

4.1; a) By definition: $\varphi_{i_1} \wedge \dots \wedge \varphi_{i_k} (e_{\sigma(1)}, \dots, e_{\sigma(k)}) = \frac{k!}{1! \dots 1!} \sum \text{sgn}(\sigma) \dots$
 $\dots \varphi_{i_1} \otimes \dots \otimes \varphi_{i_k} (e^{i_{\sigma(1)}}, \dots, e^{i_{\sigma(k)}}) \quad (*)$

But $\varphi_i(e_j) = \delta_{ij} \rightarrow (*) = 1 + 0 + \dots + 0 = 1$

b) $v_k = \sum v_k^i e_i \rightarrow$

$(*) \varphi_{i_1} \wedge \dots \wedge \varphi_{i_k} (v_1, \dots, v_k) = \varphi_{i_1} \wedge \dots \wedge \varphi_{i_k} (\sum v_1^i e_i, \dots, \sum v_k^i e_i)$

But, again as $\varphi_i(e_j) = \delta_{ij}$, if $I = \{i_1, \dots, i_k\}$.

$(*) = \varphi_{i_1} \wedge \dots \wedge \varphi_{i_k} (\sum_{i \in I} v_1^i e_i, \dots, \sum_{i \in I} v_k^i e_i)$

which is

$$\det \begin{bmatrix} v_1^{i_1} & \dots & v_1^{i_k} \\ \vdots & & \vdots \\ v_k^{i_1} & \dots & v_k^{i_k} \end{bmatrix}$$

4.2.

If $\dim V = n \Rightarrow \dim \Lambda^n = \binom{n}{n} = 1$. That is f^* , as a linear transformation on Λ^n can only be a multiplication.

Let $\omega \in \Lambda^n$, and let c be as defined in the book. $\rightarrow f^*(\omega) = c\omega$.

$$\begin{aligned} \text{But } f^*(\omega)(e_1, \dots, e_n) &= \omega(f(e_1), \dots, f(e_n)) = \\ &= \omega(\sum f_{i1} e_i, \sum f_{i2} e_i, \dots, \sum f_{in} e_i) = \end{aligned}$$

$$\text{By 4-6: } \det(f_{ij}) \omega(e_1, \dots, e_n)$$

$$\Rightarrow c = \det(f_{ij})$$

4-3; Following the hint, let $w_i = \sum_k a_{ik} v_k \rightarrow g_{ij} = T(w_i, w_j) =$

$$T\left(\sum_k a_{ik} v_k, \sum_k a_{jk} v_k\right) = \sum_m a_{im} a_{jm}$$

by expanding and noting that $T(v_k, v_l) = \delta_{kl}$

$$\Rightarrow (g_{ij}) = (a_{ij})(a_{ij})^T \Rightarrow |\omega(w_1, \dots, w_n)|^2 = |\det(a_{ij})|^2 = \det(g_{ij})$$

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4.9; a) As determinant is alternating, $v \times v = 0$

To show that $e_i \times e_j = e_k$, it suffices to prove that for

$$w = e_1, e_2, e_3 \quad : \quad \langle w, e_3 \rangle = \det \begin{pmatrix} e_1 \\ e_2 \\ w \end{pmatrix}, \text{ which is obvious.}$$

b) let
$$\langle w, e_i \rangle = \det \begin{pmatrix} v \\ w \\ e_i \end{pmatrix}$$

$$\text{and } w = \langle w, e_1 \rangle e_1 + \langle w, e_2 \rangle e_2 + \langle w, e_3 \rangle e_3.$$

or, we can use 'a' and note that

$$\begin{cases} w = w^1 e_1 + w^2 e_2 + w^3 e_3 \\ v = v^1 e_1 + v^2 e_2 + v^3 e_3 \end{cases} \rightarrow$$

$$w \times v = (w^1 e_1 + w^2 e_2 + w^3 e_3) \times (v^1 e_1 + v^2 e_2 + v^3 e_3) =$$

expanding and the facts of part 'a' gives the result.

$$\begin{aligned} \text{c) } \|v \times w\|^2 &= \|v\|^2 \|w\|^2 - (v \cdot w)^2 = \|v\|^2 \|w\|^2 (1 - \cos^2 \theta) \\ &\stackrel{\text{verify!}}{=} \|v\|^2 \|w\|^2 \sin^2 \theta. \end{aligned}$$

$$\langle v \times w, v \rangle = \det \begin{pmatrix} v \\ w \\ v \end{pmatrix} = 0 = \det \begin{pmatrix} v \\ w \\ w \end{pmatrix} = \langle w, v \times w \rangle.$$

$$\text{d) } \langle v, w \times z \rangle = \det \begin{pmatrix} w \\ z \\ v \end{pmatrix} = \det \begin{pmatrix} z \\ v \\ w \end{pmatrix} = \langle w, z \times v \rangle = \dots \langle z, v \times w \rangle.$$

similarly

Check that for $i, j = 1, 2, 3$,

$$v \times (e_i \times e_j) = \langle v, e_j \rangle e_i - \langle v, e_i \rangle e_j \text{ holds. By}$$

linearity, $v \times (w \times z) = \langle v, z \rangle w - \langle v, w \rangle z.$

$$(v \times w) \times z = -z \times (v \times w) = -\langle w, z \rangle v + \langle v, z \rangle w.$$

HW12-3.

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4.9-e). This is what we used in 'c'!

We used expansion. (supposedly!)

4-10; If $\{w_1, \dots, w_{n-1}\}$ is not a set of linearly independent

$$\text{sets, } \rightarrow \begin{cases} \det g_{ij} = 0 \\ w_1 \times \dots \times w_{n-1} = 0 \end{cases}$$

So, let it be linearly independent. Consider the $(n-1)$ -dim'l subspace $W = \{w_1, \dots, w_{n-1}\}$. $\Rightarrow \dim W^\perp = 1$ Define

$$f = \frac{w_1 \times \dots \times w_{n-1}}{|w_1 \times \dots \times w_{n-1}|} \Rightarrow \forall \tilde{w}_1, \dots, \tilde{w}_{n-1} \in W : \exists c : \text{s.t.}$$

$$cf = \tilde{w}_1 \times \dots \times \tilde{w}_{n-1} \quad \text{Define } \psi(\tilde{w}_1, \dots, \tilde{w}_{n-1}) = c.$$

ψ is an $(n-1)$ -form on W .

ψ is a volume form on W . \rightarrow By 4.3

$$|\psi(w_1, \dots, w_{n-1})| = |c| = |w_1 \times \dots \times w_{n-1}| = \sqrt{|\det g_{ij}|}$$

HW12-4.