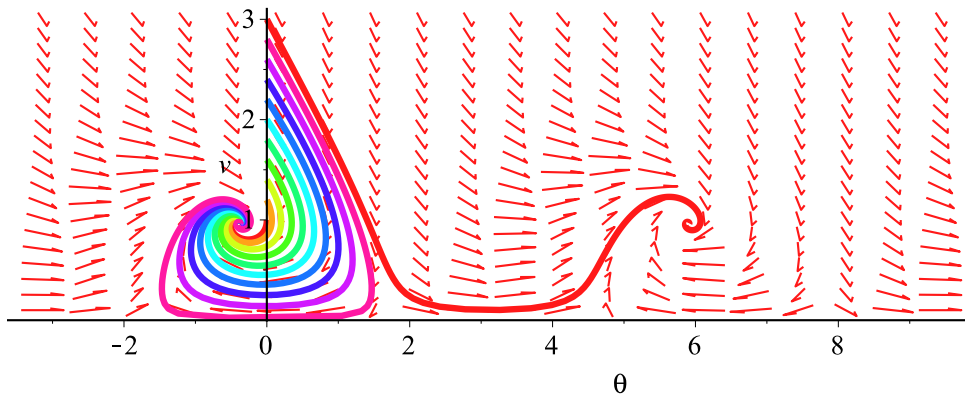


```
> phug(0.4);
```

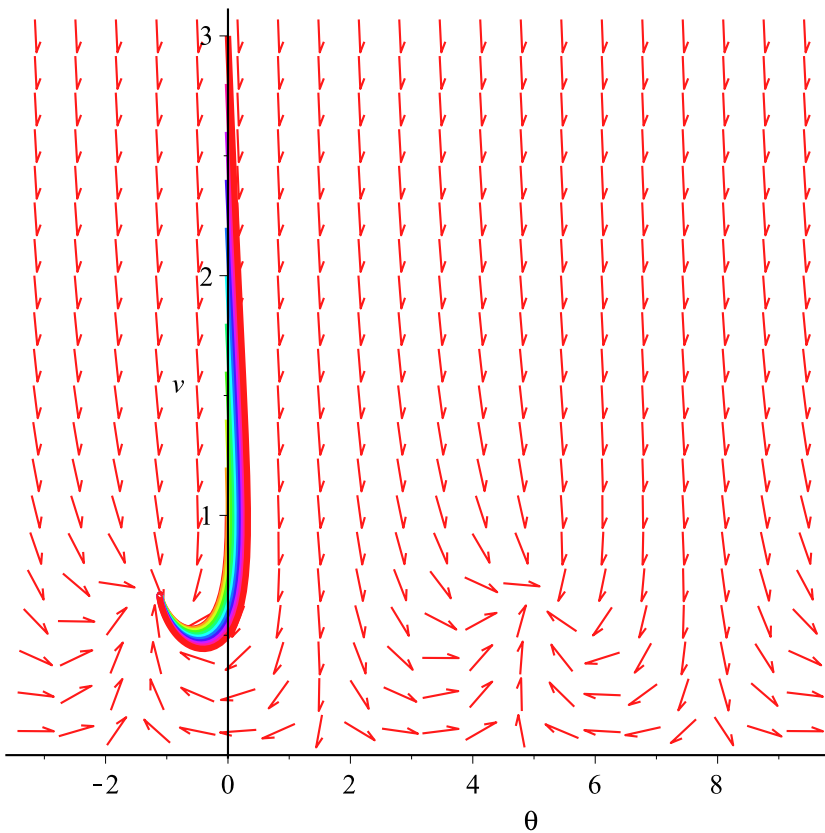
$$\left[\frac{d}{dt} \theta(t) = \frac{v(t)^2 - \cos(\theta(t))}{v(t)}, \frac{d}{dt} v(t) = -\sin(\theta(t)) - 0.4 v(t)^2 \right]$$

(2)

```
> DEplot(phug(0.4), [theta(t),v(t)], t=0..10,
[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],
theta=-Pi..3*Pi, v=0.1..3,
obsrange=false,
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],
numpoints=200);
```

