ON THE DIMENSIONS OF CERTAIN INCOMMENSURABLY CONSTRUCTED SETS

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Abstract

It is well known that the Hausdorff dimension of the invariant set \( \Lambda_t \) of an iterated function system \( \mathcal{F}_t \) on \( \mathbb{R}^n \) depending smoothly on a parameter \( t \) does not vary continuously. In fact, it has been shown recently that in general it varies lower-semi-continuously. For a specific family of systems we investigate numerically the conjecture that discontinuities in the dimension only arise when in some iterate of the iterated function system two (or more) of its branches coincide. This happens in a set of co-dimension one, but which is dense. All the other points are conjectured to be points of continuity.

1 Introduction

Let \( \mathcal{F}_t \) be a collection of smooth contracting diffeomorphisms \( \{f_i\}_{i=0}^N \) acting on \( \mathbb{R}^n \), depending smoothly on a parameter \( t \). For each \( t \), there exists ([2]) a unique compact invariant set \( \Lambda_t \) defined by \( \Lambda_t = \bigcup f_i(\Lambda_t) \) and this set supports a natural (see section 2) invariant probability measure \( \nu_t \). It is known that (under certain weak conformality conditions for systems in dimension greater than 1) the Hausdorff dimension and the Lebesgue measure of the invariant set vary semi-continuously ([16]). That this is the best possible general result is illustrated by the family of systems discussed in this paper (see Theorem 1.1). The question that arises is: where and how often do the discontinuities arise? Can we say that in some sense the dimension and the measure of the set are typically continuous?

In this paper, \( \mathcal{F}_t \) will denote the system given by \( \{f_i\}_{i=0}^2 \) where \( t \in [0,1/2] \) is a parameter

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and
\[
\begin{align*}
    f_0(x) &= \frac{x}{3} \\
    f_1(x) &= \frac{x + t}{3} \\
    f_2(x) &= \frac{x + 1}{3}
\end{align*}
\]

Denote its unique invariant set by $\Lambda_t$.

The Hausdorff dimension and Lebesgue measure, denoted by $\text{Hdim}$ and $\mu$ respectively, of the invariant set depend on the parameter $t$. The following striking result was stated in [16], although the most important parts of it were proved in older papers (referenced in [16]). A proof of this can also be found in [4].

**Theorem 1.1** Let $\mathcal{F}_t$ be the system just described. Then
i) If $t = p/q$ is rational and $pq = 2 \pmod{3}$ then $\mu(t) = 1/q$.
ii) If $t = p/q$ is rational and $pq \neq 2 \pmod{3}$ then $\text{Hdim}(t) < 1$.
iii) For all irrational $t$, $\mu(t) = 0$.
iv) For almost all $t$, $\text{Hdim}(t) = 1$.

We shall see in section 2 that whenever the system respects an (invertible) affine image $L$ of $\mathbb{Z}^n$ in the sense that $\cup_i f_i^{-1}(L) \subseteq L$ (we call this commensurably constructed), then efficient algorithms to calculate, or estimate, the dimension are available. For the family under consideration, it is easy to see that $\Lambda_t$ is commensurably constructed if and only if $t$ is rational. The following conjecture (attributed [4] to Furstenberg) stipulates that discontinuities should only occur at rational values of $t$.

**Conjecture 1.2** For all irrational $t$, $\text{Hdim}(t) = 1$.

(Note that Theorem 1.1 already guarantees the continuity of the measure at irrational values of $t$.)

The aim of this note is to provide numerical and heuristic evidence that for irrational values of $t$ (in particular the golden mean) the dimension of the invariant set equals 1. Thus in section 2 we outline our algorithms used to do the numerics. In section 3 we prove that for certain Liouville numbers $t$, the invariant set indeed has dimension 1. The main purpose of this paper is to present evidence in support of Conjecture 1.2. This is done in section 4.

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## 2 Methods for Commensurably Constructed Sets

In this section, we will list some methods to calculate or estimate the dimension for rational values of $t$. We remind the reader that as proved by [16] (see also section 3), the Hausdorff
dimension of the invariant set is equal to its limit capacity (for the sets under consideration). The algorithms we discuss will thus only have to calculate the limit capacity (or box-dimension).

