







• Describe the image of the linear transformation f(x,y)=(3x+6y,x+2y)

## Definition

Let  $v_1$ ,  $v_2$ ,...,  $v_m$  be in  $\mathbb{R}^n$ . The span of  $v_1$ ,  $v_2$ ,...,  $v_m$  is the set of all linear combinations

c1. v1+ c2. v2+...+ cm vm

We denote it by  $span(v_1, v_2, ..., v_m)$ 



Consider two vectors v and w in R<sup>n</sup>. Describe geometrically span(v) and span(v,w).

### Theorem

The image of a linear transformation T(x)=Ax is the span of the columns of A.

(Compare this theorem with the previous Example)

# Theorem: Properties of the Image

Consider a linear transformation T from  $R^{\mathsf{m}}$  to  $R^{\mathsf{n}}$ 

The zero vector is in the image.

- If x and y are in the image, then x+y is in the image.
- If x is in the image and k is an scalar, then k.x is in the image.











#### An n x n matrix A is invertible if and only if one of the following holds

- The linear system A.x=b has a unique solution.
- rref(A)=Id
- rank(A)=n
- im(A)=R<sup>n</sup>
- ker(A)={0}

## Definition

- A subset W of R<sup>n</sup> is a (linear) subspace of R<sup>n</sup> if satisfies the following
- I. W contains the zero vector.
- 2. If v and w are in W then v+w are in W.
- 3. If v is in W and k is any scalar then k.v is in W.

## EXAMPLE: Are the following sets subspaces?

- I. A line L in R<sup>2</sup>
- 2. The union of two lines in  ${\sf R}^2$
- 3. A plane in R<sup>3</sup>
- 4. {0}
- 5. The kernel and image of a linear transformation.

## Definition

Consider vectors  $v_1$ ,  $v_2$ , ...  $v_m$  in  $R^n$ .

- A vector v<sub>i</sub> is redundant if v<sub>i</sub> is a linear combination of v<sub>1</sub>, v<sub>2</sub>, ... v<sub>i-1</sub>.
- The vectors v<sub>1</sub>, v<sub>2</sub>, .. v<sub>m</sub> are linearly independent if none of them is redundant.