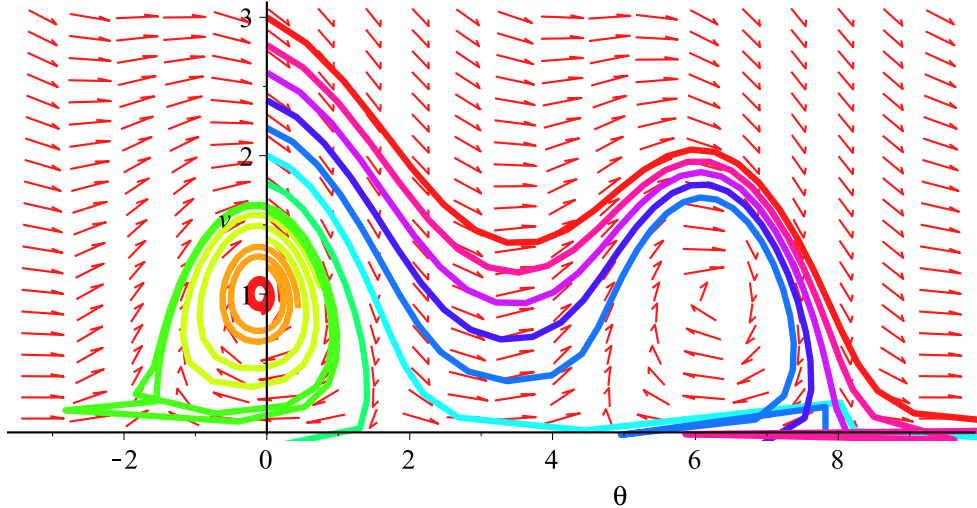


```
> DEplot(phug(2), [theta(t),v(t)], t=0..10,
  [ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],
  theta=-Pi..3*Pi, v=0.1..3,
  obrange=false,
  linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],
  numpoints=200);
```

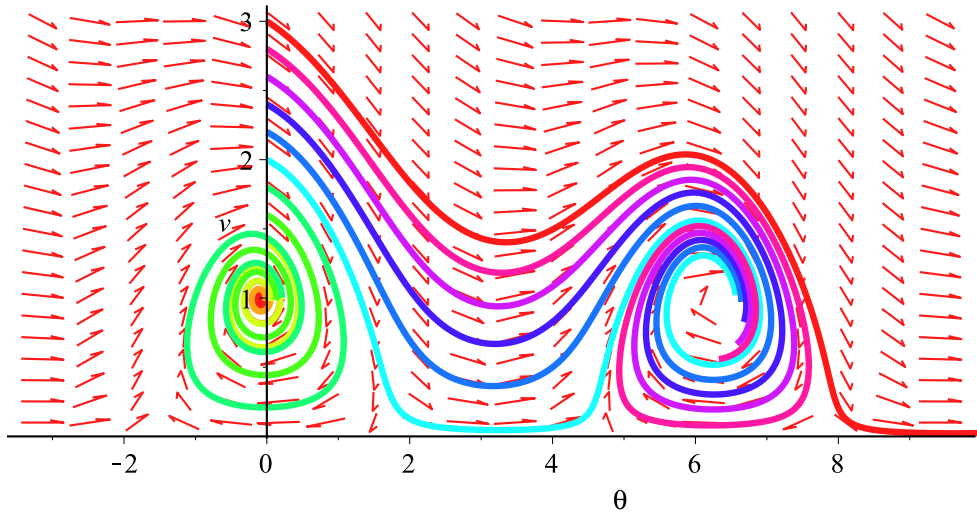


Do Euler's method for my solutions, with $R=0.1$

```
> DEplot(phug(0.1), [theta(t),v(t)], t=0..10,  
[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],  
theta=-Pi..3*Pi, v=0.1..3,  
obsrange=false,  
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],  
method=classical[foreuler]);
```



```
> DEplot(phug(0.1), [theta(t),v(t)], t=0..10,  
[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],  
theta=-Pi..3*Pi, v=0.1..3,  
obsrange=false,  
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],  
method=classical[foreuler], stepsize=0.01);
```