Suppose \( t \) is rational, say \( p/q \), then by the affine coordinate transform \( x \to x/q \) we may map the iterated function system to the following:

\[
\begin{align*}
  f_0(x) &= \frac{x}{3} \\
  f_1(x) &= \frac{x + p}{3} \\
  f_2(x) &= \frac{x + q}{3}
\end{align*}
\]

(2.1)

An equivalent definition of the invariant set of this system is the set of points

\[
\Lambda(3, \{0, p, q\}) = \{ x \in \mathbb{R} | x = \sum_{i=1}^{\infty} 3^{-i} r_i , \ r_i \in \{0, p, q\} \} .
\]

(2.2)

We can thus approximate the set by considering the points that can be written as \( \sum_{i=0}^{k-1} 3^{-i} r_i , \ r_i \in \{0, p, q\} \equiv R \). A simpler way of stating this is

\[
\Lambda_k = 3^{-k} \sum_{i=0}^{k-1} 3^i R \quad \text{and} \quad \Lambda = \lim_{k \to \infty} \Lambda_k ,
\]

where the summation here is a sum of sets. The sum of two sets \( A \) and \( B \) is defined as follows:

\[
Z = A + B \overset{\text{def}}{=} \{ z | z = a + b, a \in A, b \in B \} .
\]

(See [1], [13], and [14] for details.) The box-dimension is calculated by counting the number of distinct integers in \( \{ \sum_{i=0}^{k-1} 3^i R \} \). Let \( \gamma_k \) denote this number. We have then:

**Proposition 2.1** The invariant set of the system \((3, \{0, p, q\})\) has Hausdorff dimension equal to \( \lim_{k \to \infty} \frac{\ln \gamma_k}{\ln 3^k} \).

The method of calculating the dimension in which we are interested here is a refinement of this. It was independently (and slightly earlier) developed by Rao and Wen ([11]) and proved by different methods.

Note that if \( R \) consists of integers then expressions in \( \{ \sum_{i=0}^{k-1} 3^i R \} \) have integer values. In these cases we may define the maps \( T_k \) and \( t_k \) from the integers to the nonnegative integers:

\[
\begin{align*}
  T_k(\ell) &= \# \{ \sum_{i=0}^{k-1} 3^i R = \ell \} . \\
  t_k(\ell) &= \min \{ T_k(\ell), 1 \} .
\end{align*}
\]

By a ‘word’ \( w \) (in \( t_k \)) we mean an ordered set of consecutive values of \( t_k \), \( \{ t_k(i_0), t_k(i_0 + 1), \ldots t_k(i_0 + |w| - 1) \} \), where \( |w| \) is the length of the word, and such that \( i_0, i_0 + 1, \ldots i_0 + |w| - 1 \)
is maximal with respect to the condition that less than \( q/2 - 1 \) consecutive values are zero. Similarly we can define words in \( T_k \).

The ‘sentence’ \( t_{k+1} \) is created from the sentence \( t_k \) by multiplying by 3 and adding \( R \). If we apply this operation to a word \( w \) in \( t_k \) we refer to the resulting part of \( t_{k+1} \) as the ‘offspring’ of \( w \). It is easy to see that if \( w_1 \) and \( w_2 \) are consecutive words in \( t_k \) then \( 3w_1 + q \) and \( 3w_2 \) are separated by \( q/2 - 1 \) or more zeros. Thus the offspring of a word must consist of words.

If we let \( \{ w_j \} \) be a list of all the words occurring in \( \bigcup_k T_k \), then we can write the offspring of \( w_i \) as a (finite) linear combination \( \sum_j d_{ij} w_j \). Let \( \lambda_D \) be the leading eigenvalue of the matrix \( D = (d_{ij}) \).

**Theorem 2.2** If the number of words in the development of the system \((3, \{0, p, q\})\) is finite, then the invariant set of that system has Hausdorff dimension equal to \( \ln \lambda_D / \ln 3 \).

**Remark:** The numerical algorithm we used to calculate \( \lambda_D \) does not terminate unless the number of distinct words in \( \bigcup_k T_k \) is finite and smaller than a realistic limit set by memory limitations: if this is not the case, the algorithm does not finish its calculation of the values of the entries of the transition matrix \( D \). In fact, in [11] it is proved that if the dimension of the invariant set of the system \((3, \{0, p, q\})\) is smaller than 1, then the number of words is always finite. We do not include this proof here, since in practice the calculational limits are quickly exhausted (see section 4).

