

MAT211 Lecture 17

Determinants.

Recall that a 2×2 matrix A

$$\begin{vmatrix} a & b \\ c & d \end{vmatrix}$$

is invertible

If and only if $a \cdot d - b \cdot c \neq 0$.

The number $a \cdot d - b \cdot c$ is the determinant of A .

Definition

A *pattern* in an $n \times n$ matrix A is a choice of entries of A , such that there is only one entry in each row and only one in each column.

Example

- Find all possible patterns in 2×2 matrices
- Find all possible patterns in 3×3 matrices.
- How many patterns are there in 4×4 matrices? And in $n \times n$ matrices?

Definition

The entries of a pattern P of a matrix A are inverted if one of them is located right and above the other in A .

The signature of a pattern P of a matrix A , denoted by $\text{sgn}(P)$ is

$$(-1)^{\text{(number of pairs of inverted entries in } P)}$$

EXAMPLE

- Find the signature of the pattern of a 3×3 matrix A ,
 a_{31}, a_{22}, a_{13}

Definition

The determinant of a square matrix A , denoted by $\det A$ is

$$\sum \text{sgn}(P) \cdot \text{product}(\text{elements in } P)$$

where the sum is taken over all patterns P .

EXAMPLE

Using the definition, compute the determinant of 2×2 and 3×3 matrices.

Sarrus rule.

Example

Compute the determinant of

$$\begin{vmatrix} 1 & 10 \\ 0 & 0 \end{vmatrix} \quad \begin{vmatrix} 1 & 10 & 2 \\ -1 & 0 & 4 \\ 5 & 6 & 6 \end{vmatrix}$$

Theorem: Consider square matrices A and B .

- If A is upper triangular then $\det(A)$ is the product of the diagonal entries of A .
- $\det(A) = \det(A^t)$
- $\det(A \cdot B) = \det(A) \cdot \det(B)$
- If A and B are similar, $\det(A) = \det(B)$.
- If A is invertible $\det(A^{-1}) = 1/\det(A)$.

Example

- Compute the determinant of the inverse of

$$\begin{vmatrix} 1 & 10 & 0 & 3 & 1 \\ 0 & -1/6 & 0 & 5 & 45 \\ 0 & 0 & 6 & 5 & 99 \\ 0 & 0 & 0 & 5 & 8 \\ 0 & 0 & 0 & 0 & 2 \end{vmatrix}$$

Theorem: Elementary row operations and determinants

- If B is obtained from A by multiplying a row of A by a scalar k then $\det(B) = k \cdot \det(A)$
- If B is obtained from A by swapping two rows then $\det(B) = -\det(A)$
- If B is obtained from A by adding a multiple of a row to another row then $\det(B) = \det(A)$.

Definition

- Consider a linear space V and a linear transformation T from V to V . The determinant of T is the determinant of the matrix of T with respect to any basis of V .

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EXAMPLE

- Find the determinant of the transformations
 - From P_2 to P_2 , $T(f)=2f- 3f'$
 - From $U^{2 \times 2}$ to $U^{2 \times 2}$ $T(M)=AM$, where A is

$$\begin{vmatrix} -1 & -10 \\ 0 & -100 \end{vmatrix}$$

Example:

Of an 4×4 matrix A with columns v_1, v_2, v_3, v_4 and determinant 4.

Compute the determinant of the matrices

$$(v_1, -30v_2, v_3, v_4)$$

$$(v_2, v_3, v_1, v_4)$$

$$(v_1, v_1 + v_2, v_1 + v_2 + v_3, v_1 + v_2 + v_3 + v_4)$$

Algorithm: Using Gauss-Jordan to compute determinant

- Consider a square matrix A . Suppose that in the process of computing $\text{rref}(A)$ one arrives to a matrix B by swapping rows s times and dividing columns by scalars k_1, k_2, \dots, k_r . Then

$$\det(A) = k_1 \cdot k_2 \cdot \dots \cdot k_r \cdot \det(B).$$
 In particular, if $B = \text{rref}(A)$

$$\det(A) = k_1 \cdot k_2 \cdot \dots \cdot k_r.$$

EXAMPLE 5.2-9

- Compute the determinant using gaussian elimination

$$\begin{vmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 2 & 2 & 2 \\ 1 & 1 & 3 & 3 & 3 \\ 1 & 1 & 1 & 4 & 4 \\ 1 & 1 & 1 & 1 & 5 \end{vmatrix}$$

Theorem

- Consider row columns $v_1, v_2, \dots, v_{i-1}, v_{i+1}, \dots, v_n$ with n entries. The function from \mathbb{R}^n to \mathbb{R} ,

$$T(x) = \det(v_1 \ v_2 \ \dots \ v_{i-1} \ x \ v_{i+1} \ \dots \ v_n)$$

is linear.

Theorem (for math curious students)

- The determinant is the only function from $(\mathbb{R}^n)^n$ to \mathbb{R} such that
 - It is linear on each rows (fixing the all the other rows).
 - It is alternating (swapping rows changes sign)
 - It has value 1 on the identity matrix.

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Theorem

- If A is an $n \times n$ matrix with orthogonal columns v_1, v_2, \dots, v_n then
$$|\det A| = \|v_1\| \cdot \|v_2\| \cdot \dots \cdot \|v_n\| .$$

If B is an $n \times n$ matrix

- $$|\det B| = \|v_1\| \cdot \|v_2^\perp\| \cdot \dots \cdot \|v_n^\perp\| ,$$
- where v_i^\perp is the component of v_i perpendicular to $\text{span}(v_1, \dots, v_{i-1})$.

Definition

- Consider vectors v_1, v_2, \dots, v_m in \mathbb{R}^n . The m -parallelepiped defined by the vectors v_1, v_2, \dots, v_m is the set of all vectors of the form $c_1 v_1 + c_2 v_2 + \dots + c_m v_m$ where c_1, c_2, \dots, c_m are scalars such that $0 \leq c_i \leq 1$.

Theorem

- Consider vectors v_1, v_2, \dots, v_m in \mathbb{R}^n . The volume of the m -parallelepiped defined by v_1, v_2, \dots, v_m is $\sqrt{|A^t A|}$ where A is the matrix with columns v_1, v_2, \dots, v_m .
- If $m=n$ then the volume is $|\det A|$.

Example

- Find the volume