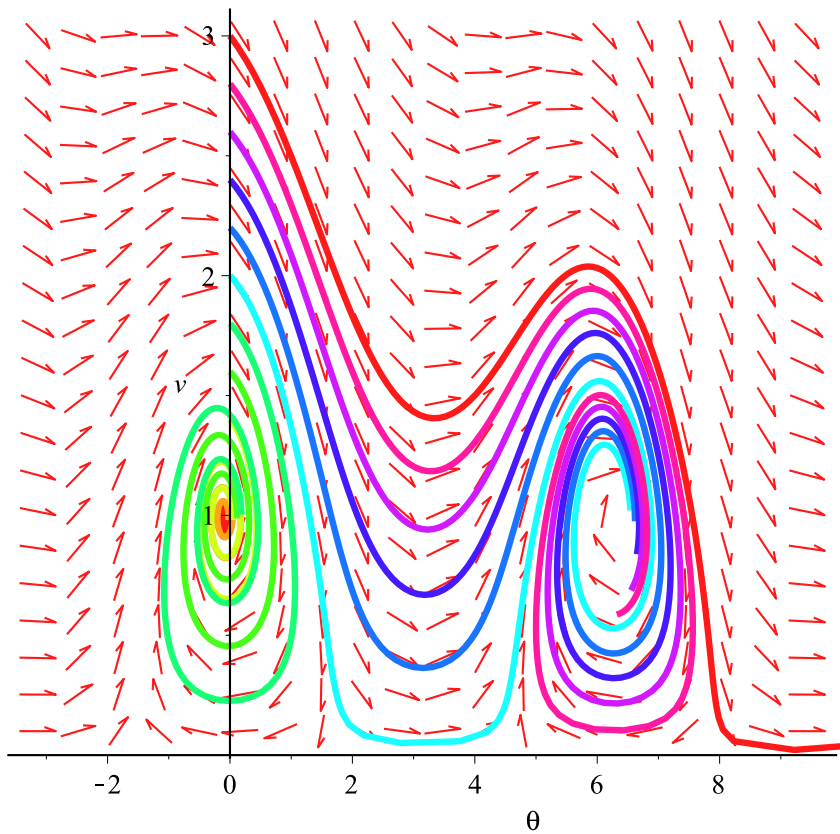


```
> DEplot(phug(0.1), [theta(t),v(t)], t=0..10,
```

```

[ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],
theta=-Pi..3*Pi, v=0.1..3,
obsrange=false,
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],
method=classical[rk4], stepsize=0.05);

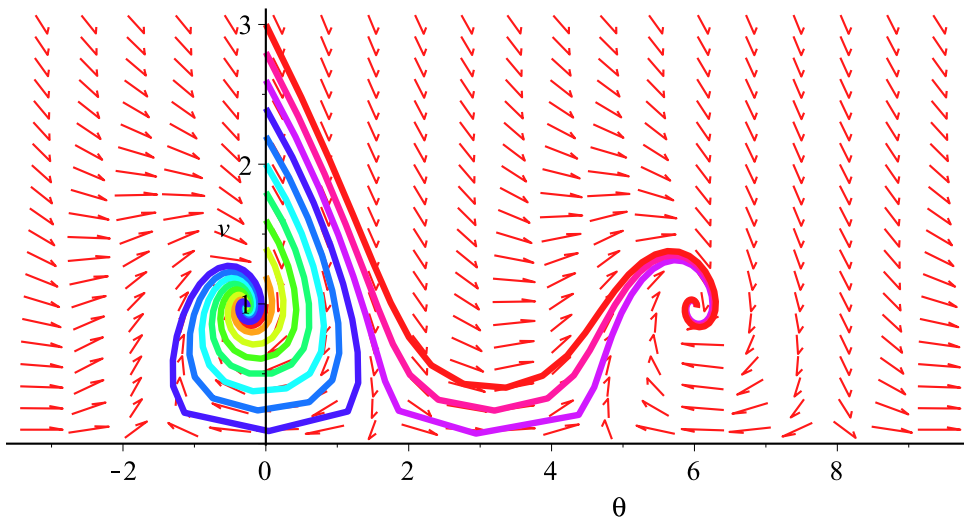
```



```

> movie:=
[seq(
  DEplot(phug(R), [theta(t),v(t)], t=0..10,
    [ seq( [ theta(0)=0, v(0)=v0], v0=1..3, .2) ],
    theta=-Pi..3*Pi, v=0.1..3,
    obsrange=false,
    linecolor=[seq(COLOR(HUE, h), h=0..1, .1)]),
    R=0..1, .05)]:
> movie[4];

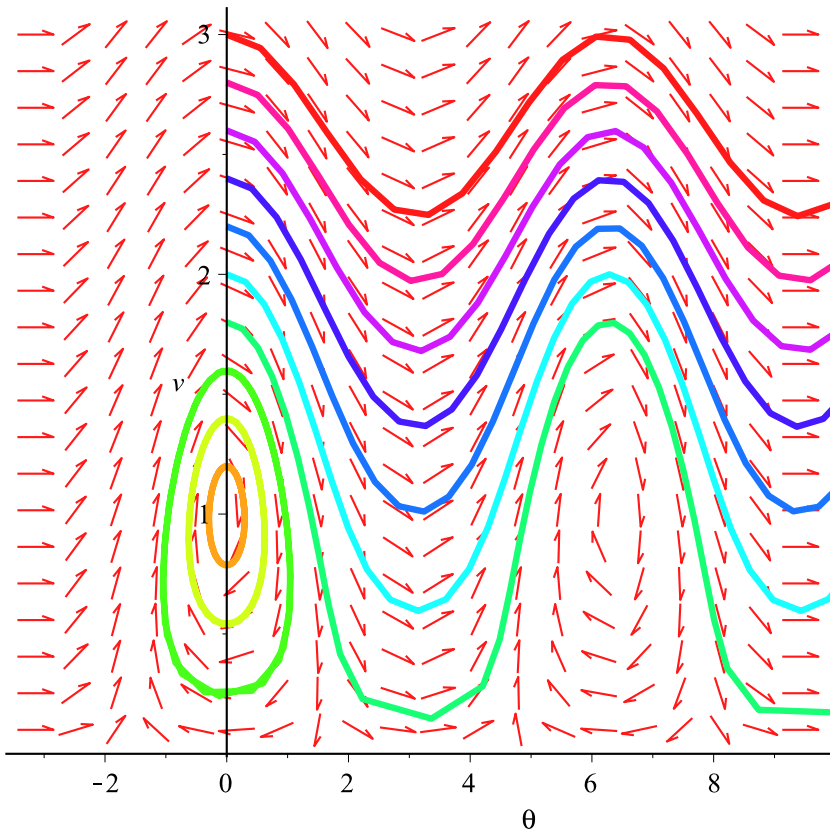
```



```

> with(plots):
> display(movie, insequence=true);