**Proof:** Supposing the number of distinct words is finite, we obtain a finite matrix \( D \). Moreover, the matrix is primitive, since all words were constructed from the initial word \{0\}. By the Perron-Frobenius theorem, there is a unique leading eigenvalue \( \lambda_D > 0 \). The associated eigenvector \( v \) gives the asymptotic distribution of words. For large \( k \), the number of occurrences of every type of word is multiplied by \( \lambda_D \) from one level to the next. But that means that the number \( \gamma_k \) is multiplied by \( \lambda_D \). Now apply Proposition 2.1. \( \blacksquare \)

The new method thus consists in identifying words and expressing its offspring in terms of the original words and calculating the eigenvalue of the corresponding transition matrix. If \( w = \{ t_k(i_0), t_k(i_0 + 1), \ldots t_k(i_0 + |w| - 1) \} \) is a word, we can specify this word by listing, in order, the distances of the non-zero entries from the first entry. For example, the word \( \{1, 1, 0, 1, 0, 1\} \) for \((3, \{0, 1, 5\})\) would be denoted as \( \{0, 1, 3, 5\} \). Using this notation, we see that for the system \((3, \{0, 1, 3\})\), where no consecutive zeroes are allowed, the development yields only 2 distinct words, namely \( \{0, 1\} \) and \{0\}. This line of reasoning leads to the following.

\[
\begin{align*}
\{0\} & \rightarrow \{0, 1, 3\} \equiv \{0\} \cup \{0, 1\} \\
\{0, 1\} & \rightarrow \{0, 1, 3, 4, 6\} \equiv \{0\} \cup 2 \cdot \{0, 1\}
\end{align*}
\]

We can write down the transition matrix \( D \) as

\[
D = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}.
\]

We conclude that the dimension of this set equals

\[
\text{Hdim}(\Lambda_{1/3}) = \ln((3 + \sqrt{5})/2) / \ln 3 \approx 0.867 \ldots ,
\] (2.3)
since \((3 + \sqrt{5})/2\) is the leading eigenvalue of the matrix \(D\). The same result was earlier obtained by [3].

As we noted above, and can be checked in section 4, the above algorithm rather quickly exhausts our computational limits. For our purposes, it is sufficient to have a lower bound estimate of the Hausdorff dimension. This can be done much more efficiently as we shall now see.

We may follow [2] and adopt the view that the system \(\mathcal{F}_t\) (as it was given in equation (1.1)) acts linearly on the space of probability measures on the interval as follows (\(V\) is an interval):

\[
\mathcal{F}_t \mu(V) = \frac{1}{3} \sum_{n=0}^{2} \mu(f_n^{-1}(V)) ,
\]

(2.4)

where the \(f_n\) are given in equation (1.1). If we put an appropriate metric on the space of measures, \(\mathcal{F}_t\) is a (uniform) contraction (see [2]).

Define a sequence \(\nu_{p/q}^{(k)}\) of probability measures associated with the system \((3, \{0, p/q, 1\})\).

\[
\nu_{p/q}^{(k)}(V) = 3^{-k} \sum_{q^{-1}3^{-k}i \in V} T_k(i) ,
\]

(2.5)

where \(T_k\) is the function defined before for the system \((3, \{0, p, q\})\) (note the difference in the systems).

The following is wellknown (see for example [2]).

**Lemma 2.3** The limit \(\lim_{k \to \infty} \nu_{p/q}^{(k)}\) is the unique fixed point of \(\mathcal{F}_{p/q}\).

**Proof:** It is sufficient to prove that \(\mathcal{F}_{p/q} \nu_{p/q}^{(k)} = \nu_{p/q}^{(k+1)}\). Write \(R = \{0, p, q\}\) and observe that it consists of integers. From the definition of \(T\), we see that

\[
T_{k+1}(\ell) = \# \{ \sum_{i=0}^{k-1} 3^i R + 3^k R = \ell \} = \sum_j T_k(j) \cdot \# \{ j + 3^k R = \ell \} .
\]

Combining this with equation 2.5 we obtain

\[
\nu^{(k+1)}(V) = 3^{-k-1} \sum_{q^{-1}3^{-k-1}i \in V} T_{k+1}(i) = 3^{-k-1} \sum_{q^{-1}3^{-k-1}i \in V} \left[ \sum_j T_k(j) \cdot \# \{ j + 3^k R = i \} \right] .
\]

We may rewrite this as

\[
\nu^{(k+1)}(V) = \frac{1}{3} 3^{-k} \sum_j T_k(j) ,
\]

where the accented summation is over those \(j\) that satisfy

\[
q^{-1}3^{-k-1}(j + 3^k R) = q^{-1}3^{-k}i \in V \Rightarrow q^{-1}3^{-k}j \in 3V - R/q .
\]
Thus by (1.1) we see that
\[ \nu^{(k+1)}(V) = \frac{1}{3} \sum_{n} \nu^{(k)}(f_n^{-1}(V)) \]

in accordance with (2.4). Together with the fact that \( \mathcal{F} \) is a contraction this proves the result.

