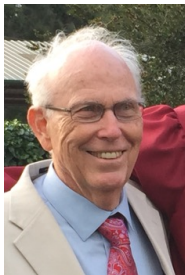


THE SPECIAL LAGRANGIAN POTENTIAL EQUATION

with Reese Harvey



SOME HISTORY

Calibrations

A **Calibration** on a manifold X is a smooth k -form $\varphi \in \mathcal{E}^k(X)$ with $d\varphi = 0$ such that

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An oriented k -dimensional submanifold $M \subset X$ is a **φ -submanifold** if

$$T_x M \in \mathbf{G}(\varphi) \quad \forall x \in M.$$

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This Proposition extends from submanifolds to integral currents.

Kähler Manifolds

Herb Federer: (using Wirtinger's inequality)

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The $\frac{1}{k!}\omega^k$ -submanifolds are **complex submanifolds**.

The (locally closed) $\frac{1}{k!}\omega^k$ -currents are **positive holomorphic chains**.

Jim King

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I will work in \mathbb{C}^n ,

but we knew that everything carried over to **Calabi-Yau** manifolds.

The Special Lagrangian Calibration

$$\varphi \equiv \operatorname{Re}\{\mathbf{dz}_1 \wedge \cdots \wedge \mathbf{dz}_n\} \quad \text{in } \mathbb{C}^n$$

This is a sum of 2^{n-1} orthogonal simple vectors.

Nevertheless, for a **unit simple** vector $\xi = \mathbf{e}_1 \wedge \cdots \wedge \mathbf{e}_n$

$$|\{\mathbf{dz}_1 \wedge \cdots \wedge \mathbf{dz}_n\}(\xi)| \leq 1$$

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and $|\{\mathbf{dz}_1 \wedge \cdots \wedge \mathbf{dz}_n\}(\xi)| = 1 \iff \xi$ is **Lagrangian**.

The Special Lagrangian Calibration

Thus for a **unit simple** vector $\xi = \mathbf{e}_1 \wedge \cdots \wedge \mathbf{e}_n$

$$\operatorname{Re}\{\mathbf{d}z_1 \wedge \cdots \wedge \mathbf{d}z_n\}(\xi) = \pm 1 \quad \iff$$

ξ is Lagrangian and $\operatorname{Im}\{\mathbf{d}z_1 \wedge \cdots \wedge \mathbf{d}z_n\}(\xi) = \mathbf{0}$

The Special Lagrangian Calibration

Otherwise said, for an oriented real n -plane P

$$\operatorname{Re}\{dz_1 \wedge \cdots \wedge dz_n\}|_P = \pm d\operatorname{vol}_P \quad \iff$$

$$P \text{ is Lagrangian and } \operatorname{Im}\{dz_1 \wedge \cdots \wedge dz_n\}|_P = 0$$

Lagrangian Graphs

Let $z = x + iy$, and consider a submanifold of the form

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The tangent space to $M^n = \text{graph}(F)$ at x is just the graph of $(DF)_x$.

W.r.t. coordinates $(x_1, \dots, x_n, y_1, \dots, y_n)$ the matrix is just

$$\left(\left(\frac{\partial^2 u}{\partial x_i \partial x_j} \right) \right)$$

Lagrangian Graphs

This matrix is symmetric, so under a change of variables (gx, gy) we get

$$\left(\left(\frac{\partial^2 u}{\partial x_i \partial x_j} \right) \right) = \begin{pmatrix} \lambda_1 & & & \\ & \cdot & & \\ & & \cdot & \\ & & & \lambda_n \end{pmatrix}$$

The graph of this in $\mathbb{C}^n = \mathbb{R}^n \oplus J\mathbb{R}^n$ is spanned by

$$\mathbf{e}_1 + \lambda_1 J\mathbf{e}_1, \dots, \mathbf{e}_n + \lambda_n J\mathbf{e}_n$$

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$$\xi = (\mathbf{e}_1 + \lambda_1 \mathbf{J}\mathbf{e}_1) \wedge \cdots \wedge (\mathbf{e}_n + \lambda_n \mathbf{J}\mathbf{e}_n).$$

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Example ($n = 3$) $\text{tr}(\mathbf{D}^2 u) = \det(\mathbf{D}^2 u)$ i.e. $\Delta u = MA(u).$

