Approximate Syllabus for MAT 555 Spring, 2017

Text: Introduction to Dynamical Systems, by Brin and Stuck

- Jan 24 Examples of dynamical systems Readings: 1.1, 1.2, 1.3 Exercises: 1.2.1, 1.2.4
- Jan 26 Limit sets, Minimal sets, Topological transitivity/Mixing 2.1, 2.2 2.1.1, 2.1.2, 2.1.5
- Jan 31 Symbolic Dynamics (Shift Spaces) 1.3, 1.4, 3.1 1.4.4
- Feb 2 Smale's Horseshoe, Coding & Topological conjugacy 1.8 1.8.3
- Feb 7 Translations and linear flow on n-dimensional torus 1.7 1.7.1, 1.7.3, 2.2.6
- Feb 9 Subshifts of finite type & Perron-Frobenius Theorem 1.4, 3.2, 3.3 3.3.1
- Feb 14 Perron-Frobenius & Applications (continued) 3.3, 4.12
- Feb 16 Topological Entropy 2.5
- Feb 21 Topological entropy (equivalent definitions) 2.5 2.5.1, 2.5.7
- Feb 23 Computing h_{top} (subshifts of finite type, etc.) 2.6
- Feb 28 The Variational Principle 9.5
- Mar 2 Poincaré Recurrence Theorem and applications 4.2 4.2.1
- Mar 7 Invariant Measures, Krylov-Bogolyubov Theorem 4.1, 4.6 4.4.5
- Mar 9 Ergodic Measures 4.3, 4.6

Mar 14–23 No class

- Mar 28 Ergodic Theorems. Birkhoff Ergodic Theorem 4.3, 4.5 4.5.2
- Apr 4 Mixing, Weak Mixing, Ergodicity & Unique Ergodicity 4.3, 4.4 4.3.3, 4.4.2, 4.4.3
- Apr 6 Applications of Ergodicity to Number Theory. Szemeredi's Theorem 4.11 4.11.2
- Apr 11 One-dimensional complex dynamics 8.5, 8.6
- Apr 13 One-dimensional complex dynamics (II) 8.5, 8.6
- Apr 18 Fatou-Bieberbach domains
- Apr 20 Hyperbolicity in dimension one
- Apr 25 Hyperbolicity in dimension > 1, Invariant cones. 5.2, 5.4
- Apr 27 Structural Stability of Hyperbolic maps 5.3, 5.5
- May 2 Stable Manifold Theorem 5.6
- May 4 18 Further topics/ Review