Returning to the invariant set of (2.1), denote
\[ S \equiv \{ \Lambda - \Lambda \} \cap \mathbb{Z} \] (2.6)

that is, the set of integer differences contained in \( \Lambda \). Writing \( \Lambda - \Lambda \) as a set of numbers on the base 3, as was done in equation (2.2), we easily see that \( \Lambda - \Lambda \) is the invariant set of the system \((3, \{0, \pm p, \pm (q - p), \pm q\})\). An easy argument (which we leave to the reader) shows that this is the same as the invariant set of \((3, \{0, \pm q\})\), which is given by \([-q/2, q/2]\). Let \( \mathbb{R}^S \) be the vector space obtained by associating a basis vector \( e_\ell \) to each element \( \ell \) of \( S \). Following [14], define a linear map \( \mathcal{T} : \mathbb{R}^S \to \mathbb{R}^S \), the transition operator for the differences, whose matrix elements are given by:
\[ \mathcal{T}_{ij} \equiv \sum_\ell T_1(\ell)T_1(\ell + i - 3j) \] (2.7)

where \( i \) and \( j \) are in \( S \). This operator plays a very fundamental role in the theory of iterated function systems, although it goes by very different names and formulations ([10], [8], [14], [15], [4], [12], to name a few). In words, it is the matrix whose \((i, j)\)-th entry corresponds to the number of differences in \( R \) that are equal to \( i - 3j \). We will call this operator the difference operator. One may reduce the dimension of the matrix by a factor of almost 2, by exploiting the fact that we are interested only in how \( \mathcal{T} \) operates on even vectors, \( v_{-i} = v_i \). This is due to the fact that for every difference \( r_1 - r_2 = d \), we must have a difference \(-d \) in the sequence (see [14]). The reduced difference operator defined as
\[ \text{for } i \geq 0 : \quad \mathcal{T}_{ij}^{(R)} = \mathcal{T}_{i,j} + \mathcal{T}_{i,-j} \quad \text{if } j > 0 \]
\[ \mathcal{T}_{ij}^{(R)} = \mathcal{T}_{i,j} \quad \text{if } j = 0 \]

acts on the reduced space as the original \( \mathcal{T} \) does on symmetric vectors. From now on we use the abbreviation \( \mathcal{T} \) for this operator as well.

The content of the following lemma is that the number of differences in \( \{ \sum_{i=0}^{k-1} 3^i R \} \) equal to \( d \) may be calculated by iterating the matrix \( \mathcal{T} \). This is very similar to what is proved in section 3 of [14] in greater generality. We give a simplified proof for completeness. Recall that \( e_0 \) is the standard basis vector in \( \mathbb{R}^S \) associated with \( 0 \in S \).

**Lemma 2.4** The growth rate of \( \sum_i T_k(i)^2 \) (as \( k \to \infty \)) is equal to the growth rate \( \kappa \) of \( |\mathcal{T}^k e_0| \).

**Proof:** Start by observing that
\[ T_{k+1}(i) = \# \{ R + 3 \sum_{\ell=0}^{k-1} 3^\ell R = i \} = \sum_j T_1(i - 3j)T_k(j) \]
Using this formula, we see that for each \( d \in S \)
\[
\sum_{i} T_{k+1}(i)T_{k+1}(i + d) = \sum_{i} \sum_{j,n} T_{1}(i - 3j)T_{1}(d + i - 3n)T_{k}(j)T_{k}(n)
\]
where all the summations are over \( \mathbb{Z} \). Eliminate \( i \) and \( j \) in favor of \( p \) and \( r \) by setting:
\[
i = p + 3n - 3r, \\
j = n - r,
\]
in order to obtain
\[
\sum_{i \in \mathbb{Z}} T_{k+1}(i)T_{k+1}(i + d) = \sum_{n,p,r \in \mathbb{Z}} T_{1}(p)T_{1}(p + d - 3r)T_{k}(n)T_{k}(n - r)
\]
\[
= \sum_{r \in \mathbb{Z}} \left( \sum_{p \in \mathbb{Z}} T_{1}(p)T_{1}(p + d - 3r) \right) \left( \sum_{n \in \mathbb{Z}} T_{k}(n)T_{k}(n - r) \right).
\]
Note that by symmetry we may change \( r \) to \(-r\) in \( \sum T_{k}(n)T_{k}(n - r) \). Also, \( T_{1}(p)T_{1}(p + d - 3r) \) is non-zero only if \( s - Mr \in R - R \). Since \( d - 3r \) must be in \( R - R \subset [-q,q] \) and \( d \in S \), it is easy to see that \( r \) must be in \([-q/2,q/2] \). Thus by using equation (2.7) we then see that
\[
\sum_{i} T_{k+1}(i)T_{k+1}(i + d) = \sum_{r \in S} T_{d,r} \left( \sum_{n \in \mathbb{Z}} T_{k}(n)T_{k}(n + r) \right).
\]
By a recursion argument we get that
\[
\sum_{i} T_{k}(i)T_{k}(i + d) = \left( T^k e_0 \right)_{d-th \ component}.
\]
(2.8)