Circular Symmetry

Note that there is an S^1 -**symmetry**

If we set

$$\varphi \equiv \operatorname{Re}\{e^{-i\theta} dz_1 \wedge \cdots \wedge dz_n\},$$

Then we get the equation

$$\operatorname{Im}[\{e^{-i\theta} dz_1 \wedge \cdots \wedge dz_n\}(\xi)] = 0, \quad \text{i.e.,}$$

$$\operatorname{Im} \left\{ e^{-i\theta} \prod_{k=1}^n (1 + i\lambda_k) \right\} = 0$$

A Different Way to Write the Equation

Caffarelli, Nirenberg and Spruck

$$\operatorname{Im} \left\{ e^{-i\theta} \prod_{k=1}^n (1 + i\lambda_k) \right\} = 0$$

Consider

$$1 + i\lambda_k \in \mathbb{C}.$$

Then

$$\lambda_k = \tan \theta_k \quad \text{where} \quad -\frac{\pi}{2} < \theta_k < \frac{\pi}{2}$$

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$$\Theta = \sum_{k=1}^n \arg(1 + i\lambda_k) = \sum_{k=1}^n \theta_k = \sum_{k=1}^n \arctan(\lambda_k).$$

The Special Lagrangian Potential Operator

$$\operatorname{Im} \left\{ e^{-i\theta} \prod_{k=1}^n (1 + i\lambda_k) \right\} = \operatorname{Im} \left\{ e^{-i\theta} e^{R+i\Theta} \right\} = e^R \operatorname{Im} \left\{ e^{-i\theta} e^{i\Theta} \right\} = 0$$

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$\mathbf{SL}(A)$ takes values in $(-n\frac{\pi}{2}, n\frac{\pi}{2})$.

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There exist many explicit and many families of solutions to these equations

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A Lagrangian of mean curvature 0 is Special Lagrangian

The Dirichlet Problem

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$$\operatorname{tr} \{ \arctan (D^2 u) \} = \theta$$

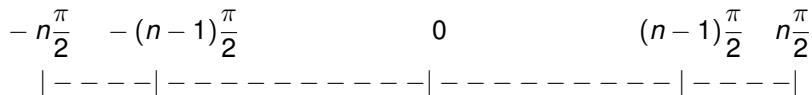
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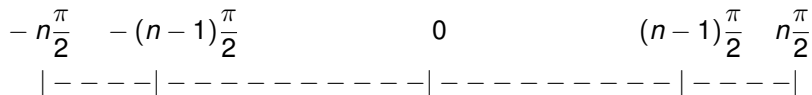


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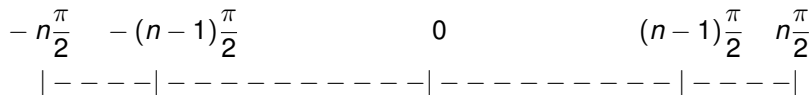
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What about solutions for other phases?

Viscosity Solutions

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Def. Fix a domain $\Omega \subset \mathbb{R}^n$ and $u \in USC(\Omega)$. By a **test function** for u at $x \in \Omega$ we mean a C^2 -function ϕ in a neighborhood of x with

$$u \leq \phi \text{ near } x \quad \text{and} \quad u(x) = \phi(x).$$

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Def. Fix a domain $\Omega \subset \mathbb{R}^n$ and $u \in USC(\Omega)$. Then u is **\mathbf{F}_θ -subharmonic** if for every test function ϕ for u at any point $x \in \Omega$, we have

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Def. $u \in C(\Omega)$ is **\mathbf{F}_θ -harmonic**, i.e., a **viscosity solution of our equation**, if

u is **\mathbf{F}_θ -subharmonic** and $-u$ is **$\tilde{\mathbf{F}}_\theta$ -subharmonic**

Work of Wang and Yuan

These viscosity solutions are interesting.

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Graphing the gradients gives infinitely many Special Lagrangian Varieties each with an isolated singularity

Continuous Solutions to the (DP)

Definitions hold for any non-empty closed $\mathbf{F} \subset \text{Sym}^2(\mathbb{R}^n)$ satisfying

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$$\text{strictly } \mathbf{F}\text{-convex} \quad \text{and} \quad \text{strictly } \tilde{\mathbf{F}}\text{-convex}$$

then Perron existence holds for the (DP).