```



> phug(.2);

$$\left[\frac{d}{dt} \theta(t) = \frac{v(t)^2 - \cos(\theta(t))}{v(t)}, \frac{d}{dt} v(t) = -\sin(\theta(t)) - 0.2 v(t)^2 \right] \quad (3)$$

> xphug:= R-> [diff(theta(t),t) = (v(t)^2-cos(theta(t)))/v(t),
diff(v(t),t) = -sin(theta(t)) - R*v(t)^2 ,
diff(x(t),t) = v(t)*cos(theta(t)),
diff(y(t),t) = v(t)*sin(theta(t))];

$$xphug := R \rightarrow \left[\frac{d}{dt} \theta(t) = \frac{v(t)^2 - \cos(\theta(t))}{v(t)}, \frac{d}{dt} v(t) = -\sin(\theta(t)) - R v(t)^2, \frac{d}{dt} x(t) = v(t) \cos(\theta(t)), \frac{d}{dt} y(t) = v(t) \sin(\theta(t)) \right] \quad (4)$$

> DEplot(xphug(0.25), [theta(t),v(t),x(t),y(t)], t=0..30,
[[theta(0)=0, v(0)=3, x(0)=0, y(0)=5]],
theta=-Pi..3*Pi, v=0.1..3, x=0..10, y=0..7,
obstrange=false,
linecolor=[seq(COLOR(HUE, h), h=0..1, .1)],
scene=[x,y], numpoints=200);