To see that the lemma holds it is sufficient to notice that the growth rate of this expression is independent of \( d \), because it is an eigenvalue of \( T \). Thus we may set \( d = 0 \).

We note that one can easily prove that the eigenvalue of \( T \) referred to in this proof is the leading one. However, this fact will not be used in the numerical part of this work. In fact, the algorithm we will be using (see equation (4.1)) is based on equation (2.8).

The following result gives an efficient to estimate the dimension of the sets under consideration. It is apparently new, although a related one has appeared in [7]. The method of proof used in that paper is very different.

**Theorem 2.5** Let \( \kappa \) be the leading eigenvalue of the difference operator associated to the system \((3,\{0,p,q\})\). Then
\[
\text{Hdim } (\Lambda(3,\{0,p,q\})) \geq \frac{\ln(9/\kappa)}{\ln 3}.
\]
Proof: Note that \( v_{p/q}(n) = 1 \) for all \( n \). Denote by \( x_{p/q}(n) \) and \( v_{p/q}(n) \) the restrictions of \( T_n \) and \( t_n \) to the \( i \)-th components where \( q^{-1}3^{-n} \cdot i \in \Lambda \). Now Hölder’s inequality gives us the following estimate (we drop the superscripts \((n)\)):

\[
\cos \theta_n \overset{\text{def}}{=} \frac{\sum v_i x_i}{\sqrt{\sum v_i^2} \cdot \sqrt{\sum x_i^2}} = \frac{\sum x_i}{\sqrt{\sum x_i^2}} \leq 1 ,
\]

where, of course, the summations are over the indices \( i \) such that \( q^{-1}3^{-n} \cdot i \in \Lambda \). From the above definitions we know that \( 3^{-n} \sum x_i \) estimates \( v_{p/q}(n) \). To take the limit as \( n \to \infty \) recall that \( v_{p/q} \) converges to \( \nu \) by Lemma 2.3. Also note that \( \sum v_i \) estimates the number \( N_n \) of intervals of size \( q^{-1}3^{-n} \) needed to cover \( \Lambda \). According to the previous lemma, the growthrate of \( \sum x_i^2 \) is given by \( \kappa \), the leading eigenvalue of \( T \).

\[
\lim_{n \to \infty} \frac{1}{n} \ln \cos \theta_n = \lim_{n \to \infty} \frac{1}{n} \ln \left( \frac{3^n v_{p/q}(n)}{\sqrt{N_n} \sqrt{\kappa^n}} \right) = \frac{\ln 3}{2} \left( \frac{\ln 9/\kappa}{\ln 3} - \text{boxdim}(\Lambda) \right) \leq 0 .
\] (2.9)

This gives an estimate for the box-dimension of \( \Lambda \):

\[
\text{boxdim}(\Lambda) \geq \frac{\ln(9/\kappa)}{\ln 3} .
\]

Since \( \Lambda \) is contained in \( \Lambda \) it also is an estimate for the box dimension of \( \Lambda \). But the box dimension of \( \Lambda \) equals its Hausdorff dimension (see [16]), which implies the estimate. \( \blacksquare \)

By way of illustration, we work out one example. The reduced difference operator associated with the system \( (3, \{0,1,3\}) \) is easily calculated, noting that \( S = \{0,1\} \) (for the reduced difference operator):

\[
T = \begin{pmatrix} 3 & 2 \\ 1 & 1 \end{pmatrix} \quad \text{and} \quad T \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} \quad \text{and} \quad T^2 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 11 \\ 4 \end{pmatrix} .
\]

Since in this case we have that \( \kappa = 2 + \sqrt{3} \), the lower estimate

\[
d \geq \frac{\ln(9/(2 + \sqrt{3}))}{\ln 3} = 0.80125326 .
\]

Note that this is less than the exact value of the dimension of this invariant set found before.