Strict \mathbf{F} -Convexity of $\partial\Omega$

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Def. The **asymptotic interior** of \mathbf{F} is

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Def. Let II_x be the second fundamental form of $\partial\Omega$ with respect to the inward-pointing normal at x . Then $\partial\Omega$ is strictly **F-convex** if for all $x \in \partial\Omega$

$$\begin{pmatrix} II_x & 0 \\ 0 & t \end{pmatrix} \in \text{Int } \vec{\mathbf{F}} \quad \forall t \gg 1.$$

Compute $\text{Int } \vec{\mathbf{F}}_\theta$

$$\begin{array}{ccccccc} -n\frac{\pi}{2} & -(n-2)\frac{\pi}{2} & & 0 & & (n-2)\frac{\pi}{2} & n\frac{\pi}{2} \\ |-----|-----|-----|-----|-----|-----| \end{array}$$

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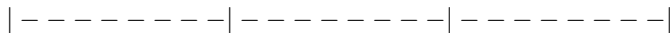
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This gives (probably) the best geometric condition on $\partial\Omega$ for existence to the (DP) for

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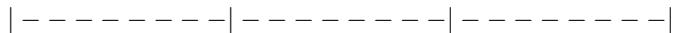
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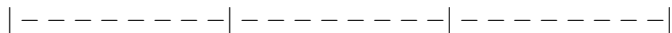
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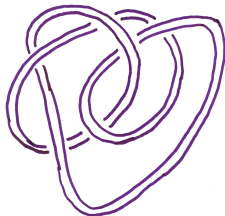
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Example: Results on Riemannian manifolds.

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$$\operatorname{tr}\{\arctan(D_x^2 u)\} = \psi(x) \quad (*)$$

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Note 2. S. Dinew, H. Do and T. D. Tô have proved the continuous viscosity version of this result.

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Note 2. The SLP operator is tamable on \mathbf{F}_θ for $\theta > (n-2)\frac{\pi}{2}$.

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This phase function satisfies the equation

$$\nabla\psi = -\mathbf{JH} \quad \text{on } L$$

where H is the mean curvature vector of L .

Some Nice Results

Theorem. (Simon Brendle and Micah Warren). *Let $\Omega, \tilde{\Omega} \subset \mathbb{R}^n$ be two domains with smooth strictly convex boundaries (2nd Fund Forms > 0). Then there exists a diffeomorphism*

$$F : \Omega \longrightarrow \tilde{\Omega}$$

whose graph is Special Lagrangian.

A Bernstein Theorem

Theorem. (Yu Yuan also Jost-Xin and for $n = 2$ Lei Fu).

Let u be a smooth solution, over all of \mathbb{R}^n , to the equation

$$\operatorname{tr} \{ \arctan(D^2 u) \} = \theta \quad \text{with } |\theta| > (n-2) \frac{\pi}{2}$$

(in the critical interval). Then u is a quadratic polynomial.

Moment Conditions

Theorem. (Lei Fu).

*Boundaries of SL submanifolds are **not** characterized by a moment condition.*

The Degenerate Special Lagrangian Equation

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Much work has been done by Solomon, Yanir Rubinstein, Tamás Darvas, and Matt Dellatorre.

The SL Potential Equation and Mirror Symmetry

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Much has been done.

Now an analogue of the SL potential equation plays a big role.

There are very good articles by T. C. Collins, A. Jacob, N. C. Leung, D. Xie and Y. Shi.

A Small Insight

(X, ω) an n -dimensional Kähler manifold
 $a \in H^{1,1}(X, \mathbb{R})$ a fixed $(1,1)$ -homology class.

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This gives rise to a hermitian Yang-Mills equation

$$\Theta_\omega(\alpha) = \sum_k \arctan(\lambda_k) \equiv \theta \pmod{2\pi}$$

where the λ_k 's are eigenvalues of an endomorphism $K : T^{1,0}X \rightarrow T^{1,0}X$ given by contracting by α and the dual of ω . Of course the elements in a all differ from a given one α_0 by $dd^c u$ for a function u on X .