In case the measure of the invariant set is positive (see Theorem 1.1), its dimension is trivially equal to 1. In this case we may calculate the dimension of the boundary of the invariant set (this idea was first developed in [14] in a more general context). An eigenvalue of \( T \) is called special if it is real and contained in \( [1,3] \).

**Theorem 2.6** Let \( (3, \{-p,q\}) \) be such that \( pq = 2 \mod 3 \). The associated matrix \( T \) always has at least one special eigenvalue. If we call the leading special eigenvalue \( \lambda \), then the Hausdorff dimension of \( \partial \Lambda \) (the boundary of \( \Lambda \)) is given by

\[
\text{Hdim}(\partial \Lambda) = \frac{\ln \lambda}{\ln 3} .
\]
Since the system \((3, \{0, 1, 3\})\) is not of the form required by the theorem, we consider instead the system \((3, \{0, 8, 13\})\). With a little work one can see that the reduced difference operator becomes:

\[
\mathcal{T} = \begin{pmatrix}
3 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 1 & 0 & 0 & 1 & 0 \\
0 & 3 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 2 & 1 & 0 & 0 \\
1 & 1 & 0 & 0 & 0 & 0 & 1 \\
0 & 0 & 3 & 0 & 0 & 0 & 0
\end{pmatrix}.
\]

To obtain the next-to-leading eigenvalue, one may set the \(\mathcal{T}_{00} = 0\) (see [14]) and use the same algorithm as in equation (4.1).

3 Methods for Incommensurably Constructed Sets

We present an estimate for the dimension for \(t\) in a certain class of irrationals. This estimate is a simple consequence of a general result (see [16]) which we give first.

**Theorem 3.1** i) The Hausdorff dimension of \(\Lambda_t\) equals its upper capacity (or box dimension).

ii) The Hausdorff dimension is a lower semicontinuous function of \(t\).

iii) The Lebesgue measure of \(\Lambda_t\) is an upper semicontinuous function of \(t\).

iv) For \(d\) greater than the upper box-dimension of \(\partial\Lambda(\mathcal{F}_{0})\), and for any \(\epsilon > 0\) and \(t\) sufficiently close to \(t_0\), the following is true:

\[
\mu(t) \leq \mu(t_0) + \epsilon |t - t_0|^{1-d}.
\]

**Definition 3.2** Let \(\mathcal{O}_\nu\) be the subset of reals \(t \in [0, 1]\) satisfying the following conditions:

i) \(t\) is irrational and for some \(C > 0\) there is an infinite number of rationals satisfying

\[
|t - \frac{p}{q}| \leq \frac{C}{q^\nu}.
\]

ii) The above equation has an infinite number of solutions \(p/q\) with \(pq = 2 \pmod{3}\).

**Theorem 3.3** When \(t \in \mathcal{O}_\nu\), the Hausdorff dimension of \(\Lambda_t\) is greater than or equal to \(1 - 1/\nu\).

**Remark:** In [4] the same statement is proved differently.

**Proof:** Suppose that \(t\) in \(\mathcal{O}_\nu\), and let \(d_0\) be the box dimension of \(\Lambda_t\). By Theorem 3.1, \(d_0 = \text{Hdim}(t)\). By the same theorem we have, using the definition of \(\mathcal{O}_\nu\), for \(d > d_0\)

\[
\mu\left(\frac{p}{q}\right) \leq \mu(t) + \epsilon |t - \frac{p}{q}|^{1-d}
\]

\[
\Rightarrow \frac{1}{q} \leq \left(\frac{C}{q^{\nu}}\right)^{1-d}.
\]
Here we have also used Theorem 1.1 twice, namely \( \mu(t) = 0 \), and \( \mu\left(\frac{e}{p}\right) = 1/q \). The last equation implies the result. ■

**Corollary 3.4** If \( t \in \cap \nu \mathcal{O}_\nu \) then \( \text{Hdim} (t) = 1 \).

Notice that the set \( \cap \nu \mathcal{O}_\nu \) is contained in the set of Liouville numbers. This set has Hausdorff dimension zero (see [9]), although it is an uncountable set. This is different from statement \( iv \) of Theorem 1.1, since now we identify a set of irrationals where the dimension is one. In the proof of the theorem it is important that the irrational number \( t \) for which we obtain an estimate is close to certain rationals. In particular, the theorem does not apply to \( t = (\sqrt{5} - 1)/2 \), the golden mean.

## 4 Numerical Results

In this section we perform numerical computations using the methods outlined in the previous sections in support of the conjecture that the Hausdorff dimension of the invariant set for the system \( (3, \{0, t, 1\}) \), where \( t \) is the golden mean (denoted by \( g \)), equals 1. We discuss the figures one by one, and then summarize our results.

In these numerical calculations we employ a convenient algorithm to calculate the appropriate eigenvalue \( \lambda \) of a matrix \( D \):

\[
\lambda = \lim_{n \to \infty} \frac{|D^{n+1} v|}{|D^n v|},
\]

where, of course, \( v = (1, 0, \cdots, 0)^t \), represents the word \( \{0\} \) (in the calculation according to Theorem 2.2) or the difference vector whose only difference is zero (in the calculation according to Theorem 2.5).

To create the first figure, \( 3^{18} \approx 4 \cdot 10^8 \) points of the invariant set for the system \( (3, \{0, g, 1\}) \) were laid out on the interval. We then performed a standard box-counting procedure to estimate the dimension. As can be seen in figure 4.1, the estimate on the dimension is not very accurate and even seems to converge to a number less than 1.

**Claim:** The conventional box-counting procedure to estimate the dimension may occasionally lead to erroneous conclusions, even when applied to relatively simple subsets of the line (such as the one under consideration).

For lack of reliable computational methods applicable to the incommensurate case, we study the dimensions of a sequence of commensurably constructed sets converging to the desired set (with \( t = g \)). The results are displayed in figure 4.2. First we calculated the exact dimension of the invariant sets associated to the systems \( (3, \{0, f_{n-1}/f_n, 1\}) \) using the word counting algorithm of section 2. Here \( f_{n-1}/f_n \) is the \( n \)-th Farey approximant to the golden mean (\( f_1 = 1, f_2 = 2 \) are the Fibonacci numbers). The number of distinct words in its ‘grammar’ increases
dramatically and the algorithm ceases to be practicable beyond \( n = 10 \). In fact, for \( n = 9 \) the ‘grammar’ consists of 8954 words with the maximum word length of 20794 letters (integers), the main restriction in continuing the sequence being the available computer memory for dictionary storage. Finding the corresponding point in figure 4.2 therefore involves calculating the leading eigenvalue of a 8954 \times 8954 transition matrix. To continue the sequence, we used the more efficient algorithm described in Theorem 2.5 giving the lower bound of the dimension. In this case, the computational difficulties arise from computational time rather than memory requirements, and here we have performed calculations up to \( n = 18 \). Note that every 4-th dimension is equal to 1 as it satisfies the criterion given in Theorem 1.1 sub i).

The apparent convergence of the sequence of dimensions in figure 4.2 is of course no proof that the dimension is continuous at \( t = g \). We set out to compare its behavior with that of at least two other sequences, namely one for which we know the dimension is continuous at its limit point \( (t = 1/2) \), and one for which we know that there is a discontinuity \( (t = 0) \).

At \( t = 1/2 \) the dimension is continuous (by Theorem 1.1). In figure 4.3, we display the dimensions of the invariant sets associated with the systems \( (3,\{0,n/(2n+1),1\}) \). In spite of the fact that only relatively few exact dimensions could be calculated, they do appear to converge to 1. The sequence of lower bounds which we displayed in the same picture clearly converges to 1. (In fact, we calculated the lower bounds for the dimensions up to \( n = 500 \) and the convergence persists, the last value for the bound being 0.999507\ldots.)

At \( t = 0 \) the dimension is discontinuous. In figure 4.4 we plotted both the exact values and the lower bounds of the dimensions of the invariant sets associated with the systems \( (3,\{0,1/n,1\}) \). First of all, we observe that if \( n = 2 \pmod 3 \), then by Theorem 1.1 the dimension of the sets equals 1. In addition if \( n = 3^k \) one can show (similar to the calculation for \( n = 3 \) done in section 2; this result is also mentioned but not proved in [4]) that the dimension

\[ d_n = \ln(N_n) [\ln(3^k+1)/2] \]

\[ d_n = \ln(N_n) [\ln(3^n+1)/2] \]

Figure 4.1: Direct calculation of the box-dimension
Figure 4.2: Dimension calculation when $t \to g$

Figure 4.3: Dimension calculation when $t \to 1/2$
of the set equals 0.876... Therefore the displayed sequence cannot converge. Indeed, from its appearance, the sequence might have many limit points.

![Graph](image)

Figure 4.4: Dimension calculation when $t \to 0$

To make this more apparent, we calculated the lower bounds for the dimension for all $n \leq 1000$ for these systems and displayed them in figure 4.5. In this picture we also included the (exact) values for the dimension of the boundary of the invariant sets associated with the systems $(3, \{0, 1/n, 1\})$ when $n = 2 \pmod{3}$ (compare Theorem 2.6). These apparently converge (slowly) to 1 (this was proved in [5]). We also note that from [16], one can conclude that these boundaries as sets (in the Hausdorff metric) converge to $\Lambda_{t=0}$.

There is a striking difference in the behavior of the dimension function depending on the limiting value of $t$: when $t \to 1/2$ the the dimension converge, and when $t \to 0$ they do not. From this we formulate the following conjecture:

**Conjecture 4.1** Whenever the limit $t \to t_0$, Hdim$(t)$ exists then Hdim$(t)$ is continuous at $t_0$.

Based on this criterion we may now take the fact that the limit of the dimension as $t \to g$ appears to exist (see figure 4.2), as evidence that Hdim$(\Lambda_{t})$ is continuous at the golden mean.

Because our main conjecture crucially relies upon this second conjecture, we felt that it was necessary to provide additional evidence for it. Thus we decided to test the convergence of the bounds for the dimensions of the invariant associated with the systems $(3, \{0, (2 + n)/(9 + 5n), 1\})$, where $t$ converges to $1/5$ and we expect the dimensions to converge to $1$ (figure 4.6), and $(3, \{0, (3 + 2n)/(8 + 5n), 1\})$, where $t$ converges to $2/5$ and the dimensions are not expected to converge (figure 4.7). From the computational viewpoint, the task of producing data for reasonable conclusions turned out to be formidable. Only after a very careful, low level optimization of the program implemented in C (which included consideration of register versus memory variable storage, inline function expansion, and substitution of algebraic operations by
logical instructions), using two processors of the 64 bit UltraSparc HPC 3000 continuously for over forty days (60,000 minutes for each of the two processes, equivalent to three months CPU time), we were able to produce the data shown in figures 4.6 and 4.7.

A few comments in passing about the last two figures. First of all, in the latter figure we have not plotted those cases (one in every three consecutive values of $n$) where the dimension would give 1. This would clutter the picture and not add any information. Furthermore, note that we only plot the lower bound in these pictures since the word algorithm that gives us the exact values of the dimension is not practicable except for very small values of $n$ (on the scale of these pictures). However from the other figures it is apparent that the tendencies of the exact dimension are reflected in the behavior of the bound.

Finally, we also consider the invariant sets associated to the systems $(3, \{0, c_{n-1}/c_n, 1\})$, where

$$c_n = 3c_{n-1} + c_{n-2},$$

$$c_0 = 1, \quad c_1 = 3,$$

converging to the value $t = (\sqrt{13} - 3)/2 \approx 0.3027 \ldots$. This should be similar to the golden mean case, except that now $pq = 0 \pmod{3}$ for all approximants. Numerically, this is a much harder problem then $t = g$, and we were able to calculate only the lower bound of the dimension up to $n = 7$. The results are shown in figure 4.8, where it is seen that the dimension also seems to converge to 1. The general behavior of successive approximants is similar to that in the golden mean case, except for the absence of points with $\text{Hdim}(t) = 1$ which satisfy the criterion given in Theorem 1.1 sub i.

Observe that in all rational cases that we have been able to check, we find that whenever $\text{Hdim}(A_{p/q}) < 1$ we also have that the lower bound of the dimension is strictly smaller than the
Figure 4.6: Dimension calculation when $t \to 1/5$

Figure 4.7: Dimension calculation when $t \to 2/5$
(exact) dimension. This leads us to believe that in these cases the dimension of the support of the invariant measure is strictly smaller than the dimension of the set. That this should occur in one-dimensional systems was apparently not known although it has been observed for 2-dimensional iterated function systems ([6]). It is interesting to note that since the estimate of the dimension tends to 1 (in the third sequence) apparently the dimension of the measure in the irrational case is equal to the dimension of the set.

**Conclusion:** We claim that our numerical work indicates that
\[ \text{Hdim}(\Lambda_g) = \text{Hdim}(\nu_g) = 1, \] where \( g \) is the golden mean.

**References**


